21/02/2017 LECTURE 18

Material Derivative (Contd.....)

Recall, in the last class, we started discussing about material derivative.

For any scalar, vectorial or tensorial quantity P_{ij}, the material derivative was given by:

$$\frac{DP_{ij\dots}(\vec{x},t)}{Dt} = \frac{\partial P_{ij\dots}(\vec{x},t)}{\partial t} + v_k \frac{\partial P_{ij\dots}(\vec{x},t)}{\partial x_k}$$

The first term indicates local rate change & second term indicates convective rate change.

✓ Also recall, the Lagrangian strain tensor & Eulerian Strain tensor.

-

- ✓ In a similar way, if the spatial gradient of velocity $\vec{v}(\vec{x},t)$ is taken, it will provide you velocity gradient tensor $\frac{\partial Vi}{\partial x_i}$
- ✓ Using tensor property : $2 + 1 \begin{bmatrix} 2 & 3 \\ 2 & 3 \end{bmatrix} = 1 \begin{bmatrix} 2 \\ 3 \end{bmatrix}$

$$\frac{\partial v_i}{\partial x_j} = \frac{1}{2} \left[\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right] + \frac{1}{2} \left[\frac{\partial v_i}{\partial x_j} - \frac{\partial v_j}{\partial x_i} \right]$$

1st part is symmetric tensor & 2nd part is anti-symmetric or skew symmetric tensor.

- ✓ The symmetric tensor is the rate of deformation tensor or it is the strain rate tensor.
- ✓ The skew symmetric tensor is called <u>Vorticity tensor or spin tensor</u>.
- \checkmark So, the velocity gradient term consist of strain rate & rotational rate.
- ✓ Later on you will see that, if the vorticity tensor is zero, the corresponding velocity flow field is irrotational.

Material Derivative of Volume:

Consider a fluid continuum to be in motion. In that fluid continuum, consider an elementary volume having initial configuration as such:



The elementary configuration's sides are $dX_1\hat{e}_1$, $dX\hat{e}_2$, $dX_3\hat{e}_3$. The box product is given the volume:

 $dU_0 = dX_1\hat{e}_1 \times dX_2\hat{e}_2.dX_3\hat{e}_3$

Volume is parallelepiped is $dU_0 = dX_1 dX_2 dX_3$

- ✓ As the fluid is moving, this parallelepiped is displaced & deformed. Let the deformed volume at time t = t be as given in the figure (for our convenience, we are right now assuming it to be parallelepiped).
- ✓ Unlike in the initial configuration, in the later configuration, the sides will be vectors having components in all three directions. The sides are: $d\vec{x}^{(1)}, d\vec{x}^{(2)}, d\vec{x}^{(3)}$

$$dx_{i} = \frac{\partial x_{i}}{\partial X_{j}} dX_{j}$$
$$dx_{i}^{(1)} = \frac{\partial x_{i}^{(1)}}{\partial X_{j}} dX_{j}$$
$$dx_{i}^{(2)} = \frac{\partial x_{i}^{(2)}}{\partial X_{j}} dX_{j}$$
$$dx_{i}^{(3)} = \frac{\partial x_{i}^{(3)}}{\partial X_{j}} dX_{j}$$

✓ The volume of the deformed parallelepiped will be $dU = d\vec{x}^{(1)} \times d\vec{x}^{(2)} d\vec{x}^{(3)}$ $= \varepsilon_{ijk} d\vec{x}^{(1)}_j d\vec{x}^{(2)}_k d\vec{x}^{(3)}_i$ [Box product]

As the original initially configured volume had edges dX_1 , dX_2 , dX_3 & there are particles associated with these edges, we assume in the distorted configuration the same particles occupy the edges $dx^{(1)}$, $dx^{(2)}$, $dx_i^{(3)}$ respectively.

If so, then,

$$dx_i^{(1)} = \frac{\partial x_i}{\partial X_1} dX_1$$
$$dx_i^{(2)} = \frac{\partial x_i}{\partial X_2} dX_2$$
$$dx_i^{(3)} = \frac{\partial x_i}{\partial X_3} dX_3$$

Therefore the distorted configured volume

$$dU = \varepsilon_{ijk} dx_i^{(1)} dx_j^{(2)} dx_k^{(3)}$$

$$dU = \varepsilon_{ijk} \frac{\partial x_i}{\partial X_1} \frac{\partial x_j}{\partial X_2} \frac{\partial x_k}{\partial X_3} dX_1 dX_2 dX_3$$

$$\varepsilon_{ijk} \frac{\partial x_i}{\partial X_1} \frac{\partial x_j}{\partial X_2} \frac{\partial x_k}{\partial X_3} = J = \left| \frac{\partial x_i}{\partial X_j} \right| \qquad \text{(The Jacobian)}$$

$$dU = J dU_0$$

Hence, the material derivative of the volume

$$\frac{D(dU)}{Dt} = \frac{D(JdU_0)}{Dt} = \frac{DJ}{Dt} dU_0$$

(You can easily guess that $\frac{D(dU_0)}{Dt} = 0$)

From further operations, it is proved that

 $\frac{DJ}{Dt} = \text{divergence of velocity vector} \times \text{Jacobian},$

i.e. $\frac{DJ}{Dt} = \frac{\partial v_p}{\partial x_p}$

$$\frac{D(dU)}{Dt} = J \frac{\partial v_p}{\partial x_p} dU_0$$

Therefore,

$$\frac{D(dU)}{Dt} = \frac{\partial v_p}{\partial x_p} dU$$

Material Derivative of property in a Volume:

You know that mass is a property associated with volume. If the density of the fluid is ρ then mass is $M = \int_{U} \rho dU$

i.e. You need to volumetrically integrate density to get mass.

Similarly, there may be several properties in a closed continuum (fluid), where these properties are obtained by volumetric integration.

Let us say that any property (scalar or Vector or Tensor) B_{ij} ... is obtained by volumetric integration.

i.e,
$$B_{ij\dots}(t) = \iiint_U \beta_{ij\dots}(\vec{x},t) dU$$

(Note: here we are not saying function of \vec{x} & t. We say only function of t. this is because volumetric integration done.

The material derivative of the property B_{ij} will be

$$\begin{split} \frac{DB_{ij\dots}(t)}{Dt} &= \frac{D}{Dt} [\iiint_{U} \beta_{ij\dots}(\vec{x},t) dU] \\ &= \iiint_{U} \frac{D}{Dt} (\beta_{ij\dots}(\vec{x},t) dU) \\ &= \iiint_{U} [\frac{D}{Dt} \beta_{ij\dots}(\vec{x},t) dU + \beta_{ij\dots}(\vec{x},t) \frac{D}{Dt} (dU)] \\ &= \iiint_{U} [\frac{\partial}{\partial t} \beta_{ij\dots}(\vec{x},t) + v_{p} \frac{\partial}{\partial x_{p}} \beta_{ij\dots}(\vec{x},t)] dU + \iiint_{U} \beta_{ij\dots}(\vec{x},t) \frac{\partial v_{p}}{\partial x_{p}} dU \\ &= \iiint_{U} [\frac{\partial}{\partial t} \beta_{ij\dots}(\vec{x},t) + v_{p} \frac{\partial}{\partial x_{p}} \beta_{ij\dots}(\vec{x},t) + \beta_{ij\dots}(\vec{x},t) \frac{\partial v_{p}}{\partial x_{p}}] dU \\ &= \iiint_{U} [\frac{\partial}{\partial t} \beta_{ij\dots}(\vec{x},t) + \frac{\partial}{\partial x_{p}} (v_{p} \beta_{ij\dots}(\vec{x},t))] dU \end{split}$$

Applying Gauss Divergence theorem on the second portion of the volumetric integral, you get,

$$\frac{DB_{ij\dots}(t)}{Dt} = \iiint_{U} \left[\frac{\partial}{\partial t}\beta_{ij\dots}(\vec{x},t)\right] dU + \iint_{A} v_{p} n_{p} \beta_{ij\dots}(\vec{x},t) dA$$

This equation is very similar to the Reynold's Transport theorem expression you had studied.

Acknowledgement:

The concept of deriving **material derivative of volume** is referred from the following text:

George E. Mase (1970). "Continuum Mechanics". Schaum's Outline Series.