

ME 101: Engineering Mechanics

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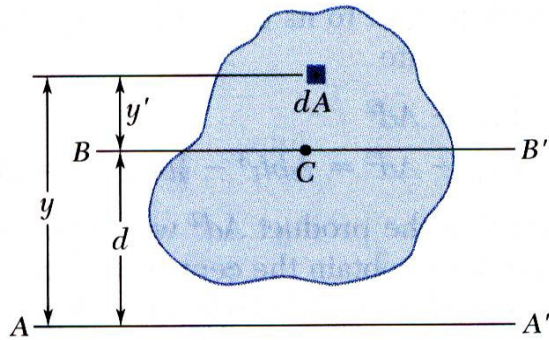
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Area Moments of Inertia

Parallel Axis Theorem



- Consider moment of inertia I of an area A with respect to the axis AA'

$$I = \int y^2 dA$$

- The axis BB' passes through the area centroid and is called a *centroidal axis*.

$$\begin{aligned} I &= \int y^2 dA = \int (y' + d)^2 dA \\ &= \int y'^2 dA + 2d \int y' dA + d^2 \int dA \end{aligned}$$

- Second term = 0 since centroid lies on BB' ($\int y' dA = y_c A$, and $y_c = 0$)

$$I = \bar{I} + Ad^2 \quad \text{Parallel Axis theorem}$$

Parallel Axis theorem:

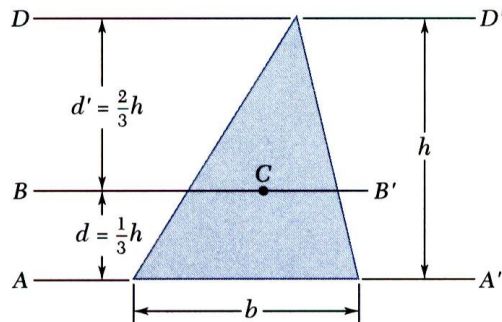
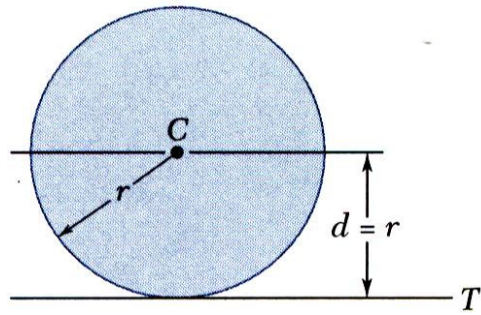
MI @ any axis =

MI @ centroidal axis + Ad^2

The two axes should be parallel to each other.

Area Moments of Inertia

Parallel Axis Theorem



- Moment of inertia I_T of a circular area with respect to a tangent to the circle,

$$I_T = \bar{I} + Ad^2 = \frac{1}{4}\pi r^4 + (\pi r^2)r^2$$

$$= \frac{5}{4}\pi r^4$$

- Moment of inertia of a triangle with respect to a centroidal axis,

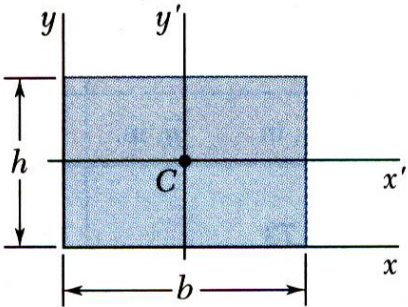
$$I_{AA'} = \bar{I}_{BB'} + Ad^2$$

$$I_{BB'} = I_{AA'} - Ad^2 = \frac{1}{12}bh^3 - \frac{1}{2}bh\left(\frac{1}{3}h\right)^2$$

$$= \frac{1}{36}bh^3$$

- The moment of inertia of a composite area A about a given axis is obtained by adding the moments of inertia of the component areas A_1, A_2, A_3, \dots , with respect to the same axis.

Area Moments of Inertia: Standard MIs



Moment of inertia about x -axis

Moment of inertia about y -axis

Moment of inertia about x' -axis

Moment of inertia about y' -axis

Moment of inertia about z -axis passing through C

Answer

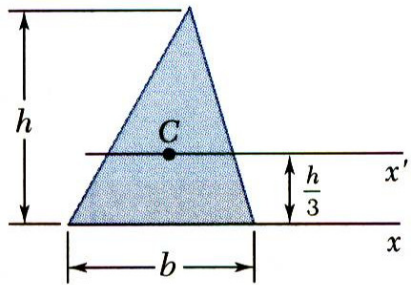
$$I_x = \frac{1}{3}bh^3$$

$$I_y = \frac{1}{3}b^3h$$

$$I_{x'} = \frac{1}{12}bh^3$$

$$I_{y'} = \frac{1}{12}b^3h$$

$$I_C = \frac{1}{12}bh(b^2 + h^2)$$

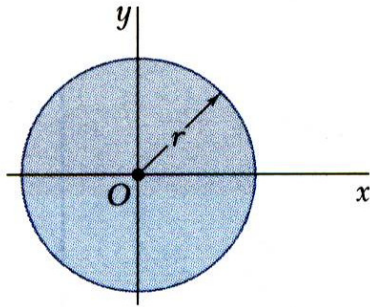


Moment of inertia about x -axis

$$I_x = \frac{1}{12}bh^3$$

Moment of inertia about x' -axis

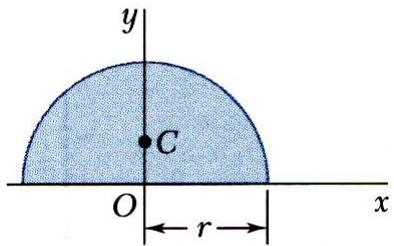
$$I_{x'} = \frac{1}{36}bh^3$$



Moment of inertia about x' -axis

$$I_x = \frac{1}{4}\pi r^4$$

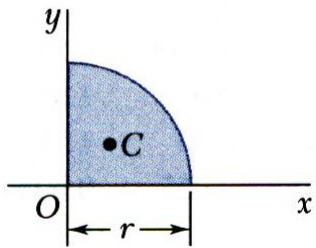
Moment of inertia about z -axis passing through O $I_0 = \frac{1}{2}\pi r^4$



Moment of inertia about x' -axis

$$I_x = I_y = \frac{1}{8}\pi r^4$$

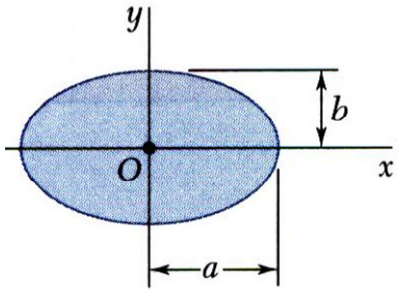
Moment of inertia about z -axis passing through O $I_0 = \frac{1}{4}\pi r^4$



Moment of inertia about x' -axis

$$I_x = I_y = \frac{1}{16}\pi r^4$$

Moment of inertia about z -axis passing through O $I_0 = \frac{1}{8}\pi r^4$



Moment of inertia about x -axis

$$I_x = \frac{1}{4}\pi ab^3$$

Moment of inertia about y -axis

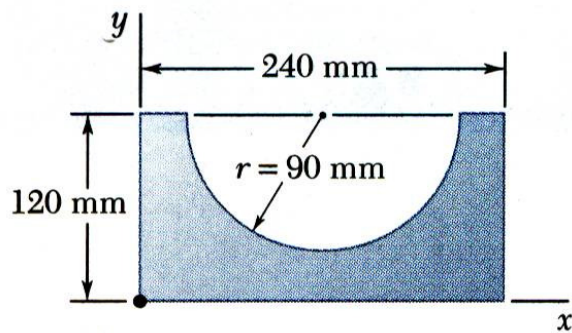
$$I_y = \frac{1}{4}\pi a^3 b$$

Moment of inertia about z -axis passing through O $I_0 = \frac{1}{4}\pi ab(a^2 + b^2)$

Area Moments of Inertia

Example:

Determine the moment of inertia of the shaded area with respect to the x axis.

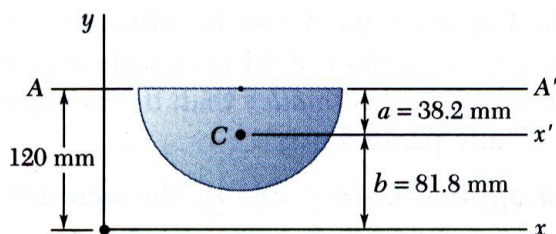


SOLUTION:

- Compute the moments of inertia of the bounding rectangle and half-circle with respect to the x axis.
- The moment of inertia of the shaded area is obtained by subtracting the moment of inertia of the half-circle from the moment of inertia of the rectangle.

Area Moments of Inertia

Example: Solution



$$a = \frac{4r}{3\pi} = \frac{(4)(90)}{3\pi} = 38.2 \text{ mm}$$

$$b = 120 - a = 81.8 \text{ mm}$$

$$A = \frac{1}{2}\pi r^2 = \frac{1}{2}\pi(90)^2 \\ = 12.72 \times 10^3 \text{ mm}^2$$

SOLUTION:

- Compute the moments of inertia of the bounding rectangle and half-circle with respect to the x axis.

Rectangle:

$$I_x = \frac{1}{3}bh^3 = \frac{1}{3}(240)(120)^3 = 138.2 \times 10^6 \text{ mm}^4$$

Half-circle:

moment of inertia with respect to AA' ,

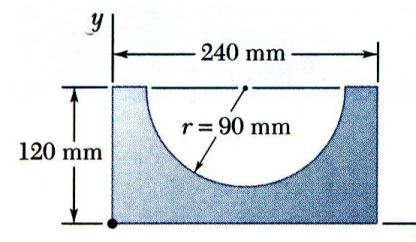
$$I_{AA'} = \frac{1}{8}\pi r^4 = \frac{1}{8}\pi(90)^4 = 25.76 \times 10^6 \text{ mm}^4$$

Moment of inertia with respect to x' ,

$$\bar{I}_{x'} = I_{AA'} - Aa^2 = (25.76 \times 10^6) - (12.72 \times 10^3)(38.2)^2 \\ = 7.20 \times 10^6 \text{ mm}^4$$

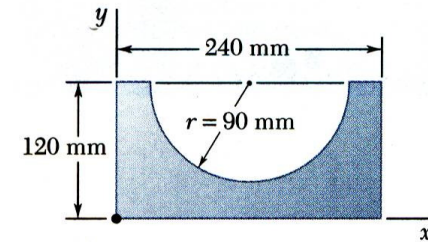
moment of inertia with respect to x ,

$$I_x = \bar{I}_{x'} + Ab^2 = 7.20 \times 10^6 + (12.72 \times 10^3)(81.8)^2 \\ = 92.3 \times 10^6 \text{ mm}^4$$

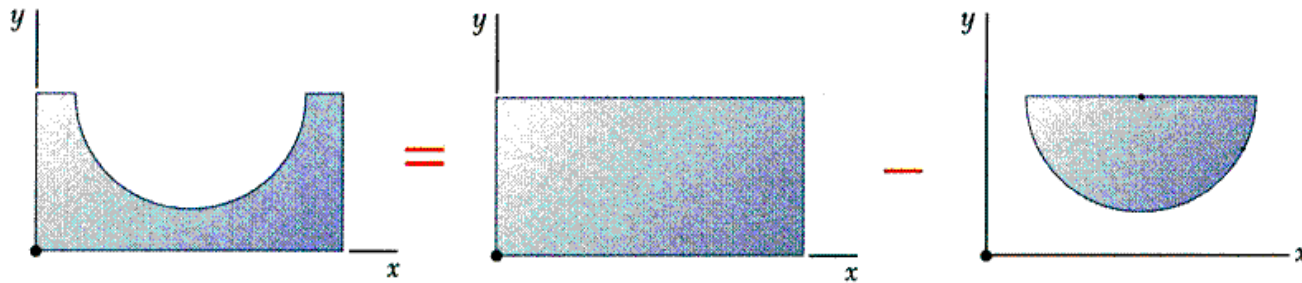


Area Moments of Inertia

Example: Solution



- The moment of inertia of the shaded area is obtained by subtracting the moment of inertia of the half-circle from the moment of inertia of the rectangle.



$$I_x = 138.2 \times 10^6 \text{ mm}^4 - 92.3 \times 10^6 \text{ mm}^4$$

$$I_x = 45.9 \times 10^6 \text{ mm}^4$$

Consider area (1)

$$I_x = \frac{1}{3}bh^3 = \frac{1}{3} \times 80 \times 60^3 = 5.76 \times 10^6 \text{ mm}^4$$

Consider area (2)

$$I_{x'} = \frac{1}{4} \left(\frac{\pi r^4}{4} \right) = \frac{\pi}{16} (30)^4 = 0.1590 \times 10^6 \text{ mm}^4$$

$$\bar{I}_x = 0.1590 \times 10^6 - \frac{\pi}{4} (30)^2 \times (12.73)^2 = 0.0445 \times 10^6 \text{ mm}^4$$

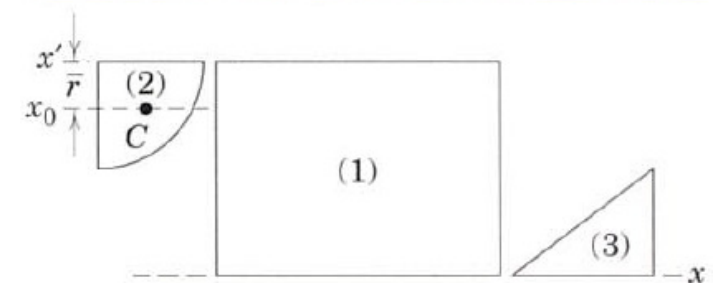
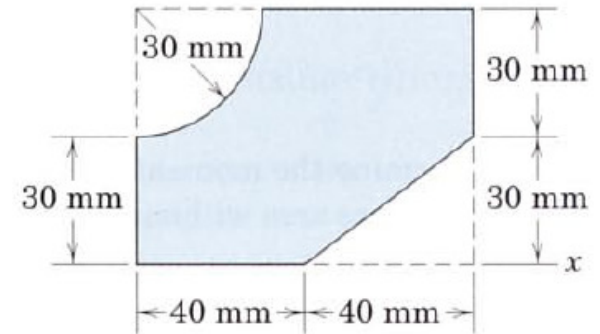
$$I_x = 0.0445 \times 10^6 + \frac{\pi}{4} (30)^2 (60 - 12.73) = 1.624 \times 10^6 \text{ mm}^4$$

Consider area (3)

$$I_x = \frac{1}{12}bh^3 = \frac{1}{12} \times 40 \times 30^3 = 0.09 \times 10^6 \text{ mm}^4$$

$$I_x = 5.76 \times 10^6 - 1.624 \times 10^6 - 0.09 \times 10^6 = 4.05 \times 10^6 \text{ mm}^4$$

$$A = 60 \times 80 - \frac{1}{4}\pi(30)^2 - \frac{1}{2}40 \times 30 = 3490 \text{ mm}^2$$



$$k_x = \sqrt{\frac{I_x}{A}} = \sqrt{\frac{4.05 \times 10^6}{3490}} = 34.00 \text{ mm}$$

Determine the moment of inertia and the radius of gyration of the area shown in the fig.

$$\overline{I1}_x = \frac{1}{12}bd^3 = \frac{1}{12} \times 24 \times 6^3 = 432 \text{ mm}^4$$

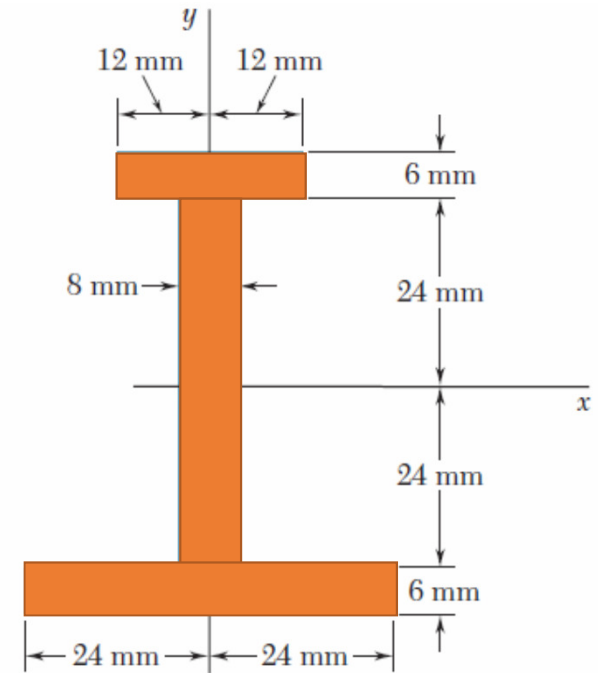
$$\overline{I2}_x = \frac{1}{12}bd^3 = \frac{1}{12} \times 8 \times 48^3 = 73728 \text{ mm}^4$$

$$\overline{I3}_x = \frac{1}{12}bd^3 = \frac{1}{12} \times 48 \times 6^3 = 864 \text{ mm}^4$$

$$I1_x = \overline{I1}_x + Ah^2 = 432 + 24 \times 6 \times (24 + 3)^2 = 105408 \text{ mm}^4$$

$$I3_x = \overline{I3}_x + Ah^2 = 864 + 48 \times 6 \times (24 + 3)^2 = 210816 \text{ mm}^4$$

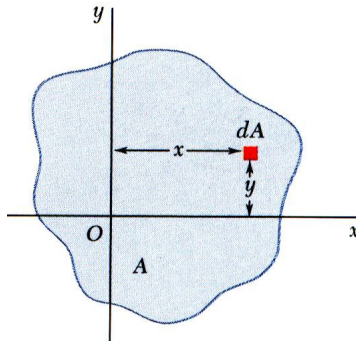
$$I_x = 105408 + 73728 + 210816 = 390 \times 10^3 \text{ mm}^4$$



$$k_x = \sqrt{\frac{I_x}{A}} = \sqrt{\frac{390 \times 10^3}{816}} = \mathbf{21.9 \text{ mm}}$$

Area Moments of Inertia

Products of Inertia: for problems involving unsymmetrical cross-sections and in calculation of MI about rotated axes. It may be +ve, -ve, or zero

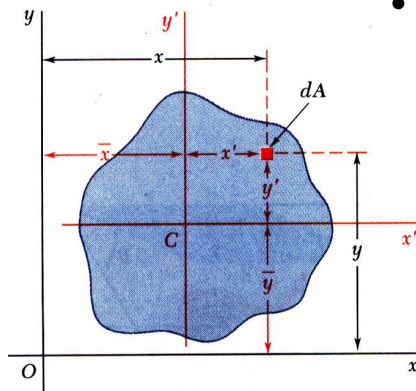
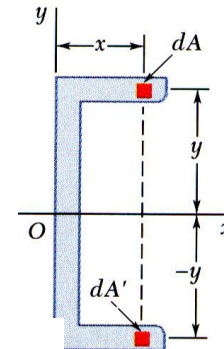


- Product of Inertia of area A w.r.t. x - y axes:

$$I_{xy} = \int xy \, dA$$

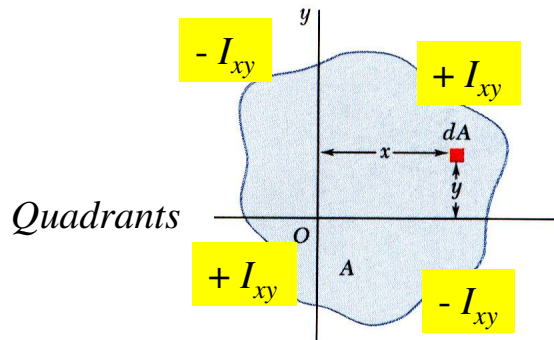
x and y are the coordinates of the element of area $dA=xy$

- When the x axis, the y axis, or both are an axis of symmetry, the product of inertia is zero.



- Parallel axis theorem for products of inertia:

$$I_{xy} = \bar{I}_{xy} + \bar{x}\bar{y}A$$

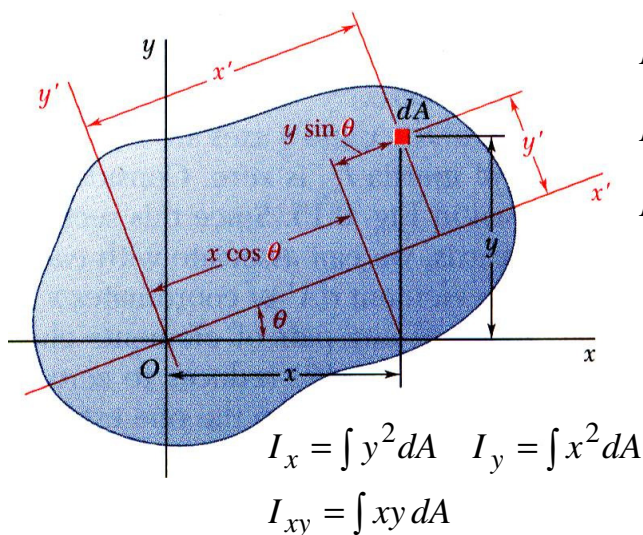


Area Moments of Inertia

Rotation of Axes

Product of inertia is useful in calculating MI @ inclined axes.

→ Determination of axes about which the MI is a maximum and a minimum



Moments and product of inertia
w.r.t. new axes x' and y' ?

Note: $x' = x \cos \theta + y \sin \theta$

$y' = y \cos \theta - x \sin \theta$

$$I_{x'} = \int y'^2 dA = \int (y \cos \theta - x \sin \theta)^2 dA$$

$$I_{y'} = \int x'^2 dA = \int (x \cos \theta + y \sin \theta)^2 dA$$

$$I_{x'y'} = \int x' y' dA = \int (x \cos \theta + y \sin \theta)(y \cos \theta - x \sin \theta) dA$$

$$\sin^2 \theta = \frac{1 - \cos 2\theta}{2} \quad \cos^2 \theta = \frac{1 + \cos 2\theta}{2}$$

$$\sin \theta \cos \theta = \frac{1}{2} \sin 2\theta \quad \cos^2 \theta - \sin^2 \theta = \cos 2\theta$$

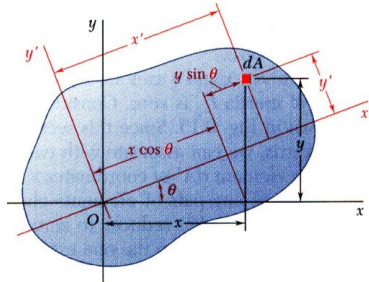
$$I_{x'} = \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta$$

$$I_{y'} = \frac{I_x + I_y}{2} - \frac{I_x - I_y}{2} \cos 2\theta + I_{xy} \sin 2\theta$$

$$I_{x'y'} = \frac{I_x - I_y}{2} \sin 2\theta + I_{xy} \cos 2\theta$$

Area Moments of Inertia

Rotation of Axes



$$I_{x'} = \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta$$

$$I_{y'} = \frac{I_x + I_y}{2} - \frac{I_x - I_y}{2} \cos 2\theta + I_{xy} \sin 2\theta$$

$$I_{x'y'} = \frac{I_x - I_y}{2} \sin 2\theta + I_{xy} \cos 2\theta$$

Adding first two eqns:

$$I_{x'} + I_{y'} = I_x + I_y = I_z \rightarrow \text{The Polar MI @ O}$$

Angle which makes $I_{x'}$ and $I_{y'}$ either max or min can be found by setting the derivative of either $I_{x'}$ or $I_{y'}$ w.r.t. θ equal to zero:

$$\frac{dI_{x'}}{d\theta} = (I_y - I_x) \sin 2\theta - 2I_{xy} \cos 2\theta = 0$$

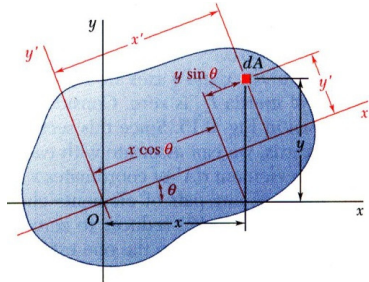
Denoting this critical angle by α

$$\tan 2\alpha = \frac{2I_{xy}}{I_y - I_x}$$

- two values of 2α which differ by π since $\tan 2\alpha = \tan(2\alpha + \pi)$
- two solutions for α will differ by $\pi/2$
- one value of α will define the axis of maximum MI and the other defines the axis of minimum MI
- These two rectangular axes are called the principal axes of inertia

Area Moments of Inertia

Rotation of Axes



$$I_{x'} = \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta$$

$$I_{y'} = \frac{I_x + I_y}{2} - \frac{I_x - I_y}{2} \cos 2\theta + I_{xy} \sin 2\theta$$

$$I_{x'y'} = \frac{I_x - I_y}{2} \sin 2\theta + I_{xy} \cos 2\theta$$

$$\tan 2\alpha = \frac{2I_{xy}}{I_y - I_x} \Rightarrow \sin 2\alpha = \cos 2\alpha \frac{2I_{xy}}{I_y - I_x}$$

Substituting in the third eqn for critical value of 2θ : $I_{x'y'} = 0$

→ Product of Inertia $I_{x'y'}$ is zero for the **Principal Axes of inertia**

Substituting $\sin 2\alpha$ and $\cos 2\alpha$ in first two eqns for **Principal Moments of Inertia**:

$$I_{\max} = \frac{I_x + I_y}{2} + \frac{1}{2} \sqrt{(I_x - I_y)^2 + 4I_{xy}^2}$$

$$I_{\min} = \frac{I_x + I_y}{2} - \frac{1}{2} \sqrt{(I_x - I_y)^2 + 4I_{xy}^2}$$

$$I_{xy@ \alpha} = 0$$

$$I_{x'} = \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta \quad \Rightarrow \quad I_{x'} - \frac{I_x + I_y}{2} = \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta$$

$$I_{x'y'} = \frac{I_x - I_y}{2} \sin 2\theta + I_{xy} \cos 2\theta$$

Squaring both the equation and adding

$$\left(I_{x'} - \frac{I_x + I_y}{2} \right)^2 + (I_{x'y'})^2 = \left(\frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta \right)^2 + \left(\frac{I_x - I_y}{2} \sin 2\theta + I_{xy} \cos 2\theta \right)^2$$

$$\left(I_{x'} - \frac{I_x + I_y}{2} \right)^2 + (I_{x'y'})^2 = \left(\frac{I_x - I_y}{2} \right)^2 \cos^2 2\theta - 2 \frac{I_x - I_y}{2} I_{xy} \cos 2\theta \sin 2\theta + (I_{xy})^2 \sin^2 2\theta$$

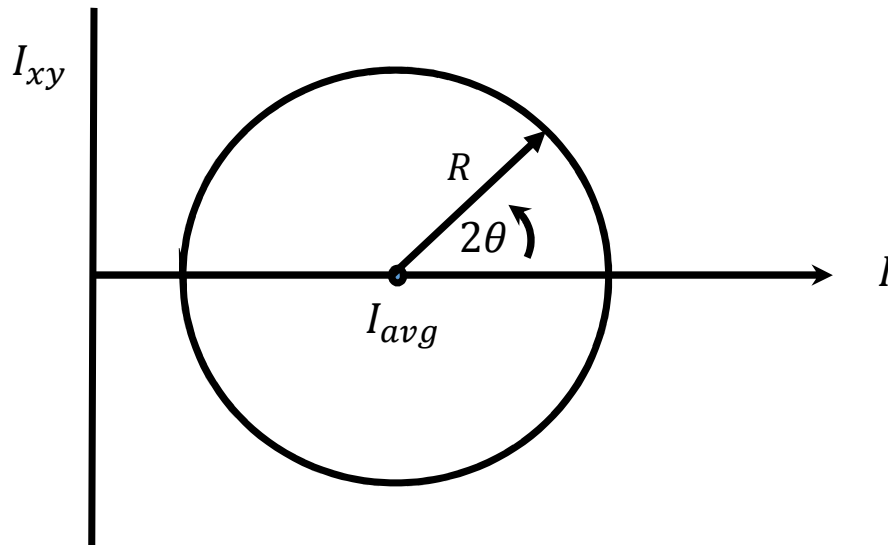
$$+ \left(\frac{I_x - I_y}{2} \right)^2 \sin^2 2\theta + 2 \frac{I_x - I_y}{2} I_{xy} \cos 2\theta \sin 2\theta + (I_{xy})^2 \sin^2 2\theta$$

$$\left(I_{x'} - \frac{I_x + I_y}{2} \right)^2 + (I_{x'y'})^2 = \left(\frac{I_x - I_y}{2} \right)^2 + (I_{xy})^2$$

$$\left(I_{x'} - \frac{I_x + I_y}{2}\right)^2 + (I_{x'y'})^2 = \left(\frac{I_x - I_y}{2}\right)^2 + (I_{xy})^2$$

Defining $\frac{I_x + I_y}{2} = I_{avg}$ And $R = \sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + (I_{xy})^2}$

$(I_{x'} - I_{avg})^2 + (I_{x'y'})^2 = R^2$ Which is a equation of circle with center $(I_{avg}, 0)$ and radius R



Area Moments of Inertia

Mohr's Circle of Inertia: Following relations can be represented graphically by a diagram called Mohr's Circle

For given values of I_x , I_y , & I_{xy} , corresponding values of $I_{x'}$, $I_{y'}$, & $I_{x'y'}$ may be determined from the diagram for any desired angle θ .

$$I_{x'} = \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta$$

$$I_{y'} = \frac{I_x + I_y}{2} - \frac{I_x - I_y}{2} \cos 2\theta + I_{xy} \sin 2\theta$$

$$I_{x'y'} = \frac{I_x - I_y}{2} \sin 2\theta + I_{xy} \cos 2\theta$$

$$\tan 2\alpha = \frac{2I_{xy}}{I_y - I_x}$$

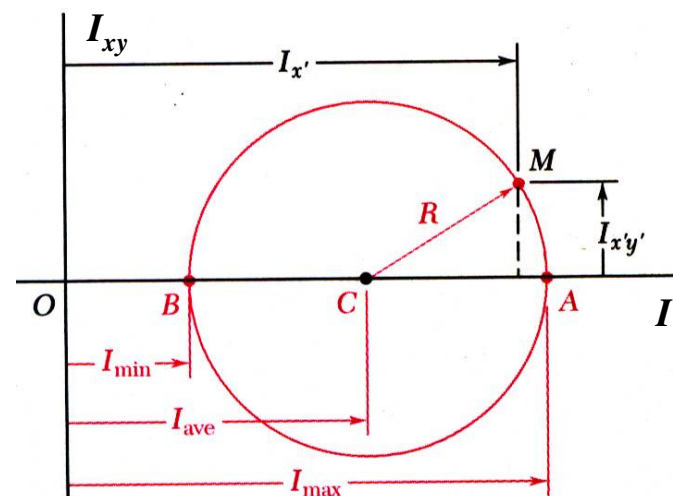
$$I_{\max} = \frac{I_x + I_y}{2} + \frac{1}{2} \sqrt{(I_x - I_y)^2 + 4I_{xy}^2}$$

$$I_{\min} = \frac{I_x + I_y}{2} - \frac{1}{2} \sqrt{(I_x - I_y)^2 + 4I_{xy}^2}$$

$$I_{xy@ \alpha} = 0$$

$$(I_{x'} - I_{ave})^2 + I_{x'y'}^2 = R^2$$

$$I_{ave} = \frac{I_x + I_y}{2} \quad R = \sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}$$

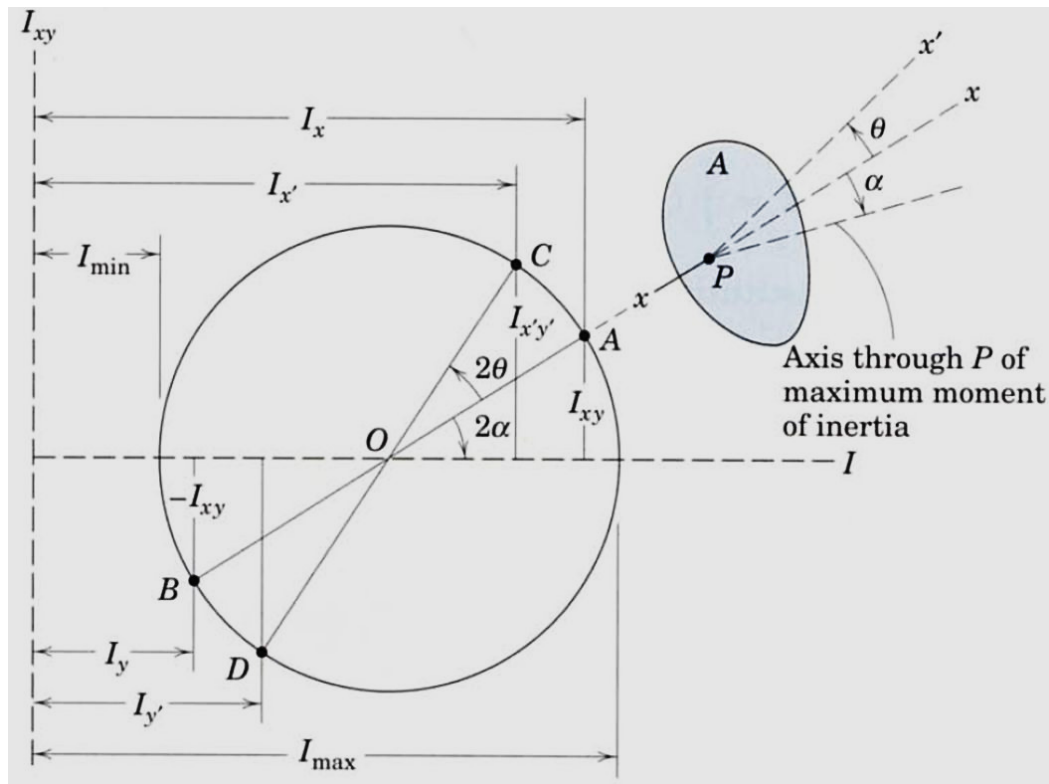


- At the points A and B, $I_{x'y'} = 0$ and $I_{x'}$ is a maximum and minimum, respectively.

$$I_{\max, \min} = I_{ave} \pm R$$

Area Moments of Inertia

Mohr's Circle of Inertia: Construction



$$\tan 2\alpha = \frac{2I_{xy}}{I_y - I_x}$$

$$I_{x'} = \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta$$

$$I_{y'} = \frac{I_x + I_y}{2} - \frac{I_x - I_y}{2} \cos 2\theta + I_{xy} \sin 2\theta$$

$$I_{x'y'} = \frac{I_x - I_y}{2} \sin 2\theta + I_{xy} \cos 2\theta$$

$$I_{\max} = \frac{I_x + I_y}{2} + \frac{1}{2} \sqrt{(I_x - I_y)^2 + 4I_{xy}^2}$$

$$I_{\min} = \frac{I_x + I_y}{2} - \frac{1}{2} \sqrt{(I_x - I_y)^2 + 4I_{xy}^2}$$

$$I_{xy@ \alpha} = 0$$

Choose horz axis → MI

Choose vert axis → PI

Point A – known $\{I_x, I_{xy}\}$

Point B – known $\{I_y, -I_{xy}\}$

Circle with dia AB

Angle α for Area

→ Angle 2α to horz (same sense) → I_{\max}, I_{\min}

Angle x to $x' = \theta$

→ Angle OA to OC = 2θ

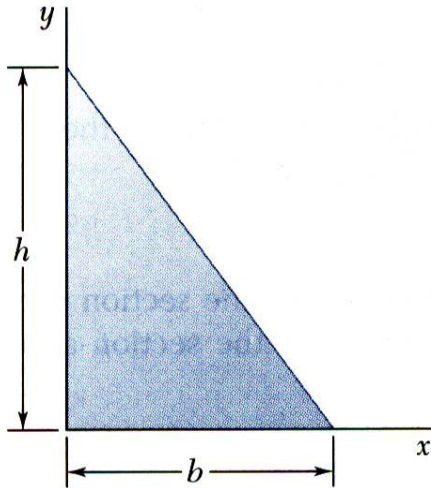
→ Same sense

Point C → $I_{x'}, I_{x'y'}$

Point D → $I_{y'}$

Area Moments of Inertia

Example: Product of Inertia



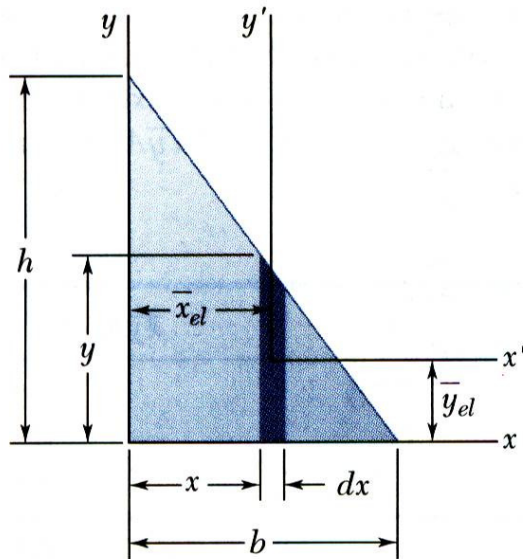
SOLUTION:

- Determine the product of inertia using direct integration with the parallel axis theorem on vertical differential area strips
- Apply the parallel axis theorem to evaluate the product of inertia with respect to the centroidal axes.

Determine the product of inertia of the right triangle (a) with respect to the x and y axes and (b) with respect to centroidal axes parallel to the x and y axes.

Area Moments of Inertia

Examples



SOLUTION:

- Determine the product of inertia using direct integration with the parallel axis theorem on vertical differential area strips

$$y = h \left(1 - \frac{x}{b} \right) \quad dA = y dx = h \left(1 - \frac{x}{b} \right) dx$$

$$\bar{x}_{el} = x \quad \bar{y}_{el} = \frac{1}{2} y = \frac{1}{2} h \left(1 - \frac{x}{b} \right)$$

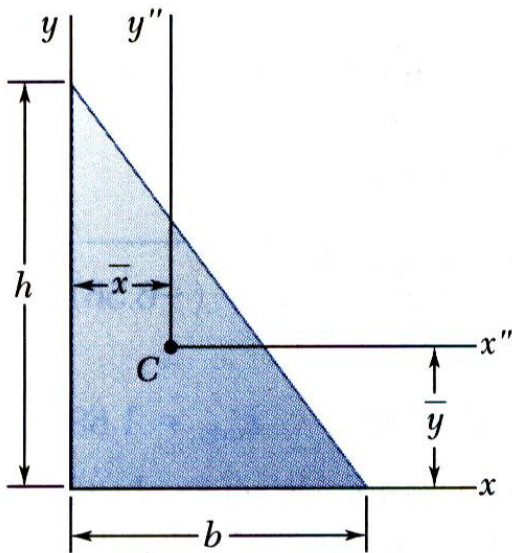
Integrating dI_x from $x = 0$ to $x = b$,

$$\begin{aligned} I_{xy} &= \int dI_{xy} = \int \bar{x}_{el} \bar{y}_{el} dA = \int_0^b x \left(\frac{1}{2} \right) h^2 \left(1 - \frac{x}{b} \right)^2 dx \\ &= h^2 \int_0^b \left(\frac{x}{2} - \frac{x^2}{b} + \frac{x^3}{2b^2} \right) dx = h^2 \left[\frac{x^2}{4} - \frac{x^3}{3b} + \frac{x^4}{8b^2} \right]_0^b \end{aligned}$$

$$I_{xy} = \frac{1}{24} b^2 h^2$$

Area Moments of Inertia

Examples



SOLUTION

- Apply the parallel axis theorem to evaluate the product of inertia with respect to the centroidal axes.

$$\bar{x} = \frac{1}{3}b \quad \bar{y} = \frac{1}{3}h$$

With the results from part a,

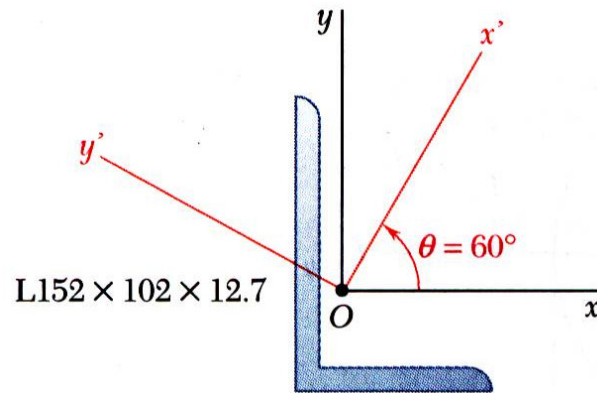
$$I_{xy} = \bar{I}_{x''y''} + \bar{x}\bar{y}A$$

$$\bar{I}_{x''y''} = \frac{1}{24}b^2h^2 - \left(\frac{1}{3}b\right)\left(\frac{1}{3}h\right)\left(\frac{1}{2}bh\right)$$

$$\bar{I}_{x''y''} = -\frac{1}{72}b^2h^2$$

Area Moments of Inertia

Example: Mohr's Circle of Inertia



The moments and product of inertia with respect to the x and y axes are $I_x = 7.24 \times 10^6 \text{ mm}^4$, $I_y = 2.61 \times 10^6 \text{ mm}^4$, and $I_{xy} = -2.54 \times 10^6 \text{ mm}^4$.

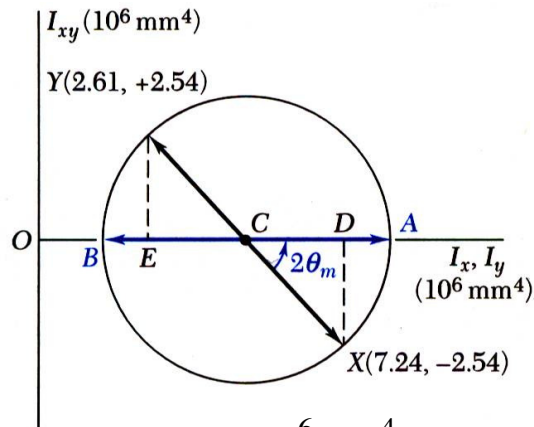
Using Mohr's circle, determine (a) the principal axes about O , (b) the values of the principal moments about O , and (c) the values of the moments and product of inertia about the x' and y' axes

SOLUTION:

- Plot the points (I_x, I_{xy}) and $(I_y, -I_{xy})$. Construct Mohr's circle based on the circle diameter between the points.
- Based on the circle, determine the orientation of the principal axes and the principal moments of inertia.
- Based on the circle, evaluate the moments and product of inertia with respect to the $x'y'$ axes.

Area Moments of Inertia

Example: Mohr's Circle of Inertia



$$I_x = 7.24 \times 10^6 \text{ mm}^4$$

$$I_y = 2.61 \times 10^6 \text{ mm}^4$$

$$I_{xy} = -2.54 \times 10^6 \text{ mm}^4$$

SOLUTION:

- Plot the points (I_x, I_{xy}) and $(I_y, -I_{xy})$. Construct Mohr's circle based on the circle diameter between the points.

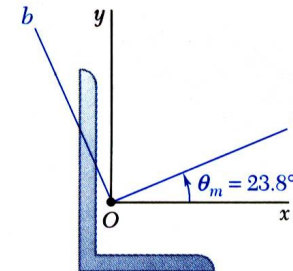
$$OC = I_{ave} = \frac{1}{2}(I_x + I_y) = 4.925 \times 10^6 \text{ mm}^4$$

$$CD = \frac{1}{2}(I_x - I_y) = 2.315 \times 10^6 \text{ mm}^4$$

$$R = \sqrt{(CD)^2 + (DX)^2} = 3.437 \times 10^6 \text{ mm}^4$$

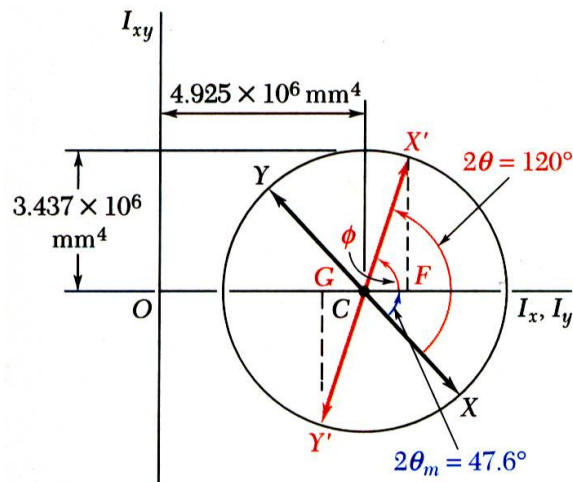
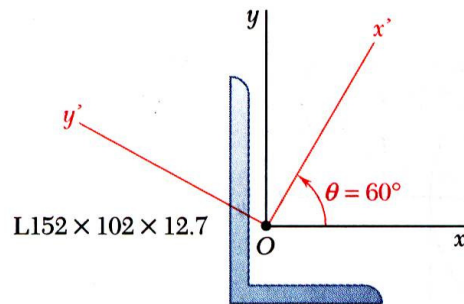
- Based on the circle, determine the orientation of the principal axes and the principal moments of inertia.

$$\tan 2\theta_m = \frac{DX}{CD} = 1.097 \quad 2\theta_m = 47.6^\circ \quad \theta_m = 23.8^\circ$$



Area Moments of Inertia

Example: Mohr's Circle of Inertia



$$OC = I_{ave} = 4.925 \times 10^6 \text{ mm}^4$$

$$R = 3.437 \times 10^6 \text{ mm}^4$$

- Based on the circle, evaluate the moments and product of inertia with respect to the $x'y'$ axes.

The points X' and Y' corresponding to the x' and y' axes are obtained by rotating CX and CY counterclockwise through an angle $\theta = 2(60^\circ) = 120^\circ$. The angle that CX' forms with the horz is $\phi = 120^\circ - 47.6^\circ = 72.4^\circ$.

$$I_{x'} = OF = OC + CX' \cos \phi = I_{ave} + R \cos 72.4^\circ$$

$$I_{x'} = 5.96 \times 10^6 \text{ mm}^4$$

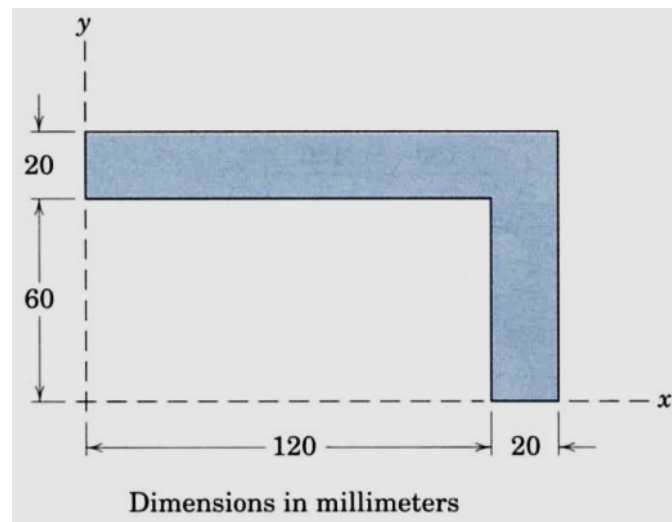
$$I_{y'} = OG = OC - CY' \cos \phi = I_{ave} - R \cos 72.4^\circ$$

$$I_{y'} = 3.89 \times 10^6 \text{ mm}^4$$

$$I_{x'y'} = FX' = CY' \sin \phi = R \sin 72.4^\circ$$

$$I_{x'y'} = 3.28 \times 10^6 \text{ mm}^4$$

Determine the product of the inertia of the shaded area shown below about the x - y axes.



Solution:

Parallel axis theorem: $I_{xy} = \bar{I}_{xy} + d_x d_y A$

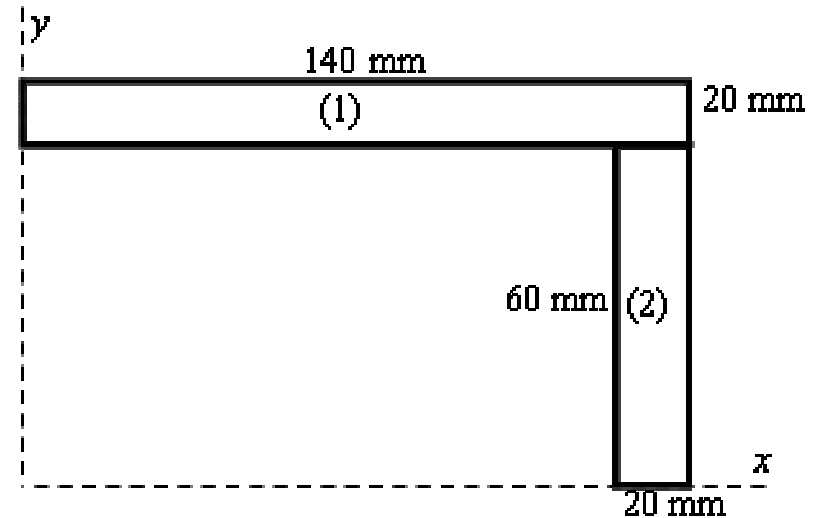
Both areas (1) and (2) are symmetric @ their centroidal

Axis $\rightarrow \bar{I}_{xy} = 0$ for both area.

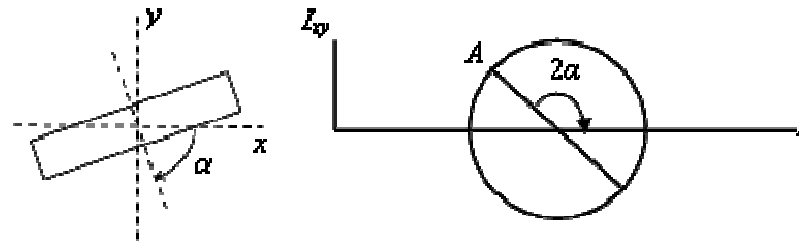
Therefore, for Area (1): $I_{xy1} = d_{x1} d_{y1} A_1$
 $I_{xy1} = 20 \times 140 \times 70 \times 70 = 13.72 \times 10^6 \text{ mm}^4$

Similarly, for Area (2): $I_{xy2} = d_{x2} d_{y2} A_2$
 $I_{xy2} = 60 \times 20 \times 130 \times 30 = 4.68 \times 10^6 \text{ mm}^4$

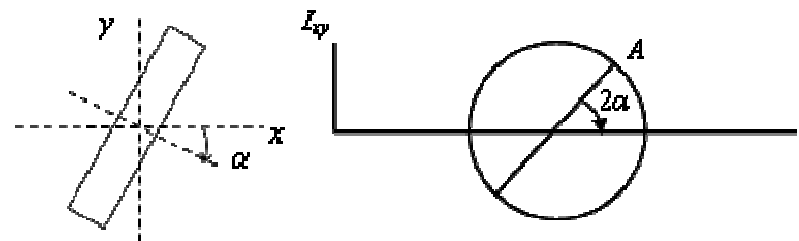
Total $I_{xy} = I_{xy1} + I_{xy2} = 18.40 \times 10^6 \text{ mm}^4$



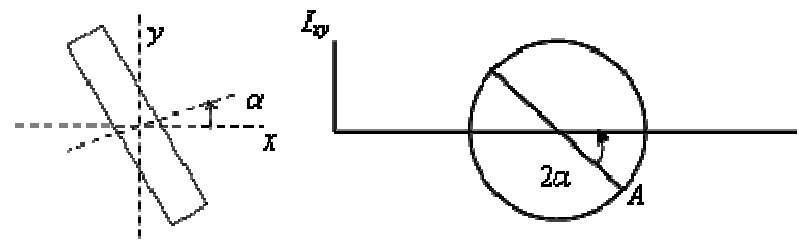
$$I_x < I_y, \quad I_{xy} (+)$$



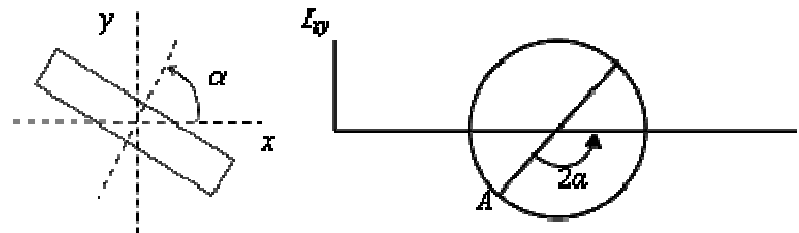
$$I_x > I_y, \quad I_{xy} (+)$$



$$I_x > I_y, \quad I_{xy} (-)$$



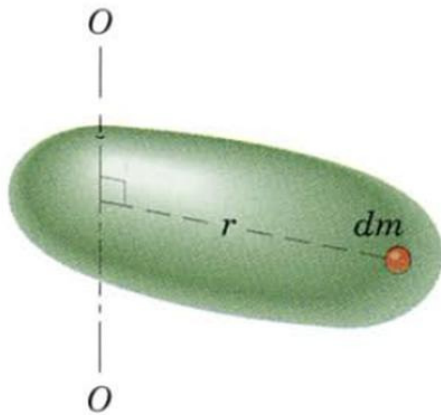
$$I_x < I_y, \quad I_{xy} (-)$$



Area Moments of Inertia

Mass Moments of Inertia (I): Important in Rigid Body Dynamics

- I is a measure of distribution of mass of a rigid body w.r.t. the axis in question (constant property for that axis).
- Units are (mass)(length)² → kg.m²



Consider a three dimensional body of mass m
Mass moment of inertia of this body about axis $O-O$:

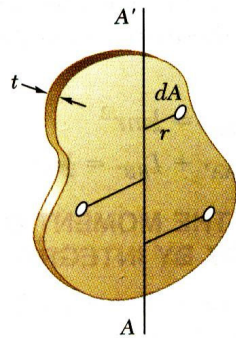
$$I = \int r^2 dm$$

Integration is over the entire body.

r = perpendicular distance of the mass element dm
from the axis $O-O$

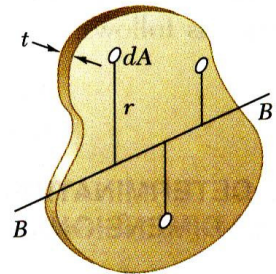
Area Moments of Inertia

Moments of Inertia of Thin Plates



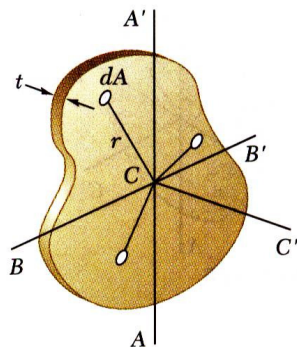
- For a thin plate of uniform thickness t and homogeneous material of density ρ , the mass moment of inertia with respect to axis AA' contained in the plate is

$$\begin{aligned} I_{AA'} &= \int r^2 dm = \rho t \int r^2 dA \\ &= \rho t I_{AA',area} \end{aligned}$$



- Similarly, for perpendicular axis BB' which is also contained in the plate,

$$I_{BB'} = \rho t I_{BB',area}$$

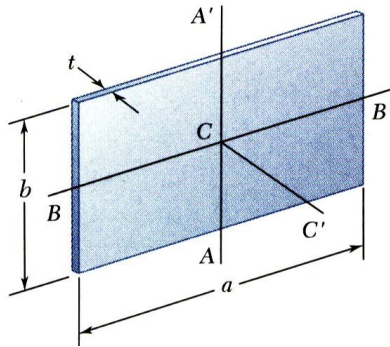


- For the axis CC' which is perpendicular to the plate,

$$\begin{aligned} I_{CC'} &= \rho t J_{C,area} = \rho t (I_{AA',area} + I_{BB',area}) \\ &= I_{AA'} + I_{BB'} \end{aligned}$$

Area Moments of Inertia

Moments of Inertia of Thin Plates

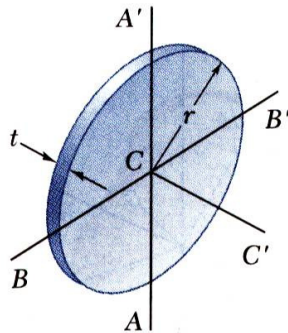


- For the principal centroidal axes on a rectangular plate,

$$I_{AA'} = \rho t I_{AA',area} = \rho t \left(\frac{1}{12} a^3 b \right) = \frac{1}{12} m a^2$$

$$I_{BB'} = \rho t I_{BB',area} = \rho t \left(\frac{1}{12} a b^3 \right) = \frac{1}{12} m b^2$$

$$I_{CC'} = I_{AA',mass} + I_{BB',mass} = \frac{1}{12} m (a^2 + b^2)$$

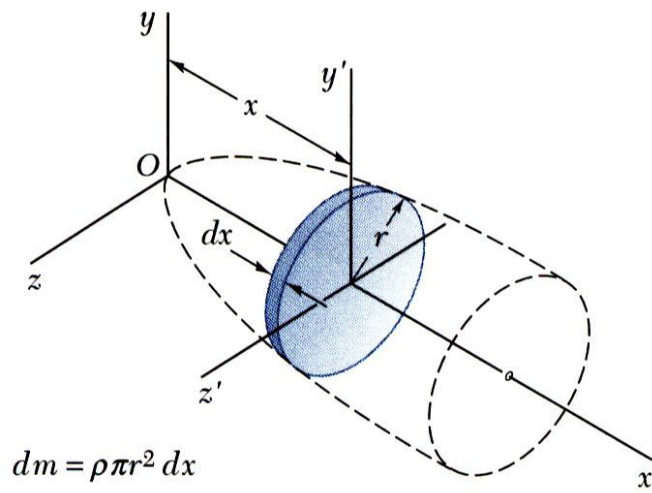


- For centroidal axes on a circular plate,

$$I_{AA'} = I_{BB'} = \rho t I_{AA',area} = \rho t \left(\frac{1}{4} \pi r^4 \right) = \frac{1}{4} m r^2$$

Area Moments of Inertia

Moments of Inertia of a 3D Body by Integration



$$dm = \rho \pi r^2 dx$$

$$dI_x = \frac{1}{2} r^2 dm$$

$$dI_y = dI_{y'} + x^2 dm = \left(\frac{1}{4} r^2 + x^2 \right) dm$$

$$dI_z = dI_{z'} + x^2 dm = \left(\frac{1}{4} r^2 + x^2 \right) dm$$

- Moment of inertia of a homogeneous body is obtained from double or triple integrations of the form

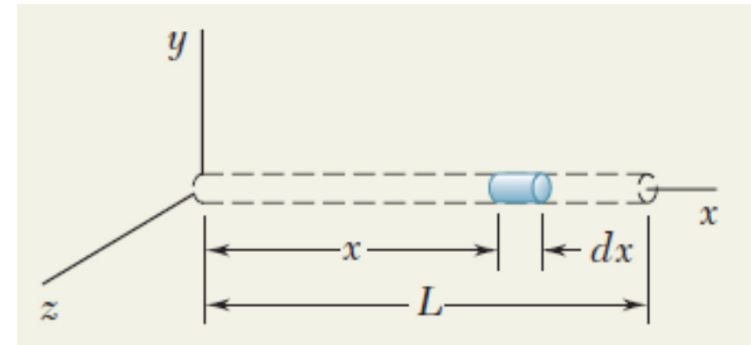
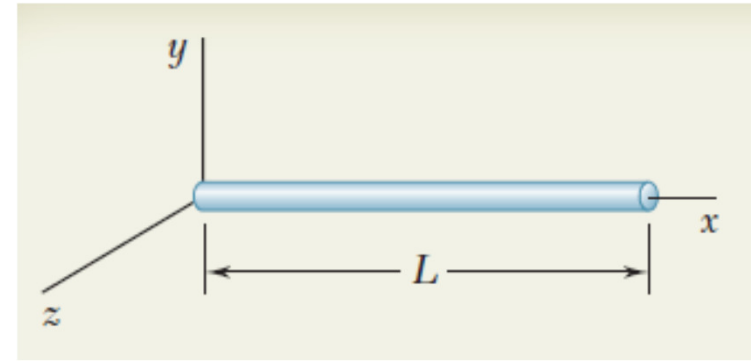
$$I = \rho \int r^2 dV$$

- For bodies with two planes of symmetry, the moment of inertia may be obtained from a single integration by choosing thin slabs perpendicular to the planes of symmetry for dm .
- The moment of inertia with respect to a particular axis for a composite body may be obtained by adding the moments of inertia with respect to the same axis of the components.

Q. No. Determine the moment of inertia of a slender rod of length L and mass m with respect to an axis which is perpendicular to the rod and passes through one end of the rod.

Solution

$$dm = \frac{m}{L}dx$$
$$I_y = \int x^2 dm = \int_0^L x^2 \frac{m}{L} dx = \left[\frac{m}{L} \frac{x^3}{3} \right]_0^L \quad I_y = \frac{1}{3}mL^2$$



Q. No. For the homogeneous rectangular prism shown, determine the moment of inertia with respect to z axis

Solution

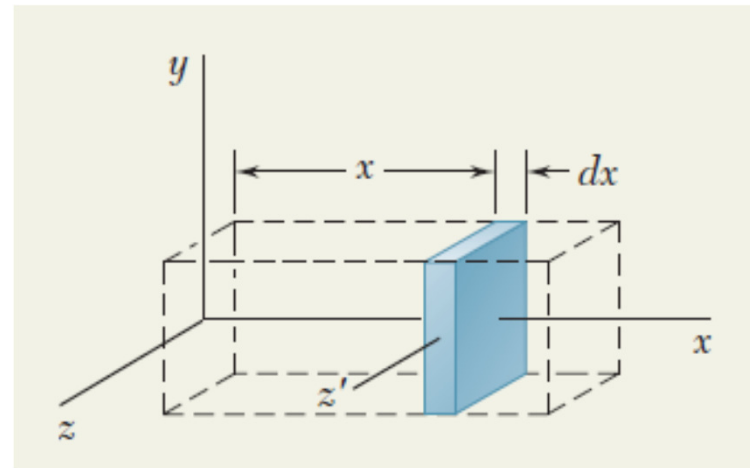
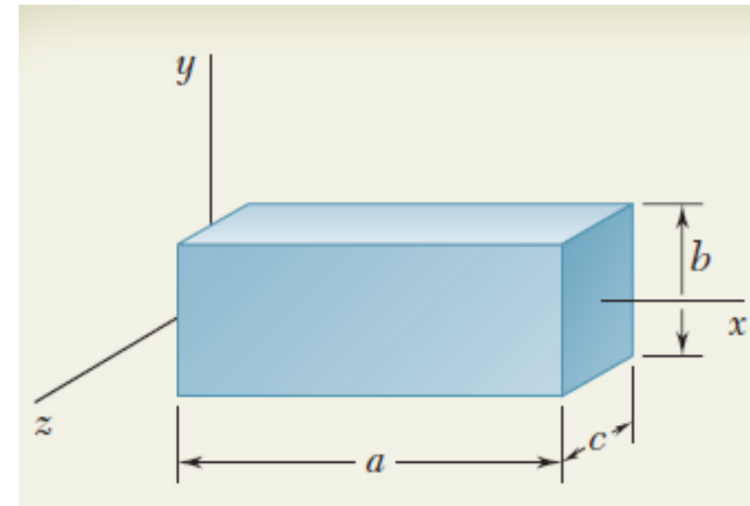
$$dm = \rho bc \, dx$$

$$dI_{z'} = \frac{1}{12}b^2 \, dm$$

$$dI_z = dI_{z'} + x^2 \, dm = \frac{1}{12}b^2 \, dm + x^2 \, dm = (\frac{1}{12}b^2 + x^2)\rho bc \, dx$$

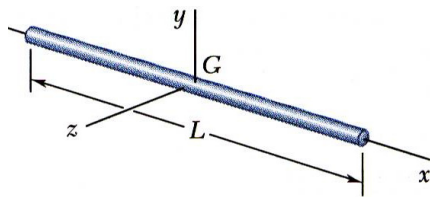
$$I_z = \int dI_z = \int_0^a (\frac{1}{12}b^2 + x^2)\rho bc \, dx = \rho abc(\frac{1}{12}b^2 + \frac{1}{3}a^2)$$

$$I_z = m(\frac{1}{12}b^2 + \frac{1}{3}a^2) \quad I_z = \frac{1}{12}m(4a^2 + b^2)$$

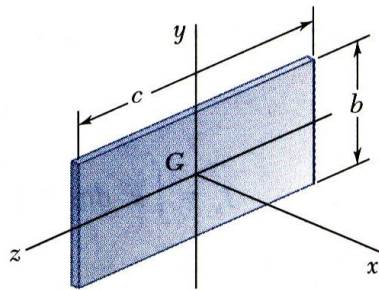


Area Moments of Inertia

MI of some common geometric shapes



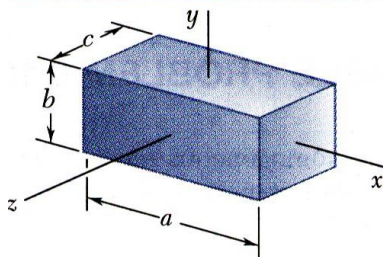
$$I_y = I_z = \frac{1}{12} mL^2$$



$$I_x = \frac{1}{12} m(b^2 + c^2)$$

$$I_y = \frac{1}{12} mc^2$$

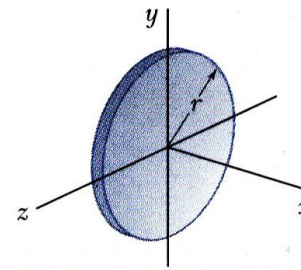
$$I_z = \frac{1}{12} mb^2$$



$$I_x = \frac{1}{12} m(b^2 + c^2)$$

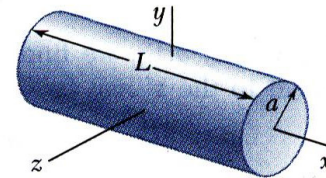
$$I_y = \frac{1}{12} m(c^2 + a^2)$$

$$I_z = \frac{1}{12} m(a^2 + b^2)$$



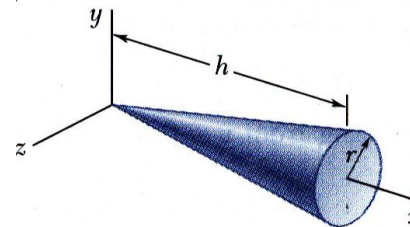
$$I_x = \frac{1}{2} mr^2$$

$$I_y = I_z = \frac{1}{4} mr^2$$



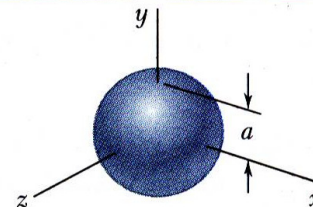
$$I_x = \frac{1}{2} ma^2$$

$$I_y = I_z = \frac{1}{12} m(3a^2 + L^2)$$



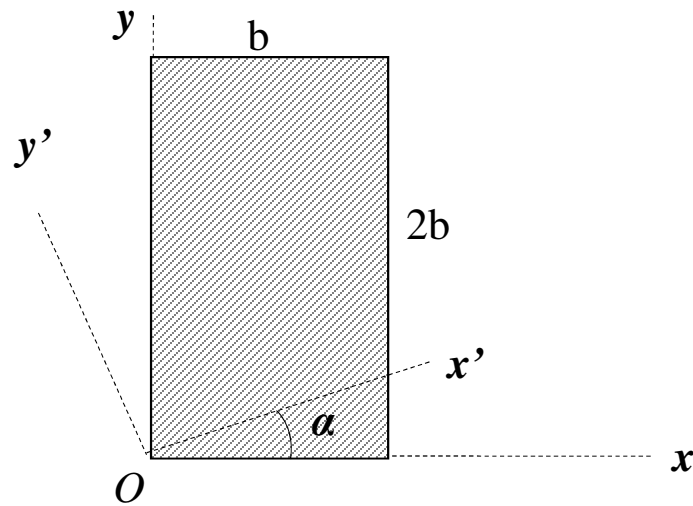
$$I_x = \frac{3}{10} ma^2$$

$$I_y = I_z = \frac{3}{5} m(\frac{1}{4} a^2 + h^2)$$



$$I_x = I_y = I_z = \frac{2}{5} ma^2$$

Q. Determine the angle α which locates the principal axes of inertia through point O for the rectangular area (Figure 5). Construct the Mohr's circle of inertia and specify the corresponding values of I_{max} and I_{min} .



$$I_x = \frac{1}{3}b(2b)^3 = \frac{8}{3}b^4$$

$$I_y = \frac{1}{3}2b(b)^3 = \frac{2}{3}b^4$$

$$I_{xy} = 2b^2\left(\frac{b}{2}\right)(b) = b^4$$

With this data, plot the Mohr's circle, and using trigonometry calculate the angle 2α

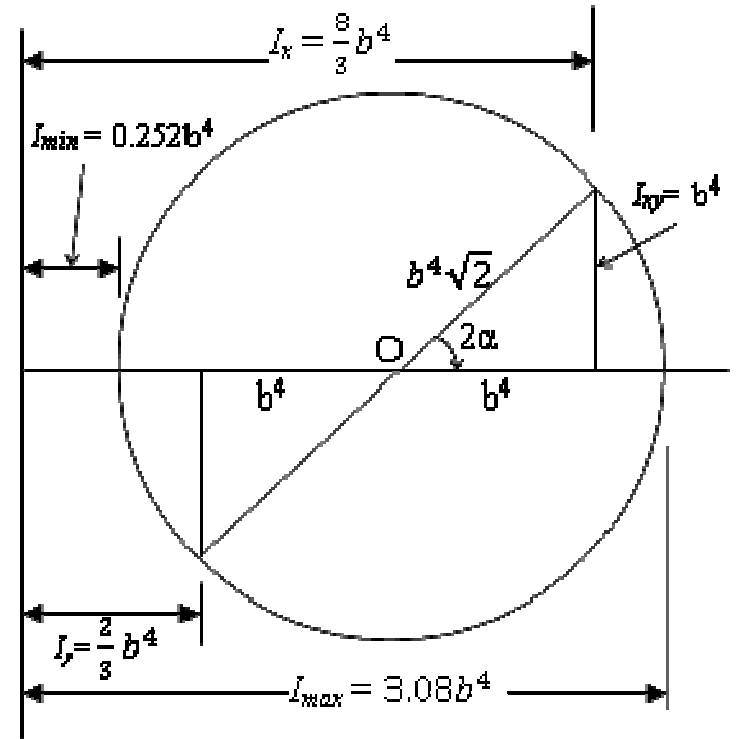
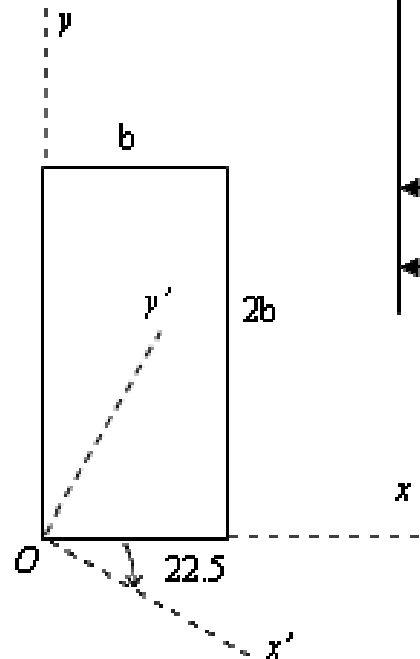
$$2\alpha = \tan^{-1}(b^4/b^4) = 45^\circ$$

Therefore, $\alpha = 22.5^\circ$ (clockwise w.r.t. x)

From Mohr's Circle:

$$I_{\max} = \frac{5}{3}b^4 + b^4\sqrt{2} = 3.08b^4$$

$$I_{\min} = \frac{5}{3}b^4 - b^4\sqrt{2} = 0.252b^4$$



Q. No. Determine the moments and product of inertia of the area of the square with respect to the x' - y' axes.

$$I_x = \frac{1}{3}b(b^3) = \frac{1}{3}b^4; \quad I_y = \frac{1}{3}b^4$$

$$I_{xy} = 0 + \left(\frac{b}{2} \times \frac{b}{2} \times b^2\right) = \frac{1}{4}b^4$$

With $\theta = 30^\circ$, using the equation of moment of inertia about any inclined axes

$$I_{x'} = \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta$$

$$I_{y'} = \frac{I_x + I_y}{2} - \frac{I_x - I_y}{2} \cos 2\theta + I_{xy} \sin 2\theta$$

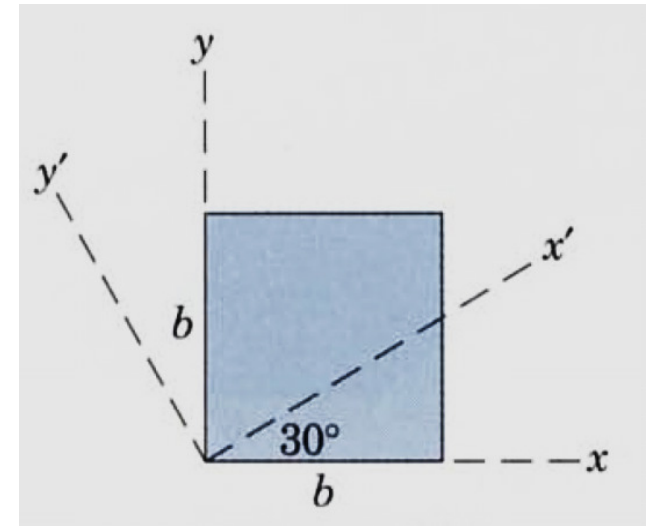
$$I_{x'y'} = \frac{I_x - I_y}{2} \sin 2\theta + I_{xy} \cos 2\theta$$

we get,

$$\rightarrow I_{x'} = \frac{b^4}{3} + 0 - \frac{1}{4}b^4 \sin 60^\circ = \left(\frac{1}{3} - \frac{\sqrt{3}}{8}\right)b^4 = 0.1168b^4$$

$$\rightarrow I_{y'} = \frac{b^4}{3} + 0 + \frac{1}{4}b^4 \sin 60^\circ = \left(\frac{1}{3} + \frac{\sqrt{3}}{8}\right)b^4 = 0.5498b^4$$

$$\rightarrow I_{x'y'} = 0 + \left(\frac{1}{4}b^4 \times \frac{1}{2}\right) = \left(\frac{1}{8} \times b^4\right) = 0.1250b^4$$



Alternatively, Mohr's Circle may be used to determine the three quantities.