

Puja K., Ranjan S. and Majhi S., Adaptive Super-Twisting Sliding Mode Fault-Tolerant Control for Robot Manipulators With External Disturbances, Accepted for presentation in the 15th IFAC Workshop on Adaptive and Learning Control Systems (ALCOS 2025), Mexico City, Mexico, Jul 2-4, 2025.

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Kumar M, Majhi S. and Ranjan S., Machine Learning and Relay Control Hardware Based Auto-tune Identification, Accepted for presentation in the 15th IFAC Workshop on Adaptive and Learning Control Systems (ALCOS 2025), Mexico City, Mexico, Jul 2-4, 2025.

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