- Finite element analysis of vector fields
- FEM can be extended to deal BVP involving vector fields
- It is very important for electrodynamic problems
 - which deal with vector electromagnetic fields
- BVP:
- Consider the problem of finding the electric field intensity \vec{E}
 - due to impressed electric current density $ec{J}_{imp}$ in a domain Ω
 - characterized by permittivity arepsilon and permeability μ
- To calculate \vec{E} we need to solve Maxwell's equations

Introduction • $\nabla \times \vec{E} = -j\omega\mu\vec{H}$ (1) • $\nabla \times \vec{H} = j\omega\epsilon\vec{E} + \vec{J}_{imp}$ (2) • $\nabla \cdot (\epsilon\vec{E}) = -\frac{1}{j\omega}\nabla \cdot \vec{J}_{imp}$ $\because \nabla \cdot \vec{J} = -\frac{\partial\rho_{v}}{\partial t} = -j\omega\rho_{v}$ • $\nabla \cdot (\mu\vec{H}) = 0$ • subject to certain BCs

• In first equation divide by μ_r we have

•
$$\left(\frac{1}{\mu_r}\nabla \times \vec{E}\right) = -j\omega\mu_0\vec{H}$$

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• Taking another curl

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = -j\omega\mu_0 \left(\nabla \times \vec{H}\right)$$

• Putting second equation

•
$$\nabla \times \vec{H} = j\omega\epsilon\vec{E} + \vec{J}_{imp}$$

• in

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = -j\omega\mu_0 \left(\nabla \times \vec{H}\right)$$

• we have

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = -j\omega\mu_0 (j\omega\epsilon\vec{E} + \vec{J}_{imp})$$

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•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = \omega^2 \mu_0 \epsilon_0 \epsilon_r \vec{E} - j \omega \mu_0 \vec{J}_{imp}$$

• $\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = k_0^2 \epsilon_r \vec{E} - j \omega \mu_0 \vec{J}_{imp}$

• where
$$k_0^2 = \omega^2 \mu_0 \epsilon_0$$
, $Z_0 = \sqrt{\frac{\mu_0}{\epsilon_0}}$ and

• hence
$$Z_0 k_0 = \omega \sqrt{\mu_0 \epsilon_0} \sqrt{\frac{\mu_0}{\epsilon_0}} = \omega \mu_0$$

• So

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•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) - k_0^2 \epsilon_r \vec{E} = -j Z_0 k_0 \vec{J}_{imp}$$

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• The functional for such electrodynamic problems¹ is

•
$$F(\vec{E}) = \int_{\Omega} \left[\frac{1}{\mu_r} (\nabla \times \vec{E}) \cdot (\nabla \times \vec{E}) - k_0^2 \epsilon_r \vec{E} \cdot \vec{E} \right] d\Omega + jZ_0 k_0 \int \vec{E} \cdot \vec{J}_{imp} d\Omega$$

• For source free vector wave equation

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) - k_i^2 \epsilon_r \vec{E} = 0$$

• The functional is

•
$$F(\vec{E}) = \int_{\Omega} \left[\frac{1}{\mu_r} \left(\nabla \times \vec{E} \right) \cdot \left(\nabla \times \vec{E} \right) - k_i^2 \epsilon_r \vec{E} \cdot \vec{E} \right] d\Omega$$

 ¹ J.-M. Jin, The Finite Element Method in Electromagnetics, John Wiley & Sons, 2002

- The solution is the set of eignevalues k_i and associated eigenvectors \vec{E}_i
- High frequency variational function
- The 2-D variational functional analysis for a homogeneous waveguide
 - For homogeneously filled waveguide, eigenmode splits into TE and TM modes
- The functional for the transverse field components subject to the prescribed boundary condition
 - $\hat{n} \times \vec{E}_t = 0$
- is given on next slide

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- $F(\vec{E}_t) = \int \int_S \left[\frac{1}{\mu_r} (\nabla_t \times \vec{E}_t) \cdot (\nabla_t \times \vec{E}_t) k_0^2 \epsilon_r \vec{E}_t \cdot \vec{E}_t \right] dS$
- Considering TE modes
 - $E_z = 0$
- The vectors of unknowns {*e*} in the generalized eigenvalue problem is found as
 - $[S]{e} = k^2[T]{e}$
- which will also include prescribed values also

- In order include only contribution from free edges
 - $[S_{ff}]{e_f} = k^2 [T_{ff}]{e_f}$
- which will also include prescribed nodes also
- This can be obtained from the functional

•
$$F\{e\} = \{e_f e_p\}^T \begin{bmatrix} S_{ff} & S_{fp} \\ S_{pf} & S_{pp} \end{bmatrix} \{e_f e_p\}$$

• Differentiate $F\{e\}$ w.r.t. $\{e_f\}$

- then applying the prescribed conditions $\{e_p\}=0$
- We can get the above relation
 - $[S_{ff}]\{e_f\} = k^2 [T_{ff}]\{e_f\}$

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- Explicit formula for the elemental matrix entries
 - $S_{ij} = \int \int_{S} \left(\nabla_t \times \vec{N}_i \right) \cdot \left(\nabla_t \times \vec{N}_j \right) dS$

• and

- $T_{ij} = \int \int_{S} \vec{N}_i \cdot \vec{N}_j \, dS$
- For wave propagating along z-axis,
 - ∇_t and $\nabla_t \times$ are operators in the x-y plane
- The three simplex coordinates are given by
 - $\lambda_i = a_i + b_i x + c_i y$

• Therefore,

- $\lambda_1 = a_1 + b_1 x + c_1 y$
- $\lambda_2 = a_2 + b_2 x + c_2 y$
- $\lambda_3 = a_3 + b_3 x + c_3 y$
- In matrix form

$$\begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \end{bmatrix} = \begin{bmatrix} b_1 & c_1 & a_1 \\ b_2 & c_2 & a_2 \\ b_3 & c_3 & a_3 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

• Also we know that λ_i is equal to 1 for node *i* and zero for other nodes

• In matrix form

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} b_1 & c_1 & a_1 \\ b_2 & c_2 & a_2 \\ b_3 & c_3 & a_3 \end{bmatrix} \begin{bmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \\ 1 & 1 & 1 \end{bmatrix}$$

• Hence we can find (b_i, c_i, a_i) as follows

•
$$\begin{bmatrix} b_1 & c_1 & a_1 \\ b_2 & c_2 & a_2 \\ b_3 & c_3 & a_3 \end{bmatrix} = \begin{bmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \\ 1 & 1 & 1 \end{bmatrix}^{-1}$$

• Let us define

•
$$\vec{v}_{ij} = \nabla \lambda_i \times \nabla \lambda_j = (b_i \hat{x} + c_i \hat{y}) \times (b_j \hat{x} + c_j \hat{y}) = (b_i c_j - b_j c_i) \hat{z} = -\vec{v}_{ji}$$

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• Let us also define

- $\phi_{ij} = \nabla \lambda_i \cdot \nabla \lambda_j = (b_i \hat{x} + c_i \hat{y}) \cdot (b_j \hat{x} + c_j \hat{y}) = b_i b_j + c_i c_j$
- Now we can find curl of $\vec{N}_i = \vec{w}_{i1,i2} = \lambda_{i1} \nabla \lambda_{i2} \lambda_{i2} \nabla \lambda_{i1}$ where i_1 and i_2 are the endpoints of edge *i* as follows
- $\nabla \times \vec{N}_{i} = \nabla \times (\lambda_{i1} \nabla \lambda_{i2} \lambda_{i2} \nabla \lambda_{i1}) = \nabla \times (\lambda_{i1} \nabla \lambda_{i2}) \nabla \times (\lambda_{i2} \nabla \lambda_{i1})$
- Note that $\nabla \times (\phi \vec{A}) = \phi \nabla \times (\vec{A}) + \nabla \phi \times (\vec{A})$
- And since $\nabla \times (\nabla \Psi) = 0$ where Ψ is scalar function, we have,
- $\nabla \times (\lambda_{i1} \nabla \lambda_{i2}) = \nabla \lambda_{i1} \times \nabla \lambda_{i2}$ and $\nabla \times (\lambda_{i2} \nabla \lambda_{i1}) = \nabla \lambda_{i2} \times \nabla \lambda_{i1} = -\nabla \lambda_{i1} \times \nabla \lambda_{i2}$
- $\therefore \nabla \times \vec{N}_i = 2\nabla \lambda_{i1} \times \nabla \lambda_{i2} = 2\vec{v}_{i1,i2}$

• Hence

•
$$S_{ij} = \int \int_{S} (\nabla_{t} \times \vec{N}_{i}) \cdot (\nabla_{t} \times \vec{N}_{j}) dS =$$

4 $\int \int_{S} (\vec{v}_{i1,i2}) \cdot (\vec{v}_{j1,j2}) dS = 4A(\vec{v}_{i1,i2}) \cdot (\vec{v}_{j1,j2})$
• where $A = |A'|$ and A' is defined as
• $A' = \frac{1}{2} \begin{vmatrix} 1 & x_{1} & y_{1} \\ 1 & x_{2} & y_{2} \\ 1 & x_{3} & y_{3} \end{vmatrix}$
• Also note that $\vec{N}_{i} \cdot \vec{N}_{j} = (\lambda_{i1} \nabla \lambda_{i2} - \lambda_{i2} \nabla \lambda_{i1}) \cdot (\lambda_{j1} \nabla \lambda_{j2} - \lambda_{j2} \nabla \lambda_{j1})$

- $\vec{N}_i \cdot \vec{N}_j = (\lambda_{i1} \nabla \lambda_{i2} \lambda_{i2} \nabla \lambda_{i1}) \cdot (\lambda_{j1} \nabla \lambda_{j2} \lambda_{j2} \nabla \lambda_{j1})$
- $= \lambda_{i1}\lambda_{j1}\nabla\lambda_{i2} \cdot \nabla\lambda_{j2} \lambda_{i1}\lambda_{j2}\nabla\lambda_{i2} \cdot \nabla\lambda_{j1} \lambda_{i2}\lambda_{j1}\nabla\lambda_{i1} \cdot \nabla\lambda_{j1} + \lambda_{i2}\lambda_{j2}\nabla\lambda_{i1} \cdot \nabla\lambda_{j1}$
- = $\lambda_{i1}\lambda_{j1}\phi_{i2,j2} \lambda_{i1}\lambda_{j2}\phi_{i2,j1} \lambda_{i2}\lambda_{j1}\phi_{i1,j2} + \lambda_{i2}\lambda_{j2}\phi_{i1,j1}$
- Hence,
- $T_{ij} = \int \int_{S} \vec{N}_i \cdot \vec{N}_j \, dS$
- $= \int \int_{S} \left(\lambda_{i1} \lambda_{j1} \phi_{i2,j2} \lambda_{i1} \lambda_{j2} \phi_{i2,j1} \lambda_{i2} \lambda_{j1} \phi_{i1,j2} + \lambda_{i2} \lambda_{j2} \phi_{i1,j1} \right) dS$

- Hence, $T_{ij} = \int \int_{S} \vec{N}_i \cdot \vec{N}_j \, dS$
- $= \int \int_{S} \left(\lambda_{i1} \lambda_{j1} \phi_{i2,j2} \lambda_{i1} \lambda_{j2} \phi_{i2,j1} \lambda_{i2} \lambda_{j1} \phi_{i1,j2} + \lambda_{i2} \lambda_{j2} \phi_{i1,j1} \right) dS$
- = $\phi_{i2,j2} \int \int_{S} \lambda_{i1} \lambda_{j1} dS \phi_{i2,j1} \int \int_{S} \lambda_{i1} \lambda_{j2} dS$
- $-\phi_{i1,j2} \int \int_{S} \lambda_{i2} \lambda_{j1} dS + \phi_{i1,j1} \int \int_{S} \lambda_{i2} \lambda_{j2} dS$
- It has been shown that $M_{ij} = \int \int_S \lambda_i \lambda_j \, dS$
- $T_{ij} = \phi_{i2,j2} M_{i1,j1} \phi_{i2,j1} M_{i1,j2}$
- $-\phi_{i1,j2}M_{i2,j1} + \phi_{i1,j1}M_{i2,j2}$