

Lecture 40: Parabolic Partial Differential Equations

(05-Nov-2012)

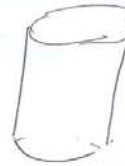
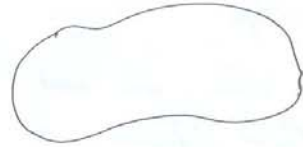
PARTIAL DIFFERENTIAL EQUATIONS

LECTURE 40

Yesterday, we were discussing on how to implement finite-difference methods for solving PDEs in non-rectangular domains

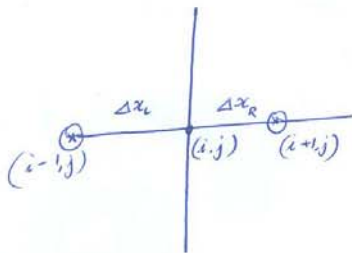
Some approaches for modeling non-rectangular domains

- * Approximating physical domain
- * Use other co-ordinate system
- * Non-uniform finite-difference approximations
- * Transform the non-rectangle space to rectangle space.



→ You can use cylindrical coordinates here.

The Non-uniform FD Approximations



If the grid space between grid points are non-uniform, then the FD method should be given as below.

$$f_{i+1,j} = f_{i,j} + \frac{\partial f}{\partial x} \Big|_{i,j} \Delta x_R + \frac{\partial^2 f}{\partial x^2} \Big|_{i,j} \frac{(\Delta x_R)^2}{2} + \frac{1}{6} (\Delta x_R)^3 \frac{\partial^3 f}{\partial x^3} \Big|_{i,j} + \dots \quad (1)$$

$$f_{i-1,j} = f_{i,j} + \frac{\partial f}{\partial x} \Big|_{i,j} (-\Delta x_L) + \frac{\partial^2 f}{\partial x^2} \Big|_{i,j} \frac{(\Delta x_L)^2}{2} + \frac{1}{6} (-\Delta x_L)^3 \frac{\partial^3 f}{\partial x^3} \Big|_{i,j} + \dots \quad (2)$$

∴ Multiply by Δx_L on eq (1) and Δx_R on eq (2) and adding:

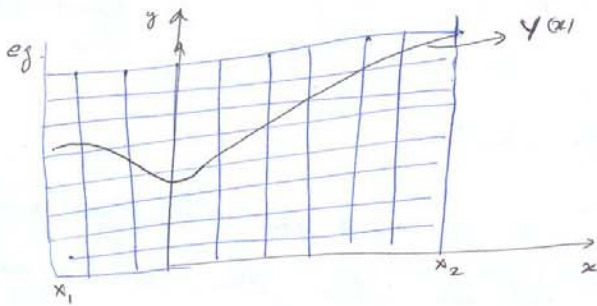
$$\Delta x_L f_{i+1,j} + \Delta x_R f_{i-1,j} = (\Delta x_L + \Delta x_R) f_{i,j} + \frac{1}{2} (\Delta x_L \Delta x_R^2 + \Delta x_L^2 \Delta x_R) \frac{\partial^2 f}{\partial x^2} \Big|_{i,j} + \dots$$

$$\text{or } \frac{\partial^2 f}{\partial x^2} \Big|_{i,j} = \frac{2 \Delta x_L}{(\Delta x_L \Delta x_R^2 + \Delta x_L^2 \Delta x_R)} f_{i+1,j} - \frac{2 (\Delta x_L + \Delta x_R)}{(\Delta x_L \Delta x_R^2 + \Delta x_L^2 \Delta x_R)} f_{i,j} + \frac{2 \Delta x_R}{(\Delta x_L \Delta x_R^2 + \Delta x_L^2 \Delta x_R)}$$

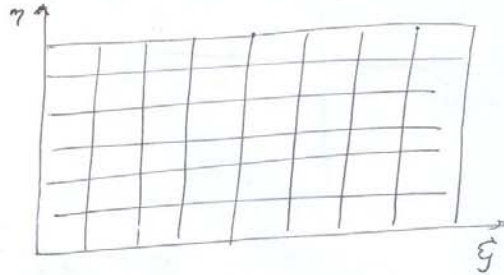
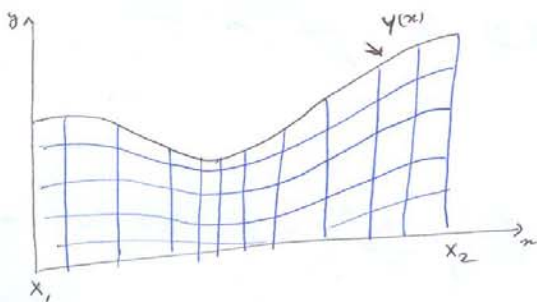
which you can get $\frac{\partial^2 f}{\partial x^2} \Big|_{i,j}$

Grid Transformation

- * Most of the engineering and science problems, described in PDE's are usually in orthogonal Cartesian coordinate system.
- * When you used the finite-difference method, the domain computational domain is also orthogonal in nature.
 - The non-rectangular physical domain can be converted to rectangular computational domain by grid transformation.



→ In the figure show the upper boundary of the physical space does not fall on grid cell boundaries.



The co-ordinates are transformed such a way that ξ and η are orthogonal

$$\xi = \xi(x, y) \quad \text{and} \quad \eta = \eta(x, y)$$

∴ The inverse transformation will be $x = x(\xi, \eta)$

$$a \frac{\partial b}{\partial x} + b \frac{\partial b}{\partial y} = c$$

$$\frac{\partial b}{\partial x} = \frac{\partial b}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial b}{\partial \eta} \frac{\partial \eta}{\partial x}$$

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Similarly for $\frac{\partial b}{\partial y} = \frac{\partial b}{\partial s} \frac{\partial s}{\partial y} + \frac{\partial b}{\partial \tau} \frac{\partial \tau}{\partial y}$

At $x = x_1, \quad \xi = \xi_{min}$
 $x = x_2, \quad \xi = \xi_{max}$

$\frac{\partial s}{\partial x}$ and $\frac{\partial s}{\partial y}$ are properties, $\therefore s = s(x, y)$

PARABOLIC PARTIAL DIFFERENTIAL EQUATIONS

Consider the diffusion equation

$$\frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial x^2}$$

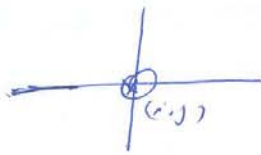
$\therefore \frac{\partial b}{\partial t} = \alpha \frac{\partial^2 b}{\partial x^2}$, etc.

\Rightarrow These are propagation problems.

\Rightarrow Propagation problems require initial values.

At any grid-point (i, j) the partial derivative will be

$$\frac{\partial b}{\partial t} = \alpha \left(\frac{\partial^2 b}{\partial x^2} + \frac{\partial^2 b}{\partial y^2} \right)$$



$$\frac{\partial b}{\partial t} \Big|_{(i,j)}^{(n)}$$

$$\frac{\partial^2 b}{\partial x^2} \Big|_{(i,j)}^{(n)}, \quad \frac{\partial^2 b}{\partial y^2} \Big|_{(i,j)}^{(n)}$$

i.e. $\frac{\partial b}{\partial t} \Big|_{(i,j)}^{(n)} = \frac{b_{i,j}^{(n+1)} - b_{i,j}^{(n)}}{\Delta t} \rightarrow \text{Forward Time.}$

$$\frac{\partial^2 b}{\partial x^2} \Big|_{(i,j)}^{(n)} = \frac{b_{i+1,j}^{(n)} - 2b_{i,j}^{(n)} + b_{i-1,j}^{(n)}}{\Delta x^2}$$

$$\frac{\partial^2 b}{\partial y^2} \Big|_{(i,j)}^{(n)} = \frac{b_{i,j+1}^{(n)} - 2b_{i,j}^{(n)} + b_{i,j-1}^{(n)}}{\Delta y^2}$$

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One can develop Forward Time Central Space (FTCS) finite difference equation for parabolic PDE.

$$\frac{f_{i,j}^{(n+1)} - f_{i,j}^{(n)}}{\Delta t} = \alpha \left[\frac{f_{i+1,j}^{(n)} - 2f_{i,j}^{(n)} + f_{i-1,j}^{(n)}}{\Delta x^2} + \frac{f_{i,j+1}^{(n)} - 2f_{i,j}^{(n)} + f_{i,j-1}^{(n)}}{\Delta y^2} \right]$$

$$\text{i.e. } f_{i,j}^{(n+1)} = f_{i,j}^{(n)} + \left(\alpha \frac{\Delta t}{\Delta x^2} \right) f_{i+1,j}^{(n)} - 2\alpha \Delta t \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} \right) f_{i,j}^{(n)} + \left(\frac{\alpha \Delta t}{\Delta x^2} \right) f_{i-1,j}^{(n)} + \left(\frac{\alpha \Delta t}{\Delta y^2} \right) f_{i,j+1}^{(n)} + \left(\frac{\alpha \Delta t}{\Delta y^2} \right) f_{i,j-1}^{(n)}$$

→ You can check the consistency and stability of the method. ⇒ Explicit Method.

Do the stability analysis of one-dimensional FTCS finite difference equation of $\frac{\partial f}{\partial t} = \alpha \frac{\partial^2 f}{\partial x^2}$

$$f_i^{(n+1)} = f_i^{(n)} + \left(\alpha \frac{\Delta t}{\Delta x^2} \right) f_{i+1}^{(n)} - 2 \frac{\alpha \Delta t}{\Delta x^2} f_i^{(n)} + \left(\frac{\alpha \Delta t}{\Delta x^2} \right) f_{i-1}^{(n)}$$

Let us define

$$d = \frac{\alpha \Delta t}{\Delta x^2}$$

$$\therefore f_i^{(n+1)} = f_i^{(n)} + d (f_{i+1}^{(n)} - 2f_i^{(n)} + f_{i-1}^{(n)})$$

$$f_i^{(n+1)} = G f_i^{(n)}$$

where $G \rightarrow$ Amplification factor

$$|G| \leq 1.0 \quad \text{for stability}$$

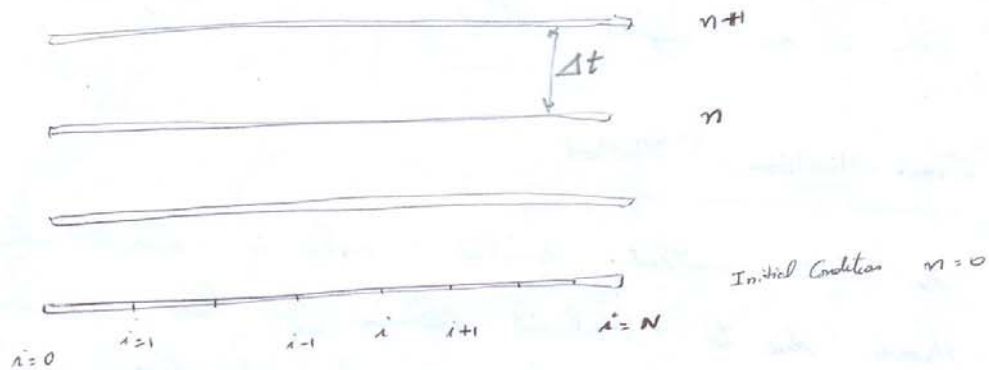
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Backward Time Centered Space Method (BTCS)

Consider the one-dimensional diffusion equation

$$\frac{\partial \phi}{\partial t} = \alpha \frac{\partial^2 \phi}{\partial x^2} \quad \rightarrow (1)$$

If we approximate the derivatives at $(n+1)$ time step
Please note your problem domain (temporal and spatial)



The one-dimensional spatial domain has to be evaluated at each time step

- let Δt \rightarrow Time step size
- $n+1$ \rightarrow The time step is present
- $n=0$ \rightarrow Initial condition
- $n+1$ \rightarrow Future time step.

$$\therefore \left. \frac{\partial \phi}{\partial t} \right|_i^{(n+1)} = \frac{\phi_i^{(n+1)} - \phi_i^{(n)}}{\Delta t} \quad O(\Delta t)$$

$$\left. \frac{\partial^2 \phi}{\partial x^2} \right|_i^{(n+1)} = \frac{\phi_{i+1}^{(n+1)} - 2\phi_i^{(n+1)} + \phi_{i-1}^{(n+1)}}{\Delta x^2} \quad O(\Delta x^2)$$

Backward-Difference Approx.

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Substituting in eqn. (1)

$$\frac{f_i^{(n+1)} - f_i^{(n)}}{\Delta t} = \alpha \frac{f_{i+1}^{(n+1)} - 2f_i^{(n+1)} + f_{i-1}^{(n+1)}}{\Delta x^2}$$

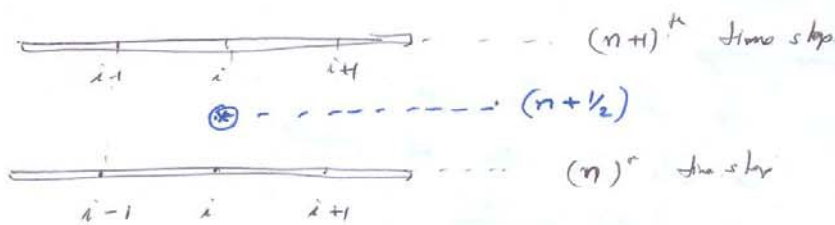
$$\text{or } \left(\frac{\alpha \Delta t}{\Delta x^2}\right) f_{i-1}^{(n+1)} - \left(1 + 2\frac{\alpha \Delta t}{\Delta x^2}\right) f_i^{(n+1)} + \left(\frac{\alpha \Delta t}{\Delta x^2}\right) f_{i+1}^{(n+1)} = -f_i^{(n)}$$

This will be the FDE for diffusion pde when we use BTCS method.

This is an implicit method.

Crank-Nicolson Method

The BTCS method described earlier is unconditionally stable. However due to backward difference for time, we have first-order approximation for temporal derivative.



$$\text{Now } f_i^{(n+1)} = f_i^{(n+1/2)} + \frac{\partial f}{\partial t} \Big|_i^{(n+1/2)} \left(\frac{\Delta t}{2}\right) + \frac{1}{2} \frac{\partial^2 f}{\partial t^2} \Big|_i^{(n+1/2)} \left(\frac{\Delta t^2}{4}\right) + \dots$$

$$f_i^{(n)} = f_i^{(n+1/2)} - \frac{\partial f}{\partial t} \Big|_i^{(n+1/2)} \frac{\Delta t}{2} + \frac{1}{2} \frac{\partial^2 f}{\partial t^2} \Big|_i^{(n+1/2)} \left(\frac{\Delta t^2}{4}\right) + \dots$$

$$\therefore f_i^{(n+1)} - f_i^{(n)} = 2 \frac{\partial f}{\partial t} \Big|_i^{(n+1/2)} \frac{\Delta t}{2} + O(\Delta t^3)$$

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$$\therefore \frac{\partial f}{\partial t} \Big|_i^{n+1/2} = \frac{f_i^{(n+1)} - f_i^{(n)}}{\Delta t} + O(\Delta t^2)$$

This is second-order approximation.

$$\therefore \frac{\partial f}{\partial t} \Big|_i^{n+1/2} = \alpha \frac{\partial^2 f}{\partial x^2} \Big|_i^{n+1/2}$$

Now $\frac{\partial^2 f}{\partial x^2} \Big|_i^{n+1/2} = \frac{1}{2} \left[\frac{\partial^2 f}{\partial x^2} \Big|_i^{(n+1)} + \frac{\partial^2 f}{\partial x^2} \Big|_i^{(n)} \right]$

i.e. $\frac{f_i^{(n+1)} - f_i^{(n)}}{\Delta t} = \frac{\alpha}{2} \left[\frac{\partial^2 f}{\partial x^2} \Big|_i^{(n+1)} + \frac{\partial^2 f}{\partial x^2} \Big|_i^{(n)} \right]$

i.e. $\frac{f_i^{(n+1)} - f_i^{(n)}}{\Delta t} = \frac{\alpha}{2} \left[\frac{f_{i+1}^{(n+1)} - 2f_i^{(n+1)} + f_{i-1}^{(n+1)}}{\Delta x^2} + \frac{f_{i+1}^{(n)} - 2f_i^{(n)} + f_{i-1}^{(n)}}{\Delta x^2} \right]$

$$\text{or } \left(\frac{\alpha \Delta t}{2 \Delta x^2} \right) f_{i-1}^{(n+1)} - \left(1 + \frac{\alpha \Delta t}{\Delta x^2} \right) f_i^{(n+1)} + \frac{\alpha \Delta t}{2 \Delta x^2} f_{i+1}^{(n+1)} = - \left(\frac{\alpha \Delta t}{2 \Delta x^2} \right) f_{i-1}^{(n)} + \left(-1 + \frac{\alpha \Delta t}{\Delta x^2} \right) f_i^{(n)} - \frac{\alpha \Delta t}{2 \Delta x^2} f_{i+1}^{(n)}$$

This is the FDE for diffusion PDE using Crank-Nicholson method. Both temporal and spatial derivatives are approximated by second-order terms.

⇒ Another example of parabolic partial differential equation is Convection-Diffusion Equation (or Advection-Dispersion Equation).

$$\frac{\partial f}{\partial t} + u \frac{\partial f}{\partial x} = \alpha \frac{\partial^2 f}{\partial x^2}$$

where $u \rightarrow$ convection velocity
 $\alpha \rightarrow$ Diffusion coefft.

You may use the FTCS, or BTCS, or Crank-Nicholson

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scheme to solve the convection - Diffusion equation.

⇒ tomorrow we will discuss on Hyperbolic partial differential equation.