

Lecture 5: Gauss-Jordan Method

Yesterday we discussed on:

→ The Gauss elimination Method

↳ Forward Elimination

↳ Backward Substitution

→ The algorithm for elimination in any k^{th} step was:

$$\left. \begin{aligned} a_{ij}^{(k)} &= a_{ij}^{(k-1)} - l_{ik} a_{kj}^{(k-1)} \\ b_i^{(k)} &= b_i^{(k-1)} - l_{ik} b_k^{(k-1)} \end{aligned} \right\} \begin{aligned} i &= k+1, k+2, \dots, n \\ j &= k, k+1, k+2, \dots, n \\ k &= 1, 2, 3, \dots, n-1 \end{aligned}$$

where
$$l_{ik} = \frac{a_{ik}^{(k-1)}}{a_{kk}^{(k-1)}}$$

Kindly check the website links for solved examples to see an example on Gauss elimination

Gauss - Jordan Method

→ The objective of Gauss-Jordan elimination is to reduce the matrix $[A]$ to an identity matrix.

→ In the process you will get a solution.

(2)

i.e.

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} \begin{Bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{Bmatrix} = \begin{Bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{Bmatrix}$$

Through a series of elimination the augmented matrix

$$\left[\begin{array}{cccc|c} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} & b_n \end{array} \right] \Rightarrow \left[\begin{array}{cccc|c} 1 & 0 & \dots & 0 & x_1 \\ 0 & 1 & 0 & \dots & 0 & x_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & & x_n \end{array} \right]$$

i.e. $[A]\{x\} = \{b\}$ becomes
 $[I]\{x\} = \{x\}$

→ The method is extension of Gauss-elimination

★ At each step,

- (i) First, the pivot element is made unity
→ Dividing pivotal row with pivotal element.

i.e.
$$\left[\begin{array}{cccc|c} a_{11} & a_{12} & a_{13} & \dots & a_{1j} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & a_{23} & \dots & a_{2j} & \dots & a_{2n} & b_2 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \ddots & \vdots & \vdots \\ a_{k1} & a_{k2} & a_{k3} & \dots & a_{kj} & \dots & a_{kn} & b_k \\ \vdots & \vdots & \vdots & \ddots & \vdots & \ddots & \vdots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \dots & a_{nj} & \dots & a_{nk} & b_n \end{array} \right]$$

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ie.
$$a_{kj}^{(k)} = \frac{a_{kj}^{(k-1)}}{a_{kk}^{(k-1)}} ; \begin{matrix} j = k, k+1, k+2, \dots, n \\ k = 1, 2, 3, \dots, n \end{matrix}$$

$$\therefore a_{kk}^{(k)} = 1 \quad \text{Also, } b_k^{(k)} = \frac{b_k^{(k-1)}}{a_{kk}^{(k-1)}}$$

(ii) Second, row operations as described in Gauss elimination need to be done.

The multiplying factor now will be

$$l_{ik} = \frac{a_{ik}^{(k-1)}}{a_{kk}^{(k-1)}} = a_{ik}^{(k-1)} ; \quad i = 1, 2, 3, \dots, k-1, k+1, k+2, \dots, n$$

(iii) Above and below the major diagonal, the elements have to be zero. \therefore Row operations performed for all rows except the pivotal row.

$$a_{ij}^{(k)} = a_{ij}^{(k-1)} - a_{ik}^{(k-1)} a_{kj}^{(k-1)}$$

$i = 1, 2, 3, \dots, k-1, k+1, k+2, \dots, n$ (No 'k' here)

$$b_i^{(k)} = b_i^{(k-1)} - a_{ik}^{(k-1)} b_k^{(k-1)} ; \quad i = 1, 2, 3, \dots, k-2, k-1, k+1, k+2, \dots, n$$

(No 'k' here).

* In Gauss-Jordan elimination, there is no need of back-substitution as vector $\{b\}$ itself arrives to the solution.

(4)

We will quickly do a small example problem:

Problem

Solve the linear system

$$\begin{aligned} -5x_1 + 2x_2 + x_3 &= 2 \\ x_1 - 8x_2 + 3x_3 &= -6 \\ 3x_1 + x_2 - 7x_3 &= -16 \end{aligned}$$

using Gauss-Jordan elimination method.

Solution

The given linear system can be represented as $[A]\{x\} = b$
 where $[A] = \begin{bmatrix} -5 & 2 & 1 \\ 1 & -8 & 3 \\ 3 & 1 & -7 \end{bmatrix}$; $\{x\} = \begin{Bmatrix} x_1 \\ x_2 \\ x_3 \end{Bmatrix}$; $\{b\} = \begin{Bmatrix} 2 \\ -6 \\ -16 \end{Bmatrix}$

The augmented matrix is $\left[\begin{array}{ccc|c} -5 & 2 & 1 & 2 \\ 1 & -8 & 3 & -6 \\ 3 & 1 & -7 & -16 \end{array} \right]$

First Step ($k=1$)

To make pivot element of $k=1$ row as 1.

$$\therefore a_{ij}^{(1)} = \frac{a_{ij}}{a_{11}}; j = 1, 2, 3$$

$$b_i^{(1)} = \frac{b_i}{a_{11}}$$

\therefore The augmented matrix looks.

$$\left[\begin{array}{ccc|c} 1 & -0.400 & -0.200 & -0.400 \\ 1 & -8 & 3 & -6 \\ 3 & 1 & -7 & -16 \end{array} \right] \begin{array}{l} R_2 = R_2 - a_{21} R_1 \\ R_3 = R_3 - a_{31} R_1 \end{array}$$

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$$\Rightarrow \left[\begin{array}{ccc|c} 1 & -0.400 & -0.200 & -0.400 \\ 0 & -7.600 & 3.200 & -5.600 \\ 0 & 2.200 & -6.400 & -14.800 \end{array} \right]$$

Second Step (k=2)

$$\left. \begin{array}{l} a_{2j}^{(2)} = \frac{a_{2j}^{(1)}}{a_{22}^{(1)}} \\ b_2^{(2)} = \frac{b_2^{(1)}}{a_{22}^{(1)}} \end{array} \right\} j = 1, 2, 3$$

\therefore We get

$$\left[\begin{array}{ccc|c} 1 & -0.400 & -0.200 & -0.400 \\ 0 & 1 & -0.421 & 0.737 \\ 0 & 2.200 & -6.400 & -14.800 \end{array} \right] \begin{array}{l} R_1 = R_1 - Q_{12} R_2 \\ R_3 = R_3 - Q_{32} R_2 \end{array}$$

$$Q_{12} = -0.400$$

$$Q_{32} = 2.200$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -0.368 & -0.105 \\ 0 & 1 & -0.421 & 0.737 \\ 0 & 0 & -5.474 & -16.421 \end{array} \right]$$

Third Step (k=3)

$$a_{3j}^{(3)} = \frac{a_{3j}^{(2)}}{a_{33}^{(2)}}, \quad b_3^{(3)} = \frac{b_3^{(2)}}{a_{33}^{(2)}} \quad ; \quad j = 1, 2, 3$$

$$\therefore \left[\begin{array}{ccc|c} 1 & 0 & -0.368 & -0.105 \\ 0 & 1 & -0.421 & 0.737 \\ 0 & 0 & 1 & 3.000 \end{array} \right] \begin{array}{l} R_1 = R_1 - Q_{13} R_3 \\ R_2 = R_2 - Q_{23} R_3 \end{array}$$

⑥

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{array} \right]$$

\therefore The solution vector is $\{x\} = \begin{Bmatrix} 1 \\ 2 \\ 3 \end{Bmatrix}$