

SOLVING DIFFERENTIAL EQUATIONS

We have seen two different categories of differential equations that are used to mathematically describe the various features in engineering and sciences

→ Ordinary Differential Equations

* IV - ODE

* BV - ODE

→ Partial Differential Equations

* Elliptic PDE

* Parabolic PDE

* Hyperbolic PDE

These differential equations were solved using

* Finite-Difference Method

till now.

Today, we will briefly go through Finite-Element Methods to solve such differential equations

* FEM is a vast topic and itself forms a separate course.

* With meagre two hours of lecture on FEM, the various features in it may not be possible to explain or solve.

* However, our objective here is to briefly cover some introductory aspects on FEM ~~etc.~~

* You may be just provided a hint that like FDM, one may also use FEM for solving

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differential equations.

* For more knowledge or information on FEM you may pursue higher level courses or books.

Q: What was FDM doing in solving differential equations?

S1 → FDM works on a methodology in which

- derivatives approximated by finite-difference formula
- substitute these formula in original differential eqn.
- obtain algebraic equations that need to be solved.

Now, the exact solution of the differential equation can be given ^{approximate} by approximate solutions that are linear combination of specific trial function

* The trial functions - independent functions
- satisfy boundary conditions.

* There will be unknown coefficients or weights that have to be assigned for each trial function

Consider a 1D BV-ODE

$$\frac{d^2 y}{dx^2} + \Phi y = F$$

with say

$$y(x_1) = y_1$$

$$y(x_2) = y_2$$



let $\Phi = \Phi(x)$
 $F = F(x)$

The exact solution of the above BV-ODE is $y(x)$.

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This exact solution is approximated by say $\tilde{y}(x)$

$$\tilde{y}(x) = \sum_{i=1}^I C_i y_i(x) = C_1 y_1(x) + C_2 y_2(x) + \dots + C_I y_I(x)$$

where $y_i \rightarrow$ trial functions

$C_i \rightarrow$ weights

$$y(x) \approx \tilde{y}(x) = \sum_{i=1}^I C_i y_i(x)$$

\Rightarrow Now if this entire domain is divided into small elements
 \rightarrow We can obtain the solution of each individual
elements and then added to form the global solution.
This is FEM.

Rayleigh - Ritz Method

\rightarrow Calculus of Variations is used in this approach.
 \rightarrow Objective of calculus of variations - to maximize
or minimize functionals (function of functions).

\rightarrow In the BV-ODE $\frac{d^2 y}{dx^2} + Qy = F$
 $y(x_1) = y_1$
 $y(x_2) = y_2$

You know the exact solution
is $y(x)$.

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→ A simple problem in calculus of variations is about a function in one independent variable $y(x)$ is a function in x .

→ We need to extremise a functional
Consider the functional

$$I[y] = \int_a^b G(x, y, y') dx$$

where $I[y]$ is the functional that has to be extremised in calculus of variations.

$G(x, y, y')$ → fundamental function

a and b are the limits in x -direction.

→ The objective here is to determine that particular $y(x)$ which extremises $I[y]$.

→ Derivative of a functional → called Variation.

Use the symbol δ

* Derivative of ordinary function given by symbol d .

As we are having fixed end points a and b .

$$\delta I = \int_a^b \left(\frac{\partial G}{\partial y} \delta y + \frac{\partial G}{\partial y'} \delta y' \right) dx$$

$$= \int_a^b \left(\frac{\delta G}{\delta y} \delta y + \frac{\partial G}{\partial y'} \delta \left(\frac{dy}{dx} \right) \right) dx$$

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$$= \int_a^b \left(\frac{\delta G}{\delta y} \delta y + \frac{\partial G}{\partial y'} \frac{d(\delta y)}{dx} \right) dx$$

Integrating by parts

$$\delta I = \int_a^b \left(\frac{\partial G}{\partial y} \delta y \right) dx + \left. \frac{\partial G}{\partial y'} \delta y \right|_a^b - \int_a^b \frac{d}{dx} \left(\frac{\partial G}{\partial y'} \right) \delta y dx$$

Uses for fixed points

$$\begin{aligned} \delta y(x=a) &= 0 \\ \delta y(x=b) &= 0 \end{aligned}$$

$$\therefore \delta I = \int_a^b \left[\frac{\partial G}{\partial y} - \frac{d}{dx} \left(\frac{\partial G}{\partial y'} \right) \right] \delta y dx = 0 \quad (\text{Extremisation})$$

For any δy , then

$$\boxed{\frac{\partial G}{\partial y} - \frac{d}{dx} \left(\frac{\partial G}{\partial y'} \right) = 0} \quad \text{or} \quad \frac{\partial G}{\partial y} = \frac{d}{dx} \left(\frac{\partial G}{\partial y'} \right)$$

This is Euler's equation of calculus of variation

So in the given problem the fundamental function $G(x, y, y')$ has to be formulated in such a way that

$$I[y] = \int_a^b G(x, y, y') dx$$

As $I[y]$ has to be extremum

let us correlate our differential equation $\frac{d^2 y}{dx^2} + \phi y = F$ to this functional $I[y]$ by suggests that the extremisation

$$\therefore I[y] = \int_a^b y'' + \phi y - F dx$$

of $I[y]$ gives $\frac{d^2 y}{dx^2} + \phi y - F = 0$

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$$\text{i.e. } \delta I = 0 = y'' + \phi y - F$$

→ The fundamental function G for this case will be

$$G(x, y, y') = (y')^2 - \phi y^2 + 2Fy$$

$$\therefore I[y] = \int_a^b [(y')^2 - \phi y^2 + 2Fy] dx$$

We know

$$\frac{\partial G}{\partial y} = \frac{d}{dx} \left(\frac{\partial G}{\partial y'} \right)$$

$$\text{i.e. } \frac{\partial}{\partial y} [(y')^2 - \phi y^2 + 2Fy] = \frac{d}{dx} \left\{ \frac{\partial}{\partial y'} [(y')^2 - \phi y^2 + 2Fy] \right\}$$

$$\text{i.e. } -2\phi y + 2F = \frac{d}{dx} (2y') = 2 \frac{d^2 y}{dx^2}$$

$$\text{i.e. } \frac{d^2 y}{dx^2} + \phi y = F \quad \text{The required ODE}$$

Now this exact solution is approximated by $\tilde{y}^{(x)}$

$$\tilde{y}^{(x)} = \tilde{y}(x, \alpha, d, e, f, \dots)$$

$$I[y^{(x)}] \approx I[\tilde{y}] = I[y(x, \alpha, d, e, f, \dots)]$$

$$\delta I = 0 = \frac{\partial I}{\partial \alpha} \delta \alpha + \frac{\partial I}{\partial d} \delta d + \dots$$

This is satisfied only if $\frac{\partial I}{\partial \alpha} = 0$, $\frac{\partial I}{\partial d} = 0$, \dots

∴ To determine the function $\tilde{y}^{(x)}$ you require parameter values α, d, e, f, \dots

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Once these parameters are identified you get $\tilde{y}(x)$, which is approximate soln. of BV-ODE.

So the Raleigh - Ritz method Steps:

(i) Determine $I[y(x)]$ that gives the BV-ODE from the Euler equation

(ii) $y(x) \approx \tilde{y}(x) = \sum_{i=1}^I C_i y_i(x)$

(iii) Substitute $\tilde{y}(x) = \sum_{i=1}^I C_i y_i$ in $I[y(x)]$

Get $I[C_i]$

(iv) $\frac{\partial I}{\partial C_i} = 0$

(v) Solve to get C_i

e.g. If $y(x_1) = y(0.0) = 0.0$
 $y(x_2) = y(1.0) = Y$

Then $I[\tilde{y}] = \int_0^1 [(y')^2 - \phi y^2 + 2Fy] dx$

$$y(x) = C_1 y_1(x) + C_2 y_2(x) + C_3 y_3(x)$$
$$= C_1 x + C_2 x(x-1) + C_3 x^2(x-1)$$

The three trial functions $y_1(x)$, $y_2(x)$ and $y_3(x)$ are linearly independent.

Applying boundary conditions

$y(1.0) = Y = C_1$

~~$y_1(x=0.0) = 0$~~
 ~~$y_1(x=1.0) = 1$~~

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$$\therefore y(x) = Yx + C_2 x(x-1) + C_3 x^2(x-1) = y(x, C_2, C_3)$$

Now integrate

$$I[y] = \int_0^1 ((y')^2 - Qy^2 + 2Fy) dx$$

$$\text{Obtain } \frac{\partial I}{\partial C_2} = 0 \quad \int \text{to obtain } C_2 \text{ and } C_3.$$
$$\frac{\partial I}{\partial C_3} = 0$$