Model checking pushdown systems

R. Ramanujam

Institute of Mathematical Sciences, Chennai

jam@imsc.res.in

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- Parameters: number of processes, delay duration
- Real time: discrete, dense domains

Extended automata

- A generic way of modelling such systems is by finite state automata with guarded transitions.
- An extended automaton is equipped with a finite set of variables $X = \{x_1, \dots, x_n\}$ with variable x_i taking values in set V_i .
- We have a finite set of guards G: each guard is a preicate over X.
- With each transition is associated an action, which is possibly a nondeterministic assignment to X.

Extended automata: semantics

A configuration is a tuple (q, v_1, \ldots, v_n) where q is a state and v_i is a valuation for x_i .

The transition system of the extended automaton is over configurations:

 $(q, v_1, \ldots, v_n) \Rightarrow (q', v'_1, \ldots, v'_n)$ if the automaton has a transition $q \stackrel{g,a}{\rightarrow} q'$, the values v_i satisfy guard g and the tuple (v'_1, \ldots, v'_n) is a possible result of applying a to (v_1, \ldots, v_n) .

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- FIFO automata: Variables queues; guards emptiness check; actions: insertion / deletion.
- Pushdown systems: Variables stack; guards – emptiness check; actions: push / pop.

Reachability problem

- Given: An extended automaton E, a set I of initial configurations and a set D of dangerous configurations.
- Decide if some $d \in D$ is reachable from some $c_0 \in I$.
- The sets *I* and *D* may be infinite.

Symbolic search

- Let post(C) denote the set of immediate successors of a possibly infinite set of configurations C.
- Forward search: Initialize C to I.
- Iterate $C := C \cup post(C)$ until $C \cap D \neq \emptyset$ or a fixed point is reached.
- Question: When is symbolic search effective ?

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- Any chain $C_1 \subseteq C_2 \subseteq \ldots$ reaches a fixpoint finitely.

Timed automata

- Variables are clocks: non-negative real valued.
- Transitions guarded by boolean combinations of comparisons with integer bounds, actions reset a subset of clocks.
- Equivalent configurations: when states are the same and values are equivalent with respect to constraints.
- Regions: equivalence classes of configurations.
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- Checking emptiness of C ∩ D: check if C contains some configuration with some state of Q_D as its first element.
- Checking equality of regions is decidable.
- Fixedpoint condition follows from the fact that the set of regions is finite.

Lossy channel systems

- Automata extended with unbounded queues.
- Send transitions: no guard, action: add message to channel.
- Receive transitions: guard: non-emptiness of channel; action removes first message.
- Loss transitions: no guard, self loop, removes an arbitrary message.

Symbolic reachability

- Order configurations by the subword ordering.
- Choose C to be all upward closed sets of configurations.
- Forward search does not work, satisfies conditions 1 to 5 but not 6.
- When *D* is a set of upward closed configurations, backward search works.

Backward symbolic search

- Key idea: Use Higman's lemma to show that any upward closed set can be finitely represented by its set of minimal elements w.r.t. the pointwise order ≥.
- Checking that if C is upward closed, so is pre(C) is easy.
- To show that a fixed point is reached in finitely many steps, again appeal to Higman's lemma.

Forward symbolic search

- Choose C to be the set of simple regular expressions.
- SREs satisfy the first 5 conditions, but the fixpoint cannot be effectively computed.
- One approach: find loops by (a kind of) static analysis (Abdallah et al LICS 99).
- Another: use Angluin's learning algorithms (Varadhan et al FSTTCS 04).

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- Applications: analysis of boolean programs, data-flow analysis, checkpoint algorithms (suspend computations to inspect stack content, for instance, to enforce security requirements).

Automata with stack

- Automata extended with one stack.
- Guards: Check the topmost symbol on stack.
- Actions: replace topmost symbol by a fixed word.
- Configuration (q, v): q holds values of global variables, v holds values of program pointer, values of local variables, return address.

Symbolic reachability

- Choose C to be the family of regular configurations.
- Each is represented by a DFA.
- *I* is typically finite and hence regular. Equality of regular sets is decidable.
- If *C* is regular, showing that pre(C) or post(C) is regular is straightforward.
- Büchi's theorem asserts that the fixedpoint of a chain is regular and can be effectively computed.

 In fact we often need to verify not only reachability but arbitrary LTL properties.

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- When valuations are arbitrary that is, the set of pushdown configurations in which an atomic proposition is true, is an arbitrary subset of the possible ones, model checking is undecidable.

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- These techniques can be extended to regular valuations.
- Lower bounds: the model checking problem is generically EXPTIME-complete.
- Over pushdown systems, model checking *CTL** reduces to model checking *LTL* over
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LTL:1

 Fix P, a countable set of atomic propositions. LTL formulae are defined by the following syntax:

$$\alpha ::= p \in P \mid \neg \alpha \mid \alpha \lor \beta \mid \bigcirc \alpha \mid \alpha \mathsf{U}\beta$$

- A model is a word $w : \mathcal{N} \to 2^P$, and the notion $w \models \alpha$ is defined as usual.
- Derived modalities: $\diamond \alpha = True \mathbf{U} \alpha$ and $\Box \alpha = \neg \diamond \neg \alpha$.

LTL:2

- Let $\mathcal{L}(\alpha) = \{w | w \models \alpha\}.$
- We know that for every formula α , we can construct a nondeterministic Büchi automaton B_{α} such that $\mathcal{L}(\alpha) = L(B_{\alpha})$, where B_{α} of size $O(2^{|\alpha|})$.
- Typically, we define a transition system
 T = (S, →, s₀, V) where V : S → 2^P is a
 valuation, and interpret formulas on runs of T.
 We thus define the model checking problem:
 T ⊨ α, if every infinite run of T satisfies α.

Pushdown systems-1

- A pushdown system is a tuple
 - $S = (C, \Gamma, \Delta, c_0, b)$: *C* is a finite set of control locations, Γ is the stack alphabet, Δ is the transition relation, c_0 is the initial location and *b* is the bottom stack symbol.
- $\Gamma \subseteq (C \times \Gamma) \times (C \times \Gamma^*)$, and a transition is written as: $(c, a) \rightarrow (d, w)$.
- A configuration is an element of $C \times \Gamma^*$.

Pushdown systems-2

- With a pushdown system S, we associate a transition system T_S with configurations as states, (c₀, b) as the initial state and the transition relation ⇒ is the least one satisfying:
 if (c, a) → (d, w) then for all u ∈ Γ*, (c, au) ⇒ (d, wu).
- Without loss of generality, we assume that *b* is never removed from stack, and that every transition increases the stack by at most one.

LTL on pushdown systems

Let $S = (C, \Gamma, \Delta, c_0, b)$ be a pushdown system, α an LTL formula, and $V : P \rightarrow 2^{C \times \Gamma^*}$. The model checking problem comes in three forms:

- Does $(c_0, b) \models \alpha$?
- Is there any configuration that violates α ?
- Is there any reachable configuration that violates α ?

All these problems are undecidable, in general.

Simple valuations

- A set of configurations C is said to be simple if $C \subseteq \{(c, aw) \mid w \in \Gamma^*\}$ for some $c \in C$, $a \in \Gamma$.
- A valuation V is simple, if for every $p \in P$, V(p) is a union of simple sets.

Regular valuations

- A valuation V is said to be regular if for every p ∈ P, V(p) is recognizable and does not contain any configuration with an empty stack.
- Then, for every $p \in P$ and $c \in C$, we have a DFA A_p^c over the alphabet Γ such that $V(p) = \{(c, w) \mid c \in C, w^R \in L(A_p^c)\}.$
- That is, p is true at (c, w) iff A^c_p enters a final state after reading the stack bottom up.

S-automata

- For a PDS $S = (C, \Gamma, \overline{\Delta}, c_0, b)$, an *S*-automaton is a tuple $A = (Q, \Gamma, \delta, C, F)$ where Q is a finite set of states, Γ (the stack alphabet of S) is its input alphabet, $\delta : (Q \times \Gamma) \rightarrow 2^Q$ is its transition function, C is its set of initial states and F is the set of accepting states.
- δ is extended as usual, and we say that a configiration (c, w) is accepted by A iff $\delta(c, w) \cap F \neq \emptyset$.
- A set of S-configurations C' is regular if it is accepted by some S-automaton.

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Consider the model checking problem for the initial configuration.

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- The problem is reduced to that of emptiness for Büchi pushdown systems.
- The emptiness problem for Büchi pushdown systems is reduced to that of computing the set of predecessors of certain regular sets of configurations.
- The set of predecessors is regular, and an algorithm is given for computing it; this is Büchi's saturation procedure.

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Step 1

- Given a PDS $S = (C, \Gamma, \Delta, c_0, b)$, and a formula α , first construct $A_{\alpha} = (Q, \delta, q_0, F)$ on 2^P .
- Construct the product $B = ((C \times Q), \Gamma, \Delta', (c_0, q_0), b, G)$ by "synchronizing" S and A_{α} .
- $((c,q),a) \rightarrow' ((c',q'),w))$ if $(c,a) \rightarrow (c',w)$ in Sand $q' \in \delta(q,\sigma)$, where σ is the set of propositions true in (c,a).
- Note that we are using the simplicity of valuations here.

Step 2

- Consider a transition $(c, a) \rightarrow (c', w)$ in B.
- It is repeating if there exists $v \in \Gamma^*$ such that (c, av) can be reached from (c, a) visiting G.
- Let Rep denoting repeating heads of transitions and let R denote the set $\{(c, aw) \mid (c, a) \in Rep, w \in \Gamma^*\}.$
- We can show that L(B) is nonempty iff $(c_0, b) \in pre^*(R)$.
- Rep is easily computed by an edge marking algorithm.

Regular valuations

- Suppose we have $P_{\alpha} = \{p_1, \dots, p_k\}$. Consider all the DFAs M_i^c for each $c \in C$.
- We form a vector of these automata in a canonical fashion with its (product) state from a set *States*.
- The crucial idea is to carry the state vector as part of the stack in a larger pushdown system with $\Gamma' = (\Gamma \times States.$
- Care is needed to ensure consistent configurations.