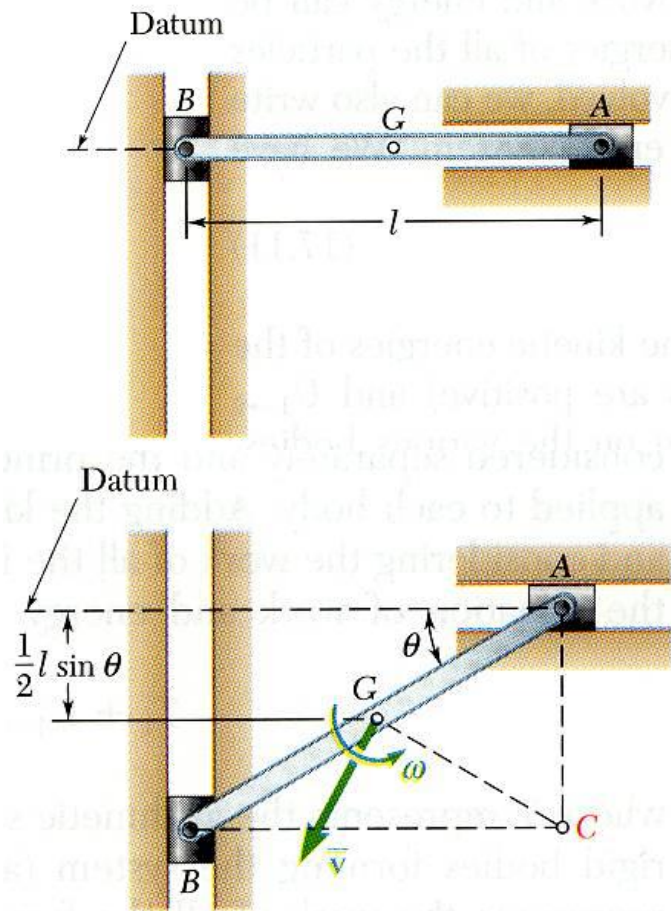


# Vector Mechanics for Engineers: Dynamics

## Conservation of Energy



- Expressing the work of conservative forces as a change in potential energy, the principle of work and energy becomes

$$T_1 + V_1 = T_2 + V_2$$

- Consider the slender rod of mass  $m$ .

$$T_1 = 0, \quad V_1 = 0$$

$$T_2 = \frac{1}{2} m \bar{v}_2^2 + \frac{1}{2} \bar{I} \omega_2^2$$

$$= \frac{1}{2} m \left( \frac{1}{2} l \omega \right)^2 + \frac{1}{2} \left( \frac{1}{12} m l^2 \right) \omega^2 = \frac{1}{2} \frac{m l^2}{3} \omega^2$$

$$V_2 = -\frac{1}{2} W l \sin \theta = -\frac{1}{2} m g l \sin \theta$$

$$T_1 + V_1 = T_2 + V_2$$

$$0 = \frac{1}{2} \frac{m l^2}{3} \omega^2 - \frac{1}{2} m g l \sin \theta$$

$$\omega = \left( \frac{3g}{l} \sin \theta \right)$$

- mass  $m$
- released with zero velocity
- determine  $\omega$  at  $\theta$

# Vector Mechanics for Engineers: Dynamics

## Power

- Power = rate at which work is done
- For a body acted upon by force  $\vec{F}$  and moving with velocity  $\vec{v}$ ,

$$\text{Power} = \frac{dU}{dt} = \vec{F} \cdot \vec{v}$$

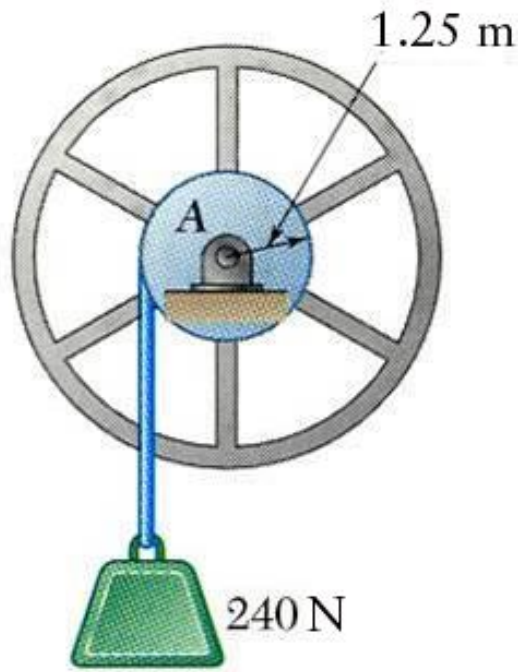
- For a rigid body rotating with an angular velocity  $\vec{\omega}$  and acted upon by a couple of moment  $\vec{M}$  parallel to the axis of rotation,

$$\text{Power} = \frac{dU}{dt} = \frac{M d\theta}{dt} = M\omega$$



# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.1



For the drum and flywheel,  $\bar{I} = 10.5 \text{ kgm}^2$   
 The bearing friction is equivalent to a couple of  $60 \text{ N} \cdot \text{m}$ . At the instant shown, the block is moving downward at  $6 \text{ m/s}$ .

Determine the velocity of the block after it has moved 4 m downward.

### SOLUTION:

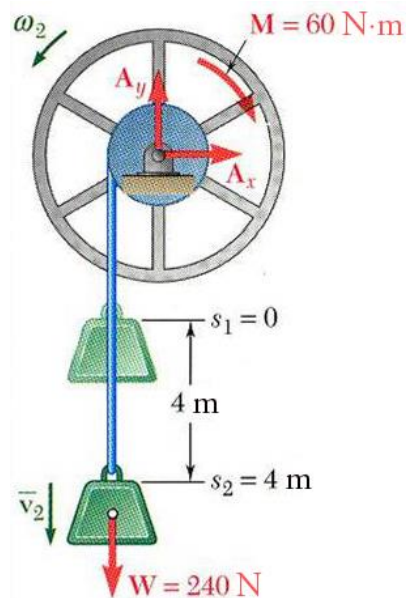
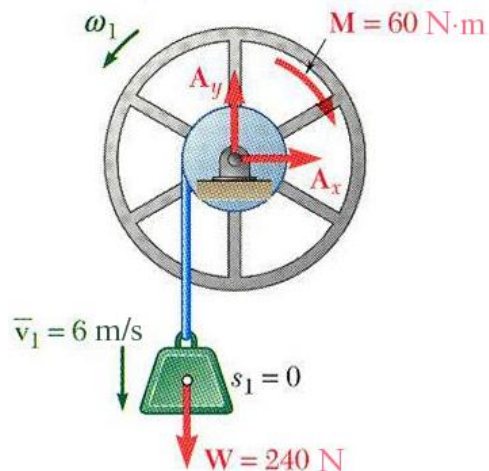
- Consider the system of the flywheel and block. The work done by the internal forces exerted by the cable cancels.
- Note that the velocity of the block and the angular velocity of the drum and flywheel are related by

$$\bar{v} = r\omega$$

- Apply the principle of work and kinetic energy to develop an expression for the final velocity.

# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.1



### SOLUTION:

- Consider the system of the flywheel and block. The work done by the internal forces exerted by the cable cancels.
- Note that the velocity of the block and the angular velocity of the drum and flywheel are related by

$$\bar{v} = r\omega \quad \omega_1 = \frac{\bar{v}_1}{r} = \frac{6 \text{ m/s}}{1.25 \text{ m}} = 4.80 \text{ rad/s} \quad \omega_2 = \frac{\bar{v}_2}{r} = \frac{\bar{v}_2}{1.25}$$

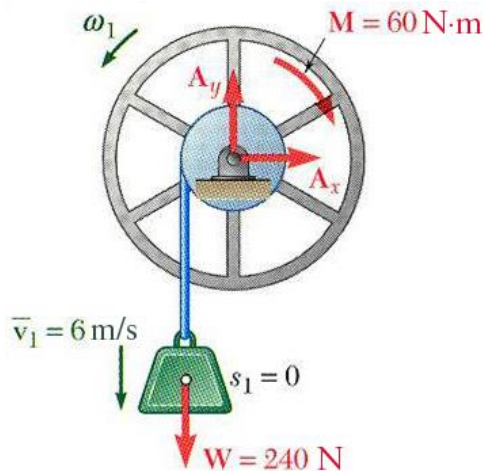
- Apply the principle of work and kinetic energy to develop an expression for the final velocity.

$$\begin{aligned} T_1 &= \frac{1}{2}mv_1^2 + \frac{1}{2}\bar{I}\omega_1^2 \\ &= \frac{1}{2} \frac{240 \text{ N}}{10 \text{ m/s}^2} (6 \text{ m/s})^2 + \frac{1}{2} (10.5 \text{ kgm}^2) (4.80 \text{ rad/s})^2 \\ &= 552.96 \text{ N}\cdot\text{m} \end{aligned}$$

$$\begin{aligned} T_2 &= \frac{1}{2}m\bar{v}_2^2 + \frac{1}{2}\bar{I}\omega_2^2 \\ &= \frac{1}{2} \frac{240}{10} \bar{v}_2^2 + \frac{1}{2} 10.5 \left( \frac{v_2}{1.25} \right)^2 = 15.36 v_2^2 \end{aligned}$$

# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.1



$$T_1 = \frac{1}{2}mv_1^2 + \frac{1}{2}\bar{I}\omega_1^2 = 552.96 \text{ N} \cdot \text{m}$$

$$T_2 = \frac{1}{2}m\bar{v}_2^2 + \frac{1}{2}\bar{I}\omega_2^2 = 15.36v_2^2$$

- Note that the block displacement and pulley rotation are related by

$$\theta_2 = \frac{s_2}{r} = \frac{4 \text{ m}}{1.25 \text{ m}} = 3.20 \text{ rad}$$

Then,

$$\begin{aligned} U_{1 \rightarrow 2} &= W(s_2 - s_1) - M(\theta_2 - \theta_1) \\ &= (240 \text{ N})(4 \text{ m}) - (60 \text{ N} \cdot \text{m})(3.20 \text{ rad}) \\ &= 768 \text{ N} \cdot \text{m} \end{aligned}$$

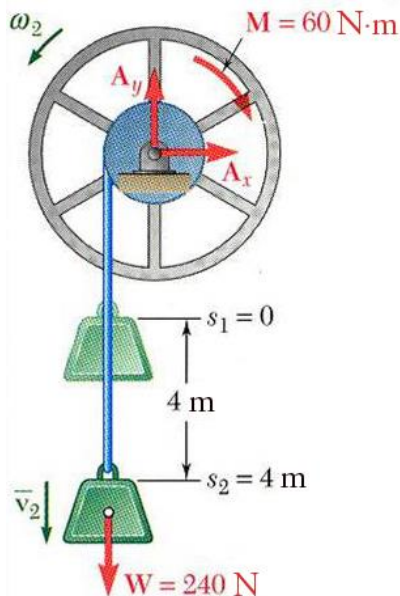
- Principle of work and energy:

$$T_1 + U_{1 \rightarrow 2} = T_2$$

$$552.96 \text{ N} \cdot \text{m} + 768 \text{ N} \cdot \text{m} = 15.36\bar{v}_2^2$$

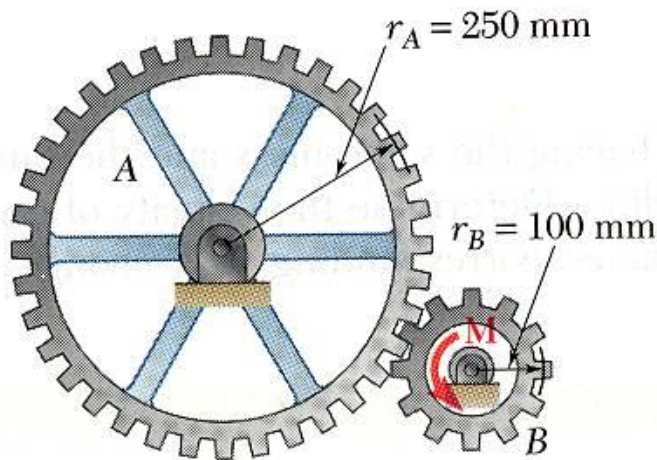
$$\bar{v}_2 = 9.27 \text{ m/s}$$

$$\bar{v}_2 = 9.27 \text{ m/s} \downarrow$$



# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.2



$$\begin{aligned} m_A &= 10 \text{ kg} & \bar{k}_A &= 200 \text{ mm} \\ m_B &= 3 \text{ kg} & \bar{k}_B &= 80 \text{ mm} \end{aligned}$$

The system is at rest when a moment of  $M = 6 \text{ N} \cdot \text{m}$  is applied to gear  $B$ .

Neglecting friction, *a*) determine the number of revolutions of gear  $B$  before its angular velocity reaches 600 rpm, and *b*) tangential force exerted by gear  $B$  on gear  $A$ .

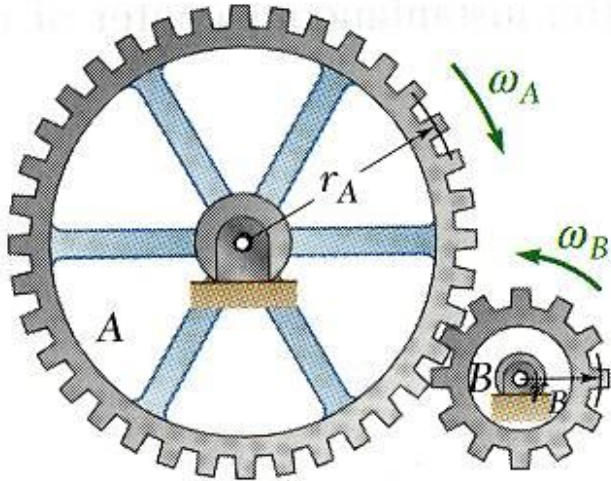
### SOLUTION:

- Consider a system consisting of the two gears. Noting that the gear rotational speeds are related, evaluate the final kinetic energy of the system.
- Apply the principle of work and energy. Calculate the number of revolutions required for the work of the applied moment to equal the final kinetic energy of the system.
- Apply the principle of work and energy to a system consisting of gear  $A$ . With the final kinetic energy and number of revolutions known, calculate the moment and tangential force required for the indicated work.



# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.2



### SOLUTION:

- Consider a system consisting of the two gears. Noting that the gear rotational speeds are related, evaluate the final kinetic energy of the system.

$$\omega_B = \frac{(600 \text{ rpm})(2\pi \text{ rad/rev})}{60 \text{ s/min}} = 62.8 \text{ rad/s}$$

$$\omega_A = \omega_B \frac{r_B}{r_A} = 62.8 \frac{0.100}{0.250} = 25.1 \text{ rad/s}$$

$$\bar{I}_A = m_A \bar{k}_A^2 = (10 \text{ kg})(0.200 \text{ m})^2 = 0.400 \text{ kg} \cdot \text{m}^2$$

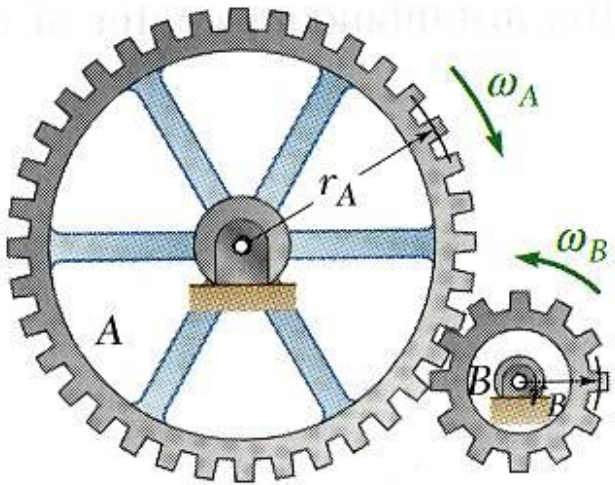
$$\bar{I}_B = m_B \bar{k}_B^2 = (3 \text{ kg})(0.080 \text{ m})^2 = 0.0192 \text{ kg} \cdot \text{m}^2$$

$$\begin{aligned} T_2 &= \frac{1}{2} \bar{I}_A \omega_A^2 + \frac{1}{2} \bar{I}_B \omega_B^2 \\ &= \frac{1}{2} (0.400) (25.1)^2 + \frac{1}{2} (0.0192) (62.8)^2 \\ &= 163.9 \text{ J} \end{aligned}$$



# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.2



- Apply the principle of work and energy. Calculate the number of revolutions required for the work.

$$T_1 + U_{1 \rightarrow 2} = T_2$$

$$0 + (6\theta_B)J = 163.9\text{J}$$

$$\theta_B = 27.32\text{rad}$$

$$\theta_B = \frac{27.32}{2\pi} = 4.35\text{rev}$$

- Apply the principle of work and energy to a system consisting of gear A. Calculate the moment and tangential force required for the indicated work.

$$\theta_A = \theta_B \frac{r_B}{r_A} = 27.32 \frac{0.100}{0.250} = 10.93\text{rad}$$

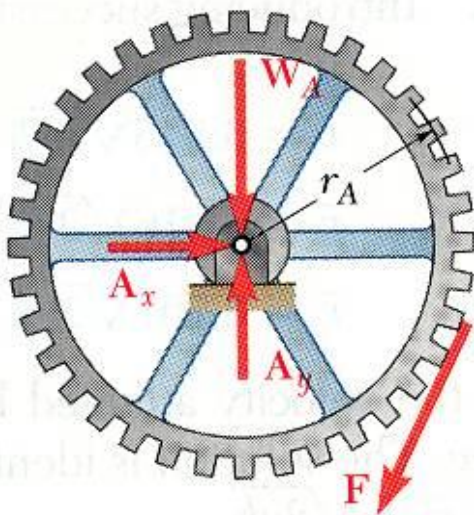
$$T_2 = \frac{1}{2} I_A \omega_A^2 = \frac{1}{2} (0.400) (25.1)^2 = 126.0\text{J}$$

$$T_1 + U_{1 \rightarrow 2} = T_2$$

$$0 + M_A (10.93\text{rad}) = 126.0\text{J}$$

$$M_A = r_A F = 11.52\text{N} \cdot \text{m}$$

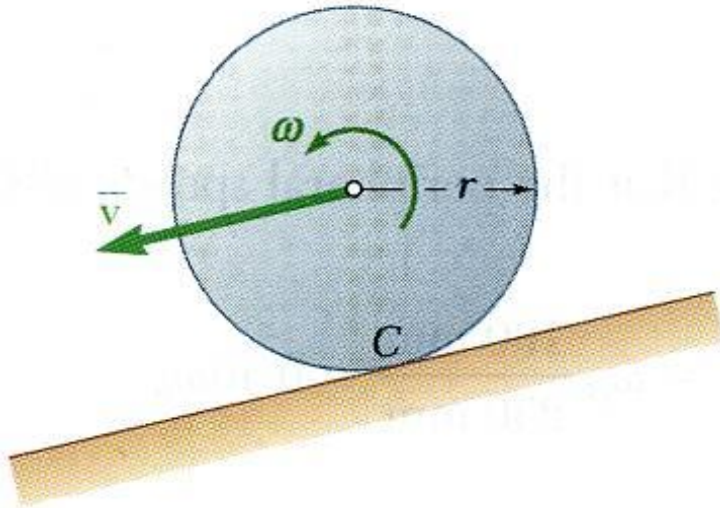
$$F = \frac{11.52}{0.250} = 46.2\text{N}$$





# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.3



A sphere, cylinder, and hoop, each having the same mass and radius, are released from rest on an incline.

Determine the velocity of each body after it has rolled through a distance corresponding to a change of elevation  $h$ .

### SOLUTION:

- The work done by the weight of the bodies is the same. From the principle of work and energy, it follows that each body will have the same kinetic energy after the change of elevation.
- Because each of the bodies has a different centroidal moment of inertia, the distribution of the total kinetic energy between the linear and rotational components will be different as well.

# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.3

### SOLUTION:

- The work done by the weight of the bodies is the same. From the principle of work and energy, it follows that each body will have the same kinetic energy after the change of elevation.

With  $\omega = \frac{\bar{v}}{r}$

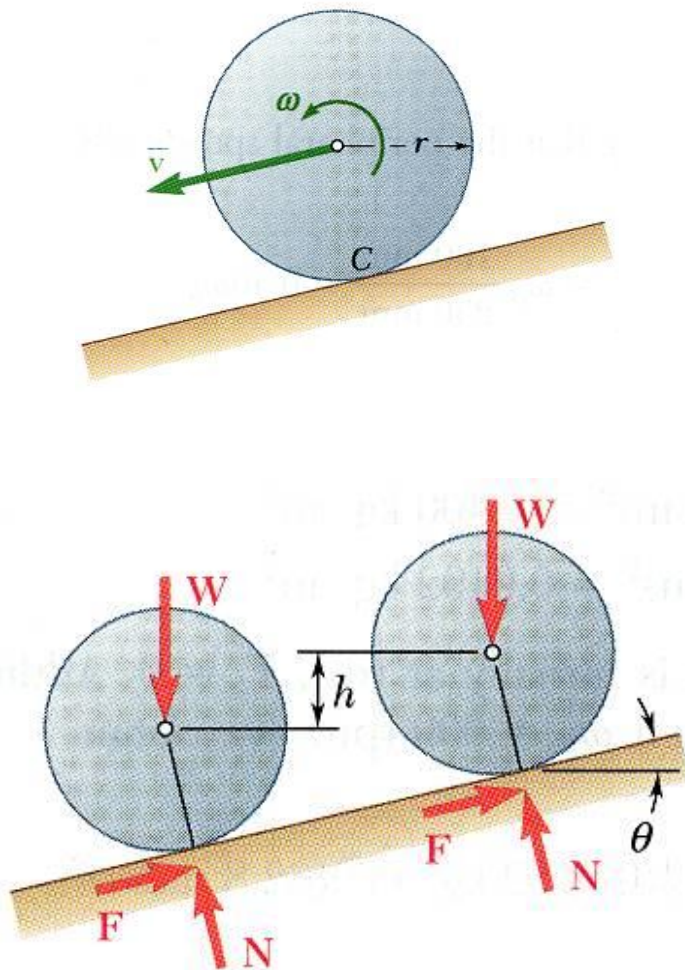
$$T_2 = \frac{1}{2}m\bar{v}^2 + \frac{1}{2}\bar{I}\omega^2 = \frac{1}{2}m\bar{v}^2 + \frac{1}{2}\bar{I}\left(\frac{\bar{v}}{r}\right)^2$$

$$= \frac{1}{2}\left(m + \frac{\bar{I}}{r^2}\right)\bar{v}^2$$

$$T_1 + U_{1 \rightarrow 2} = T_2$$

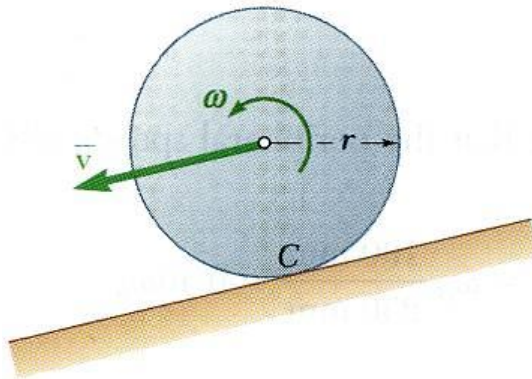
$$0 + Wh = \frac{1}{2}\left(m + \frac{\bar{I}}{r^2}\right)\bar{v}^2$$

$$\bar{v}^2 = \frac{2Wh}{m + \bar{I}/r^2} = \frac{2gh}{1 + \bar{I}/mr^2}$$



# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.3



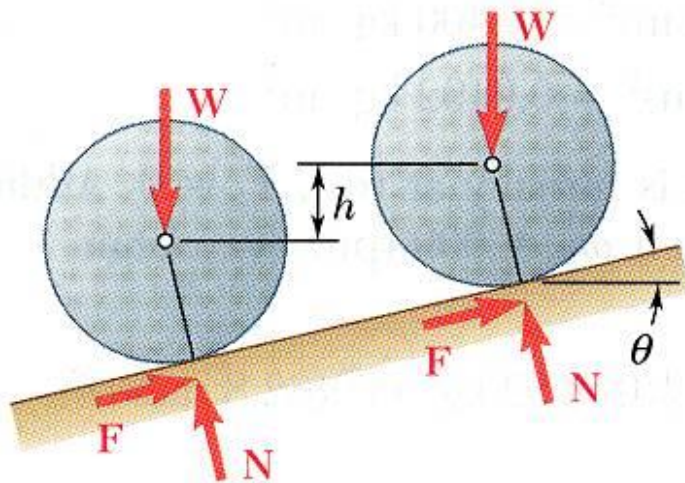
- Because each of the bodies has a different centroidal moment of inertia, the distribution of the total kinetic energy between the linear and rotational components will be different as well.

$$\bar{v}^2 = \frac{2gh}{1 + \bar{I}/mr^2}$$

$$\text{Sphere: } \bar{I} = \frac{2}{5}mr^2 \quad \bar{v} = 0.845\sqrt{2gh}$$

$$\text{Cylinder: } \bar{I} = \frac{1}{2}mr^2 \quad \bar{v} = 0.816\sqrt{2gh}$$

$$\text{Hoop: } \bar{I} = mr^2 \quad \bar{v} = 0.707\sqrt{2gh}$$



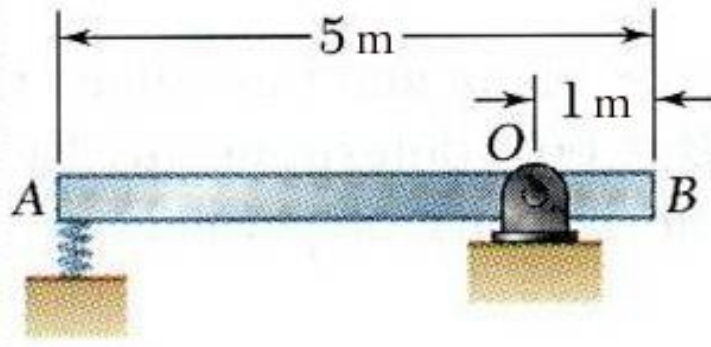
NOTE:

- For a frictionless block sliding through the same distance,  $\omega = 0$ ,  $\bar{v} = \sqrt{2gh}$
- The velocity of the body is independent of its mass and radius.
- The velocity of the body does depend on

$$\frac{\bar{I}}{mr^2} = \frac{\bar{k}^2}{r^2}$$

# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.4



A 30-N slender rod pivots about the point  $O$ . The other end is pressed against a spring ( $k = 1800 \text{ N/m}$ ) until the spring is compressed 30 cm and the rod is in a horizontal position.

If the rod is released from this position, determine its angular velocity and the reaction at the pivot as the rod passes through a vertical position.

### SOLUTION:

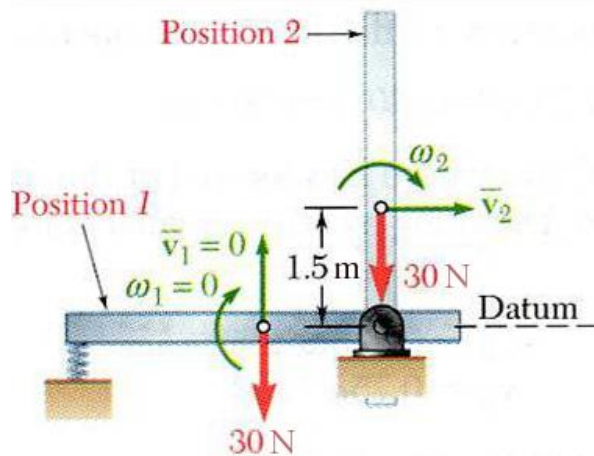
- The weight and spring forces are conservative. The principle of work and energy can be expressed as

$$T_1 + V_1 = T_2 + V_2$$

- Evaluate the initial and final potential energy.
- Express the final kinetic energy in terms of the final angular velocity of the rod.
- Based on the free-body-diagram equation, solve for the reactions at the pivot.

# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.4



### SOLUTION:

- The weight and spring forces are conservative. The principle of work and energy can be expressed as

$$T_1 + V_1 = T_2 + V_2$$

- Evaluate the initial and final potential energy.

$$\begin{aligned} V_1 &= V_g + V_e = 0 + \frac{1}{2} kx_1^2 = \frac{1}{2} (1800 \text{ N/m})(0.3 \text{ m})^2 \\ &= 81 \text{ N} \cdot \text{m} \end{aligned}$$

$$\begin{aligned} V_2 &= V_g + V_e = Wh + 0 = (30 \text{ N})(1.5 \text{ m}) \\ &= 45 \text{ N} \cdot \text{m} \end{aligned}$$

- Express the final kinetic energy in terms of the angular velocity of the rod.

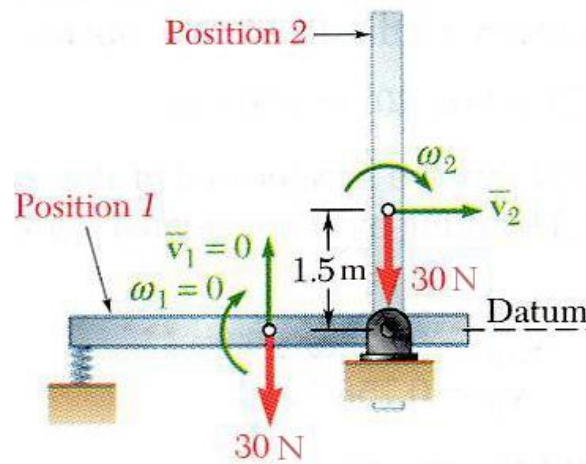
$$\begin{aligned} T_2 &= \frac{1}{2} m \bar{v}_2^2 + \frac{1}{2} \bar{I} \omega_2^2 = \frac{1}{2} m (r \omega_2)^2 + \frac{1}{2} \bar{I} \omega_2^2 \\ &= \frac{1}{2} \frac{30}{10} (1.5 \omega_2)^2 + \frac{1}{2} (6.25) \omega_2^2 = 5.375 \omega_2^2 \end{aligned}$$

$$\begin{aligned} \bar{I} &= \frac{1}{12} m l^2 \\ &= \frac{1}{12} \left( \frac{30 \text{ N}}{10 \text{ m/s}^2} \right) (5 \text{ m})^2 \\ &= 6.25 \text{ kgm}^2 \end{aligned}$$



# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.4



From the principle of work and energy,

$$T_1 + V_1 = T_2 + V_2$$

$$0 + 81 \text{ N} \cdot \text{m} = 5.375 \omega_2^2 + 45 \text{ N} \cdot \text{m}$$

$$\omega_2 = 2.58 \text{ rad/s}$$

Based on the free-body-diagram equation, solve for the reactions at the pivot.

$$\bar{a}_n = \bar{r} \omega_2^2 = (1.5 \text{ m})(2.58 \text{ rad/s})^2 = 9.98 \text{ m/s}^2 \quad \bar{a}_n = 9.98 \text{ m/s}^2 \downarrow$$

$$\bar{a}_t = r \alpha \rightarrow \quad \bar{a}_t = r \alpha \rightarrow$$

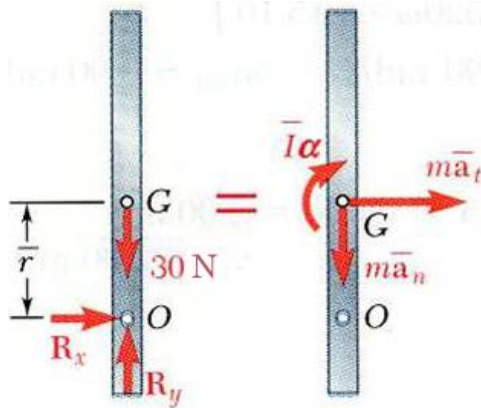
$$+\circlearrowleft \sum M_O = \sum (M_O)_{\text{eff}} \quad 0 = \bar{I} \alpha + m(\bar{r} \alpha) \bar{r} \quad \alpha = 0$$

$$+\rightarrow \sum F_x = \sum (F_x)_{\text{eff}} \quad R_x = m(\bar{r} \alpha) \quad R_x = 0$$

$$+\uparrow \sum F_y = \sum (F_y)_{\text{eff}} \quad R_y - 30 \text{ N} = -m a_n$$

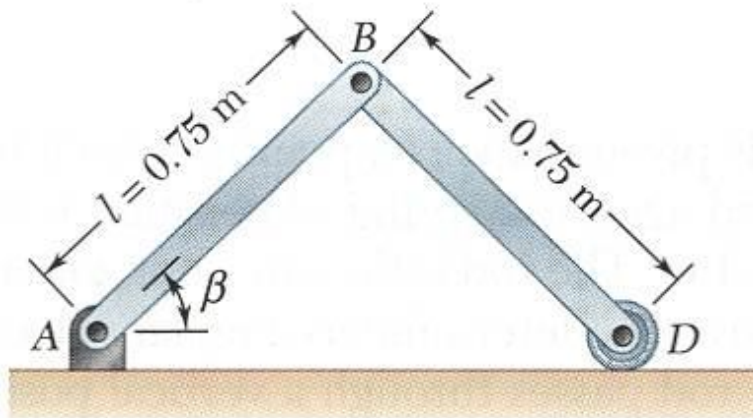
$$= -\frac{30 \text{ N}}{10 \text{ m/s}^2} (9.98 \text{ m/s}^2)$$

$$R_y = 29.9 \text{ N} \quad \bar{R} = 29.9 \text{ N} \uparrow$$



# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.5



Each of the two slender rods has a mass of 6 kg. The system is released from rest with  $\beta = 60^\circ$ .

Determine *a*) the angular velocity of rod *AB* when  $\beta = 20^\circ$ , and *b*) the velocity of the point *D* at the same instant.

### SOLUTION:

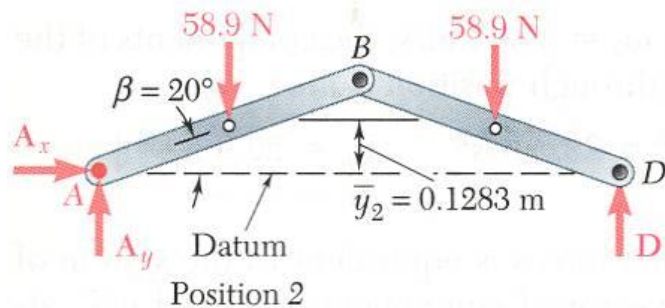
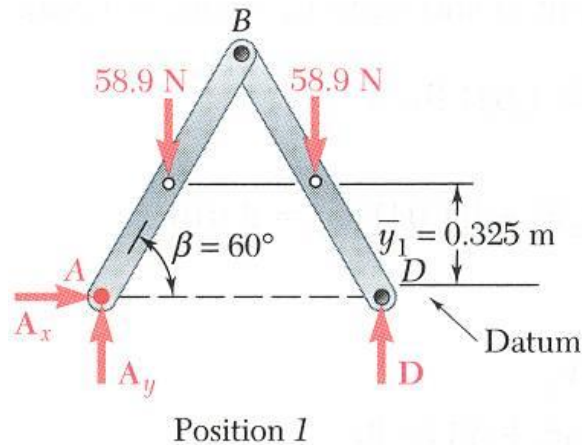
- Consider a system consisting of the two rods. With the conservative weight force,

$$T_1 + V_1 = T_2 + V_2$$

- Evaluate the initial and final potential energy.
- Express the final kinetic energy of the system in terms of the angular velocities of the rods.
- Solve the energy equation for the angular velocity, then evaluate the velocity of the point *D*.

# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.5



### SOLUTION:

- Consider a system consisting of the two rods. With the conservative weight force,

$$T_1 + V_1 = T_2 + V_2$$

- Evaluate the initial and final potential energy.

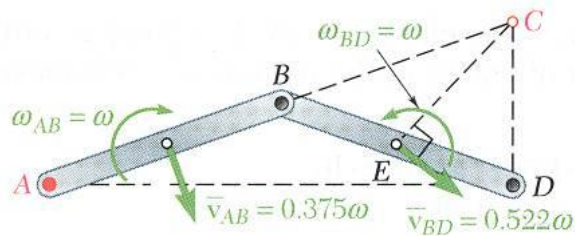
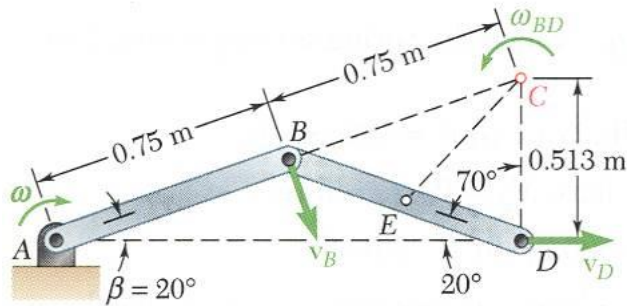
$$\begin{aligned} V_1 &= 2Wy_1 = 2(58.86\text{ N})(0.325\text{ m}) \\ &= 38.26\text{ J} \end{aligned}$$

$$\begin{aligned} V_2 &= 2Wy_2 = 2(58.86\text{ N})(0.1283\text{ m}) \\ &= 15.10\text{ J} \end{aligned}$$

$$\begin{aligned} W &= mg = (6\text{ kg})(9.81\text{ m/s}^2) \\ &= 58.86\text{ N} \end{aligned}$$

# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.5



- Express the final kinetic energy of the system in terms of the angular velocities of the rods.

$$\vec{v}_{AB} = (0.375 \text{ m})\omega \searrow$$

Since  $\vec{v}_B$  is perpendicular to  $AB$  and  $\vec{v}_D$  is horizontal, the instantaneous center of rotation for rod  $BD$  is  $C$ .

$$BC = 0.75 \text{ m} \quad CD = 2(0.75 \text{ m})\sin 20^\circ = 0.513 \text{ m}$$

and applying the law of cosines to  $CDE$ ,  $EC = 0.522 \text{ m}$

Consider the velocity of point  $B$

$$v_B = (AB)\omega = (BC)\omega_{AB} \quad \vec{\omega}_{BD} = \omega \curvearrowright$$

$$\vec{v}_{BD} = (0.522 \text{ m})\omega \searrow$$

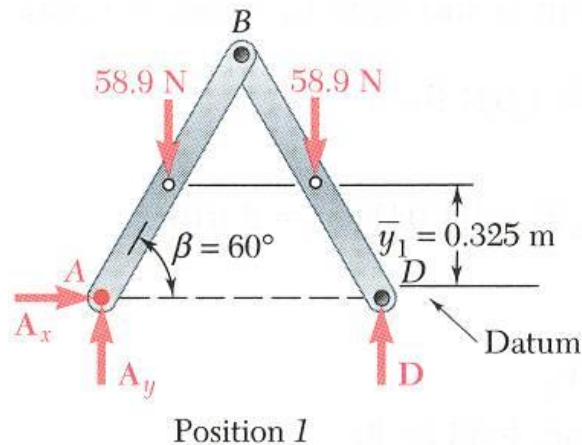
For the final kinetic energy,

$$\bar{I}_{AB} = \bar{I}_{BD} = \frac{1}{12}ml^2 = \frac{1}{12}(6 \text{ kg})(0.75 \text{ m})^2 = 0.281 \text{ kg} \cdot \text{m}^2$$

$$\begin{aligned} T_2 &= \frac{1}{12}m\bar{v}_{AB}^2 + \frac{1}{2}\bar{I}_{AB}\omega_{AB}^2 + \frac{1}{12}m\bar{v}_{BD}^2 + \frac{1}{2}\bar{I}_{BD}\omega_{BD}^2 \\ &= \frac{1}{12}(6)(0.375\omega)^2 + \frac{1}{2}(0.281)\omega^2 + \frac{1}{12}(6)(0.522\omega)^2 + \frac{1}{2}(0.281)\omega^2 \\ &= 1.520\omega^2 \end{aligned}$$

# Vector Mechanics for Engineers: Dynamics

## Sample Problem 17.5



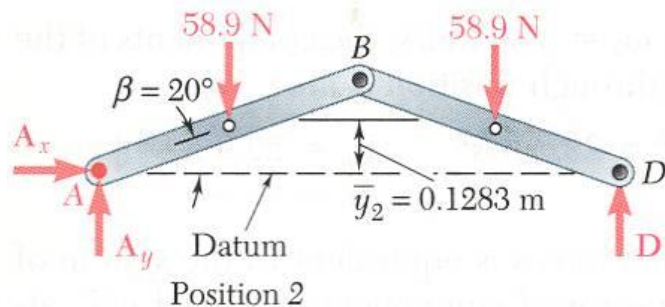
- Solve the energy equation for the angular velocity, then evaluate the velocity of the point  $D$ .

$$T_1 + V_1 = T_2 + V_2$$

$$0 + 38.26 \text{ J} = 1.520 \omega^2 + 15.10 \text{ J}$$

$$\omega = 3.90 \text{ rad/s}$$

$$\vec{\omega}_{AB} = 3.90 \text{ rad/s} \curvearrowright$$



$$\begin{aligned} v_D &= (CD)\omega \\ &= (0.513 \text{ m})(3.90 \text{ rad/s}) \\ &= 2.00 \text{ m/s} \end{aligned}$$

$$\vec{v}_D = 2.00 \text{ m/s} \rightarrow$$