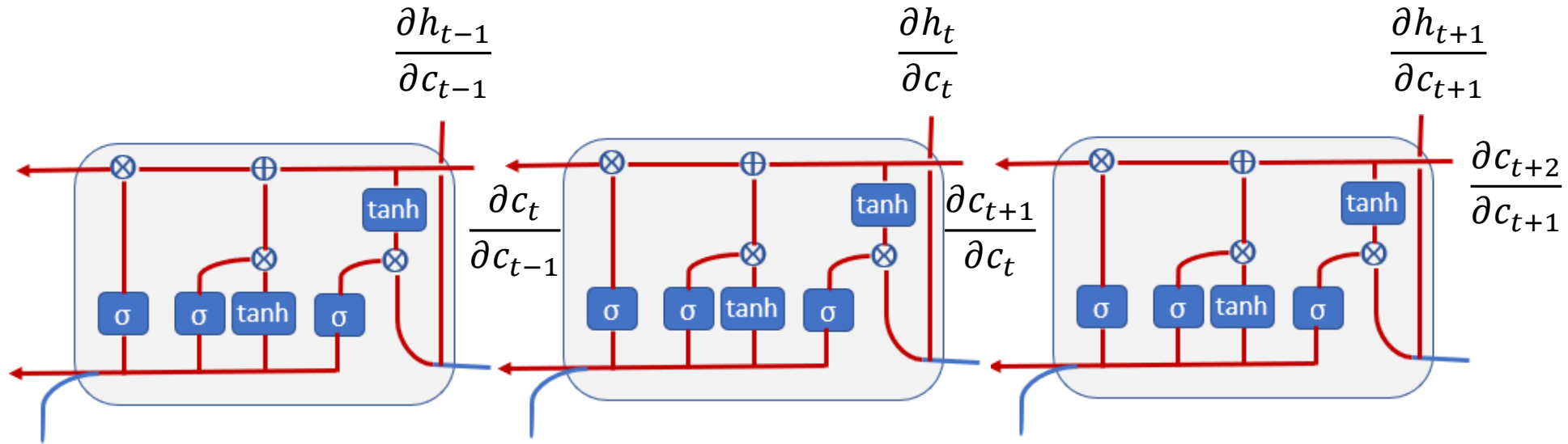


# Backpropagation in LSTM

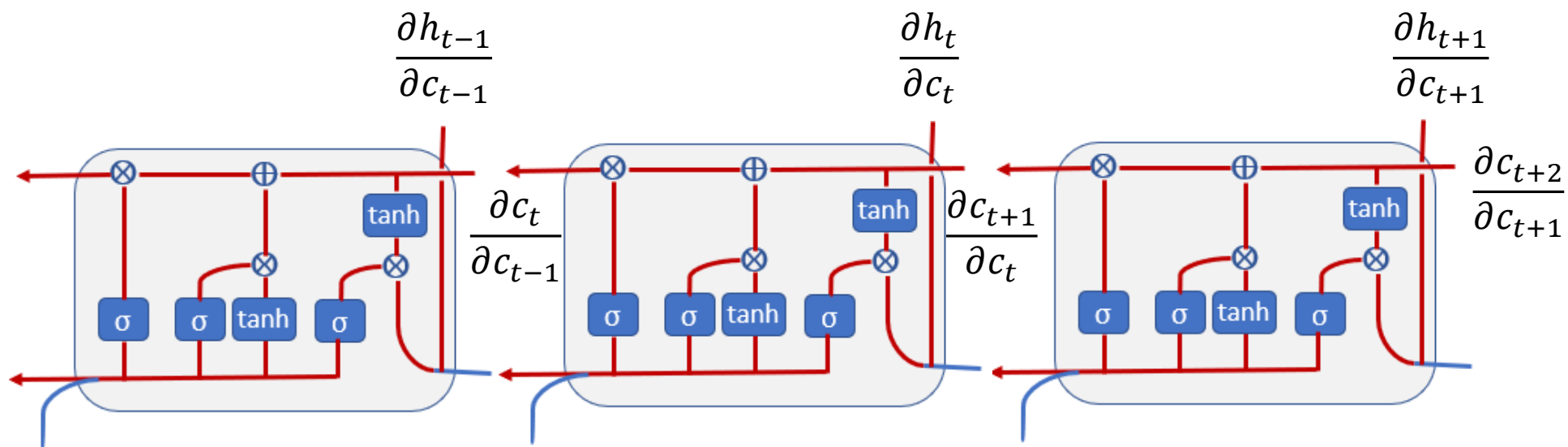


$$Z_t = \begin{bmatrix} \tilde{c}_t \\ f_t \\ i_t \\ o_t \end{bmatrix} = \begin{bmatrix} W_c & U_c \\ W_f & U_f \\ W_i & U_i \\ W_o & U_o \end{bmatrix} \cdot \begin{bmatrix} x_t \\ h_{t-1} \end{bmatrix} + \begin{bmatrix} b_c \\ b_f \\ b_i \\ b_o \end{bmatrix} = W \cdot I_t + b$$

# Topics

- Bias
- RNN Architecture
- RNN Forward Pass
- RNN Backpropagation
- LSTM Architecture
- LSTM Forward Pass
- GRU Architecture
- LSTM Back propagation

# Backpropagation in LSTM



$$\frac{\partial E}{\partial W} = \sum_{t=1}^T \frac{\partial E_t}{\partial W}$$

$$\frac{\partial E_t}{\partial W} = \frac{\partial E}{\partial h_t} \frac{\partial h_t}{\partial c_t} \frac{\partial c_t}{\partial c_{t-1}} \cdots \frac{\partial c_2}{\partial c_1} \frac{\partial c_1}{\partial W} = \frac{\partial E}{\partial h_t} \frac{\partial h_t}{\partial c_t} \left( \prod_{t=2}^T \frac{\partial c_t}{\partial c_{t-1}} \right) \frac{\partial c_1}{\partial W}$$

# Backpropagation in LSTM

$$c_t = c_{t-1} \otimes f_t \oplus i_t \otimes \tilde{c}_t$$

$$\begin{aligned} \frac{\partial c_t}{\partial c_{t-1}} &= \frac{\partial}{\partial c_{t-1}} (c_{t-1} \otimes f_t \oplus i_t \otimes \tilde{c}_t) \\ &= \frac{\partial}{\partial c_{t-1}} [c_{t-1} \otimes f_t] \oplus [i_t \otimes \tilde{c}_t] \\ &= \frac{\partial c_{t-1}}{\partial c_{t-1}} f_t + \frac{\partial f_t}{\partial c_{t-1}} c_{t-1} + \frac{\partial \tilde{c}_t}{\partial c_{t-1}} i_t + \frac{\partial i_t}{\partial c_{t-1}} \tilde{c}_t \\ &= f_t + \frac{\partial f_t}{\partial c_{t-1}} c_{t-1} + \frac{\partial \tilde{c}_t}{\partial c_{t-1}} i_t + \frac{\partial i_t}{\partial c_{t-1}} \tilde{c}_t \end{aligned}$$

# Backpropagation in LSTM

$$c_t = c_{t-1} \otimes f_t \oplus i_t \otimes \tilde{c}_t$$

$$\begin{aligned} \frac{\partial c_t}{\partial c_{t-1}} &= \frac{\partial}{\partial c_{t-1}} (c_{t-1} \otimes f_t \oplus i_t \otimes \tilde{c}_t) \\ &= \frac{\partial}{\partial c_{t-1}} [c_{t-1} \otimes f_t] \oplus [i_t \otimes \tilde{c}_t] \\ &= \frac{\partial c_{t-1}}{\partial c_{t-1}} f_t + \frac{\partial f_t}{\partial c_{t-1}} c_{t-1} + \frac{\partial \tilde{c}_t}{\partial c_{t-1}} i_t + \frac{\partial i_t}{\partial c_{t-1}} \tilde{c}_t \\ &= \underset{p}{f_t} + \underset{q}{\frac{\partial f_t}{\partial c_{t-1}} c_{t-1}} + \underset{r}{\frac{\partial \tilde{c}_t}{\partial c_{t-1}} i_t} + \underset{s}{\frac{\partial i_t}{\partial c_{t-1}} \tilde{c}_t} \end{aligned}$$

$$f_t = \sigma(W_f \cdot x_t + U_f \cdot h_{t-1} + b_f)$$

$$i_t = \sigma(W_i \cdot x_t + U_i \cdot h_{t-1} + b_i)$$

$$\tilde{c}_t = \tanh(W_c \cdot x_t + U_c \cdot h_{t-1} + b_c)$$

$$h_t = \tanh(c_t) \otimes o_t$$

$$\frac{\partial E_t}{\partial W} = \frac{\partial E}{\partial h_t} \frac{\partial h_t}{\partial c_t} \left( \prod_{t=2}^T (p + q + r + s) \right) \frac{\partial c_1}{\partial W}$$