

Lecture 36: Multi-point methods

Boundary-Value Differential Equations

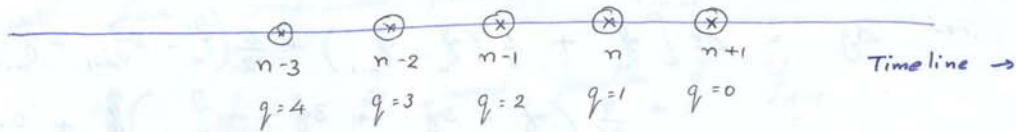
(30-Oct-2012)

LECTURE 36

30-OCT-2012

Multi-Point Methods for IV-ODE

Yesterday we started the discussion on multi-point finite-difference methods to solve IV-ODE.



When $q=1$,

$$\int_{y_n}^{y_{n+1}} dy = \Delta y = \int_{t_n}^{t_{n+1}} P_k(t) dt$$

gives Adams - finite difference equations.

In the process, we discussed on Adams - Bashforth explicit and Adams - Moulton implicit 4th order finite-difference equations, which we can again discuss as below.

⇒ The 4th order Adams - Bashforth explicit equation was developed using a third-degree Newton's backward difference polynomial, ~~at~~ with its base point at time t_n .

$$P_3(s) = f_n + s \nabla f_n + \frac{s(s+1)}{2} \nabla^2 f_n + \frac{s(s+1)(s+2)}{6} \nabla^3 f_n + O(s^4)$$

t	f	∇f	$\nabla^2 f$	$\nabla^3 f$
t_{n-3}	f_{n-3}			
t_{n-2}	f_{n-2}	$f_{n-2} - f_{n-3}$	$f_{n-1} - 2f_{n-2} + f_{n-3}$	$f_n - 3f_{n-1} + 3f_{n-2} - f_{n-3}$
t_{n-1}	f_{n-1}	$f_{n-1} - f_{n-2}$	$f_n - 2f_{n-1} + f_{n-2}$	$f_{n+1} - 3f_n + 3f_{n-1} - f_{n-2}$
t_n	f_n	$f_n - f_{n-1}$	$f_{n+1} - 2f_n + f_{n-1}$	
t_{n+1}	f_{n+1}	$f_{n+1} - f_n$		

$$I = \int_{y_n}^{y_{n+1}} dy = \Delta y = \int_{t_n}^{t_{n+1}} [P_3(t)]_n dt$$

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ie. A_n $s = \frac{t - t_n}{\Delta t}$, $ds = \frac{dt}{\Delta t}$

$$\therefore \Delta y = \Delta t \int_0^1 \left[f_n + s \nabla f_n + \frac{(s^2 + s)}{2} \nabla^2 f_n + (s^3 + 3s^2 + 2s) \nabla^3 f_n + O(\Delta t^4) \right] ds$$

ie. $\Delta y = \Delta t \left[f_n + \frac{1}{2} (f_n - f_{n-1}) + \frac{5}{12} (f_n - 2f_{n-1} + f_{n-2}) + \frac{9}{24} (f_n - 3f_{n-1} + 3f_{n-2} - f_{n-3}) + O(\Delta t^4) \right]$

ie. $\Delta y = \frac{\Delta t}{24} [55 f_n - 59 f_{n-1} + 37 f_{n-2} - 9 f_{n-3}] + O(\Delta t^5)$

\Rightarrow In a similar way you can develop 4th order Adams-Moulton implicit finite-difference equation.

$$\Delta y = \frac{\Delta t}{24} [9 f_{n+1} + 19 f_n - 5 f_{n-1} + f_{n-2}]$$

\Rightarrow The Adams-Bashforth - Moulton predictor-corrector approach to solve the IVP-ODE is as given below:

$$\begin{aligned} y_{n+1}^P &= y_n + \frac{\Delta t}{24} [55 f_n - 59 f_{n-1} + 37 f_{n-2} - 9 f_{n-3}] \\ y_{n+1}^C &= y_n + \frac{\Delta t}{24} [9 f_{n+1}^P + 19 f_n - 5 f_{n-1} + f_{n-2}] \end{aligned}$$

Non-linear Expressions In Implicit Finite-Difference Eqns.

You have seen that to solve:

$$\frac{dy}{dt} = f(t, y) \quad ; \quad y(t_0) = y_0$$

\Rightarrow You can use explicit and implicit schemes.

(3)

If $f(t, y)$ is non-linear in y , then in the implicit formulations

eg: Euler's $y_{n+1} = y_n + \Delta t f(t_{n+1}, y_{n+1})$
say

will have non-linear term in y_{n+1}

i.e. y_{n+1} is some function of y_{n+1}

i.e. $y_{n+1} = G(y_{n+1})$

or $y_{n+1} - G(y_{n+1}) = 0 = F(y_{n+1})$

Recall Newton's method (iterative) and implement here

to obtain y_{n+1}

i.e. $y_{n+1}^{(k+1)} = y_{n+1}^{(k)} - \frac{F(y_{n+1}^{(k)})}{F'(y_{n+1}^{(k)})}$

Example: Let us recall our some example

$\frac{dT}{dt} = -\alpha (T^4 - T_a^4)$; $T_0 = 2500 \text{ K}$
 $\alpha = 4 \times 10^{-12}$
 $T_a = 250 \text{ K}$

⇒ This IV-ODE is non-linear in T .

The modified Euler's implicit scheme gives

$T_{n+1} = T_n + \frac{\Delta t}{2} [f_n + f_{n+1}]$

$f = -4 \times 10^{-12} (T^4 - 250^4)$

⇒ Using $\Delta t = 2.0$ seconds,

$T_1 = T_0 + \frac{2}{2} [-4 \times 10^{-12} (2500^4 - 250^4 + T_1^4 - 250^4)]$

(4)

$$\text{i.e. } T_1 = 2500 - 4 \times 10^{-12} \left(3.90546875 \times 10^{-13} + T_1^4 \right)$$

$$\text{i.e. } T_1 = G(T_1)$$

$$\text{, where } G(T_1) = 2500 - \cancel{4 \times 10^{-12}} 156.21875 - 4 \times 10^{-12} T_1^4$$

$$\text{and } F(T_1) = \cancel{T_1 - 2500} T_1 - 2343.78125 + 4 \times 10^{-12} T_1^4$$

$$F'(T_1) = 1 - 1.6 \times 10^{-11} T_1^3$$

\therefore Start with initial guess for $T_1 = 2500$ same as T_0 .

$$T_1^{(1)} = T_1^{(0)} - \frac{F(T_1^{(0)})}{F'(T_1^{(0)})}$$

$$= 2500 - \frac{312.46875}{0.75}$$

$$= 2083.375 \text{ K}$$

$$F(T_1^{(0)}) = 312.46875$$

$$F'(T_1^{(0)}) =$$

$$F(T_1^{(1)}) = -185.048$$

$$F'(T_1^{(1)}) = 0.855315$$

$$T_1^{(2)} = T_1^{(1)} - \frac{F(T_1^{(1)})}{F'(T_1^{(1)})} = 2083.375 - \frac{-185.048}{0.855315} = 2299.725602$$

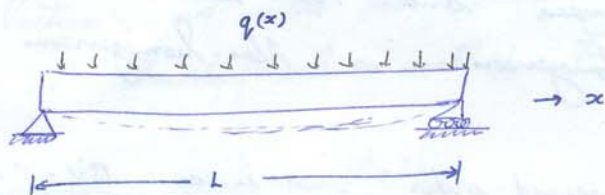
Similarly continue the iterations till convergence for each

time step.

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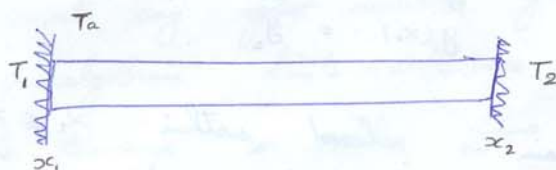
BOUNDARY - VALUE DIFFERENTIAL EQUATIONS

As a civil engineer, most of you might have studied the deflection of a beam



$$EI(x) \frac{d^4 y}{dx^4} = q(x) \quad ; \quad \begin{aligned} y(0) &= 0 \\ y(L) &= 0 \\ y''(0) &= 0 \\ y''(L) &= 0 \end{aligned}$$

⇒ The heat diffusion in a steel rod



$$\frac{d^2 T}{dx^2} - \alpha^2 T = -\alpha^2 T_a \quad ;$$

$$\begin{aligned} T(x_1) &= T_1 \\ T(x_2) &= T_2 \end{aligned}$$

⇒ These are boundary - value differential equations.
 ⇒ Boundary - value ODE's govern equilibrium problems.
 → Applied for closed domains.

⑥

In engineering and science, the boundary-value problems

- can be of single dependent variable
- coupled systems of several dependent variables
- linear and Non-linear
- Homogeneous or Non-homogeneous

Consider the second-order non-linear BV-ODE

$$\frac{d^2 y}{dx^2} + P(x, y) \frac{dy}{dx} + Q(x, y)y = F(x);$$

$$y(x_1) = y_1$$

$$y(x_2) = y_2$$

Second-order linear BV-ODE

$$\frac{d^2 y}{dx^2} + P \frac{dy}{dx} + Q y = F(x);$$

$$y(x_1) = y_1$$

$$y(x_2) = y_2$$

→ The solution domain is closed within $x_1 \leq x \leq x_2$.

Q: What are the types of boundary conditions for BV-ODE?

S: You need to specify certain conditions at the boundaries of the closed domain

- (i) The ^{value of the} dependent variable $y(x)$ specified at boundaries (Dirichlet)
- (ii) The derivative of the dependent variable specified (Neuman BC)

(7)

(iii) Combination of $y(x)$ and $\frac{dy}{dx}$ specified at the boundaries (Mixed BC's).

In our lecture, we will be discussing on the equilibrium or boundary-value method to solve the BV-ODE.

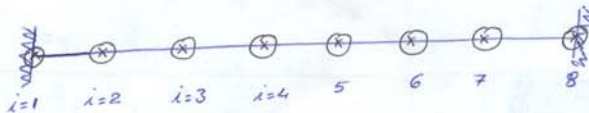
The Boundary-Value Method

- The finite-difference approach here consists of
- Discretise the continuous (spatial) domain into discrete finite-difference grid points
 - Approximate exact derivatives in the BV-ODE by finite-difference formulas
 - Substitute these formulas in the original BV-ODE at any grid arbitrary grid-point to obtain algebraic finite-difference equations.
 - Rearrange or solve these finite-difference equations.

Consider the second-order linear BV-ODE

$$\frac{d^2y}{dx^2} + P(x) \frac{dy}{dx} + Q(x)y = F(x)$$

$y(x_1) = y_1$ and $y(x_2) = y_2$



Discretising the continuous domain

* As this is one-dimensional, the domain in x -direction

⑧

is discretised into definite node points (In the figure 8 node points).

* To substitute derivatives by finite-difference formulas:

At any general node point 'i', the ODE is:

$$\left. \frac{d^2 y}{dx^2} \right|_i + P(x_i) \left. \frac{dy}{dx} \right|_i + Q(x_i) y_i = F(x_i)$$

$$\left. \frac{d^2 y}{dx^2} \right|_i \approx \frac{y_{i+1} - 2y_i + y_{i-1}}{\Delta x^2} + O(\Delta x^2)$$

$$\left. \frac{dy}{dx} \right|_i = \frac{y_{i+1} - y_{i-1}}{2\Delta x} + O(\Delta x^2)$$

* Substitute in the ODE:

$$\frac{y_{i+1} - 2y_i + y_{i-1}}{\Delta x^2} + P_i \frac{y_{i+1} - y_{i-1}}{2\Delta x} + Q_i y_i = F_i$$

* Rearrange the term:

$$y_{i-1} \left(\frac{1}{\Delta x^2} - \frac{P_i}{2\Delta x} \right) + y_i \left(-\frac{2}{\Delta x^2} + Q_i \right) + \left(\frac{1}{\Delta x^2} + \frac{P_i}{2\Delta x} \right) y_{i+1} = F_i$$

$$\text{or } \left(1 - \frac{\Delta x}{2} P_i \right) y_{i-1} + (-2 + \Delta x^2 Q_i) y_i + \left(1 + \frac{\Delta x}{2} P_i \right) y_{i+1} = F_i \quad \rightarrow \textcircled{1}$$

* Apply this finite-difference equation ① in each grid point (or nodes).