

Conservation of Angular Momentum

In the last class, we discussed about the conservation of angular momentum principle.

Using RTT, the angular momentum principle was given as

$$\frac{D\vec{H}_O}{Dt} = \frac{d}{dt} \iiint_{cv} (\vec{r} \times \vec{v}) \rho dU + \iint_{cs} (\vec{r} \times \vec{v}) \rho (\vec{v}_r \cdot \hat{n}) dA$$

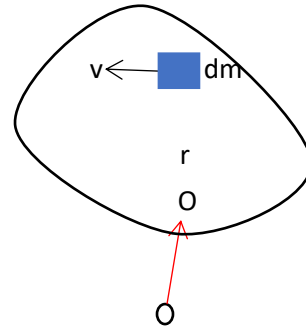
Where \vec{H}_O is the

$$\vec{H}_O = \iiint_{system} (\vec{r} \times \vec{v}) dm$$

the total angular momentum at any point O in the system

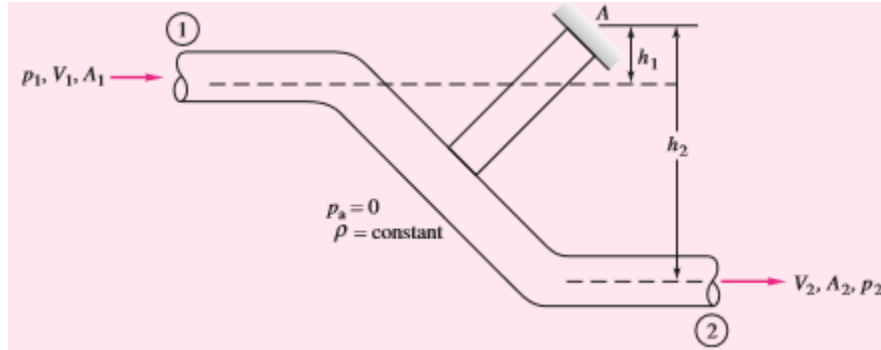
Also recall, $\frac{D\vec{H}_O}{Dt} = \sum M_O$, the net moment about the point O.

$$\sum M_O = \frac{D\vec{H}_O}{Dt} = \frac{d}{dt} \iiint_{cv} (\vec{r} \times \vec{v}) \rho du + \iint_{cs} (\vec{r} \times \vec{v}) \rho (\vec{v} \cdot \hat{n}) dA$$



Example: - (As adopted from FM White's Fluid Mechanics)

A pipe bend is supported at point A and connected to a flow system by flexible couplings at sections 1 and 2. The fluid is incompressible, and ambient pressure p_a is zero. (a) Find an expression for the torque T that must be resisted by the support at A, in terms of the flow properties at sections 1 and 2 and the distances h_1 and h_2 . (b) Compute this torque if $D_1 = D_2 = 8$ cm, $p_1 = 0.69 \times 10^6$ Pa gage, $p_2 = 0.55 \times 10^6$ Pa gage, $V_1 = 15$ m/s, $h_1 = 5$ cm, $h_2 = 25$ cm, and $\rho = 1000$ kg/m³.



(Source: Fluid Mechanics by F.M. White)

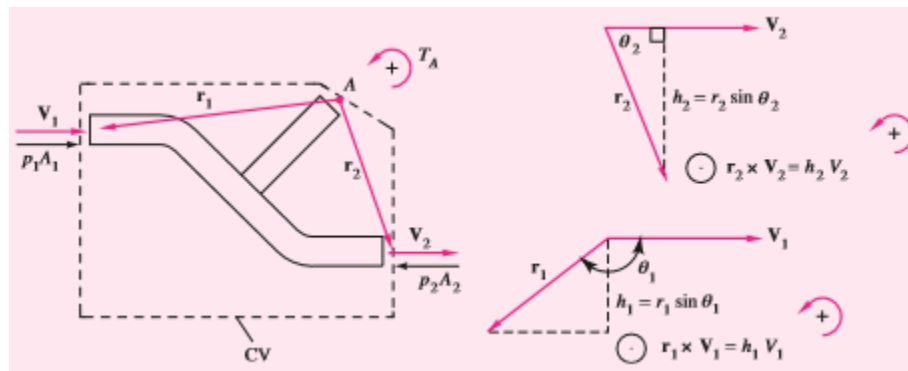
Solution :-

- a) The control volume chosen in Fig. above given cuts through sections 1 and 2 and through the support at A, where the torque T_A is desired.

The flexible couplings description specifies that there is no torque at either section 1 or 2, and so the cuts there expose no moments.

For the angular momentum terms $\vec{r} \times \vec{v}$, \vec{r} should be taken from point A to sections 1 and 2.

Note that the gage pressure forces $p_1 A_1$ and $p_2 A_2$ both have moments about A.



(Source: Fluid Mechanics by Frank M. White)

\vec{r}_1 = position vector to section 1.

\vec{r}_2 = position vector to section 2.

$$\Sigma M_A = T_A + \vec{r}_1 \times (-p_1 A_1 \hat{n}_1) + \vec{r}_2 \times (-p_2 A_2 \hat{n}_2)$$

In RTT :

$$T_A + \vec{r}_1 \times (p_1 A_1 \hat{n}_1) + \vec{r}_2 \times (-p_2 A_2 \hat{n}_2) = (\vec{r}_1 \times \vec{V}_1)(+ \dot{m}_{out}) - (\vec{r}_2 \times \vec{V}_2)(- \dot{m}_{in})$$

Figure 2 shows that all the cross products are associated with either $r_1 \sin \theta_1 = h_1$ or $r_2 \sin \theta_2 = h_2$, the perpendicular distances from point A to the pipe axes at 1 and 2.

$$\text{Therefore, } \Sigma M_A = T_A + p_1 A_1 h_1 - p_2 A_2 h_2$$

Remember that from the steady flow continuity relation. In terms of counterclockwise moments, Eq. (1) then becomes

$$T_A + p_1 A_1 h_1 - p_2 A_2 h_2 = \dot{m} [h_2 V_2 - h_1 V_1]$$

$$\text{or } T_A = -p_1 A_1 h_1 + p_2 A_2 h_2 + \dot{m} [h_2 V_2 - h_1 V_1]$$

$$\text{i.e. } T_A = h_2 (p_2 A_2 + \dot{m} V_2) - h_1 (p_1 A_1 + \dot{m} V_1)$$

The counterclockwise momentum or torque about A is expressed above.

The quantities p_1 and p_2 are gage pressures. Note that this result is independent of the shape of the pipe bend and varies only with the properties at sections 1 and 2 and the distances h_1 and h_2 .

b) $D_1 = D_2 = 8 \text{ cm,}$

$p_1 = 0.69 \times 10^6 \text{ Pa gage,}$

$p_2 = 0.55 \times 10^6 \text{ Pa gage,}$

$V_1 = 15 \text{ m/s,}$

$h_1 = 5 \text{ cm,}$

$h_2 = 25 \text{ cm and}$

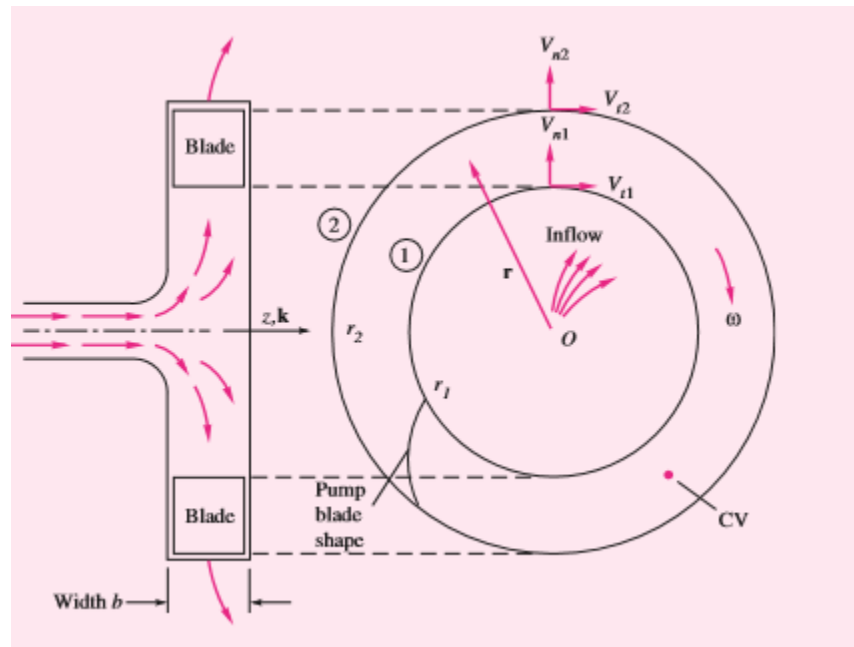
$\rho = 1000 \text{ kg/m}^3$

$$T_A = 0.25 \times (.055 \times 10^6 \times (3.14/4) \times (0.08)^2 + \dot{m} V_2) - (0.05) \times (0.69 \times 10^6 \times 3.14/4 \times (0.08)^2 + \dot{m} \times 15)$$

Work it out and complete yourself.

Example: - (As adopted from FM White's Fluid Mechanics)

Figure below shows a schematic of a centrifugal pump. The fluid enters axially and passes through the pump blades, which rotate at angular velocity ω ; the velocity of the fluid is changed from V_1 to V_2 and its pressure from p_1 to p_2 . (a) Find an expression for the torque T_o that must be applied to these blades to maintain this flow. (b) The power supplied to the pump would be $P = \omega * T_o$. To illustrate numerically, suppose $r_1 = 0.2$ m, $r_2 = 0.5$ m, and $b = 0.15$ m. Let the pump rotate at 600 r/min and deliver water at 2.5 m³/s with a density of 1000 kg/m³. Compute the torque and power supplied.



(Source: Fluid Mechanics by Frank M. White)

Solution:-

- a) The control volume is chosen to be the annular region between sections 1 and 2 where the flow passes through the pump blades. The flow is steady and assumed incompressible. The contribution of pressure to the torque about axis O is zero since the pressure forces at 1 and 2 act radially through O.

$$\sum M_o = T_o = (\vec{r}_2 \times \vec{v}_2)(+m^{\circ}_{out}) - (\vec{r}_1 \times \vec{v}_1)(m^{\circ}_{in})$$

where steady flow continuity tells us that

$$m^{\circ}_{in} = \rho v_{n1} 2\pi r_1 b = m^{\circ}_{out} = \rho v_{n2} 2\pi r_2 b = \rho Q$$

The cross product $\vec{r} \times \vec{v}$ is found to be clockwise about O at both sections:

$$r_2 \times v_2 = r_2 v_{t2} \sin 90^\circ \mathbf{k} = r_2 v_{t2} \mathbf{k} \quad \text{clockwise}$$

$$r_1 \times v_1 = r_1 v_{t1} k \quad \text{clockwise}$$

Above Equation thus becomes the desired formula for torque:

$$T_o = \rho Q (r_2 v_{t2} - r_1 v_{t1}) k \quad \text{clockwise}$$

This relation is called Eulers' turbine formula . In an idealized pump, the inlet and outlet tangential velocities would match the blade rotational speeds $V_{t1} = \omega r_1$ and $V_{t2} = \omega r_2$. Then the formula for torque supplied becomes

$$T_o = \rho Q \omega (r_2^2 - r_1^2) k \quad \text{clockwise}$$

- b) Convert ω to $600(2\pi/60) = 62.8$ rad/s. The normal velocities are not needed here but follow from the flow rate

$$V_{n1} = \frac{Q}{2\pi r_1 b}$$

$$V_{n2} = \frac{Q}{2\pi r_2 b}$$

For the idealized inlet and outlet, tangential velocity equals tip speed:

$$V_{t1} = \omega r_1 = (62.8 \text{ rad/s})(0.2 \text{ m}) = 12.6 \text{ m/s}$$

$$V_{t2} = \omega r_2 = 62.8(0.5) = 31.4 \text{ m/s}$$

Above Equation predicts the required torque to be

$$\begin{aligned} T_o &= (1000 \text{ kg/m}^3)(2.5 \text{ m}^3/\text{s})[(0.5 \text{ m})(31.4 \text{ m/s}) - (0.2 \text{ m})(12.6 \text{ m/s})] \\ &= 33000(\text{kg}\cdot\text{m}^2)/\text{s}^2 = 33000 \text{ Nm} \end{aligned}$$

The power required is

$$\begin{aligned} P &= \omega T_o = (62.8 \text{ rad/s})(33,000 \text{ N m}) = 2,070,000 \text{ (N m)/s} \\ &= 2.07 \text{ MW (2780 hp)} \end{aligned}$$

In actual practice the tangential velocities are considerably less than the impeller-tip speeds, and the design power requirements for this pump may be only 1 MW or less.