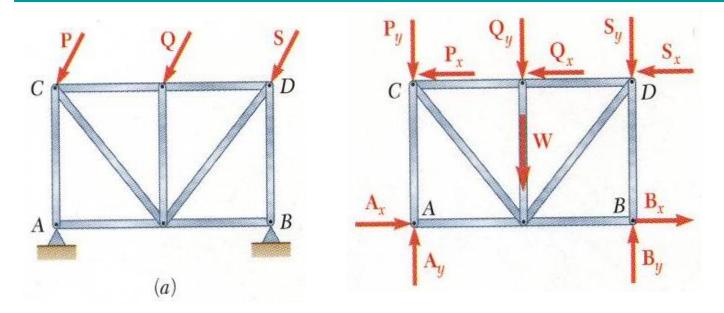
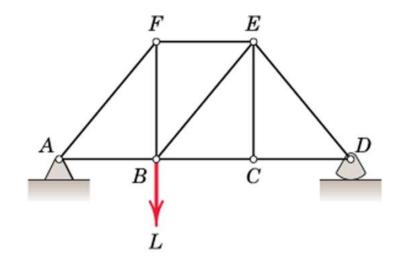
Statically Indeterminate Structure

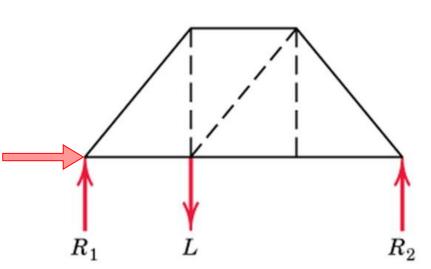


: More unknowns than equations: Statically Indeterminate

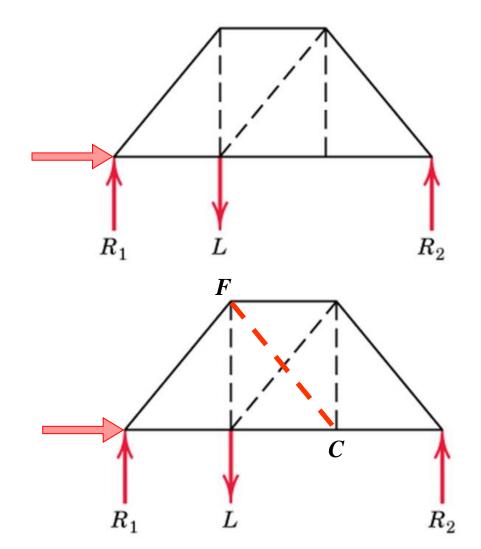


No. of unknown reactions = 3No. of equilibrium equations = 3

: Statically Determinate (External)



No. of members (m) = 9 No. of joints (j) = 6 No. of unknown reactions (R) = 3 \therefore m + R = 2j : Statically Determinate *(Internal)*



Presence of internal members

- : Additional sharing for forces
- : Additional Stability

Further addition of internal members

- : Strengthening of Joints C and F
- : Additional Stability and force sharing
- : **m + R > 2j**
- : Statically Indeterminate (Internal)

When more number of members/supports are present than are needed to prevent collapse/stability

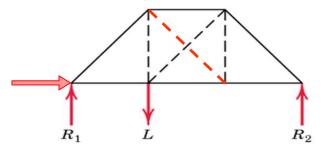
- → Statically Indeterminate Truss
- cannot be analysed using equations of equilibrium alone!
- additional members or supports which are not necessary for maintaining the equilibrium configuration → Redundant

External and Internal Redundancy

Extra Supports than required → External Redundancy

- Degree of indeterminacy from available equilibrium equations

Extra Members than required → Internal Redundancy



Internal Redundancy or Degree of Internal Static Indeterminacy Extra Members than required \rightarrow Internal Redundancy

Equilibrium of each joint can be specified by two scalar force equations \rightarrow 2j equations for a truss with "j" number of joints

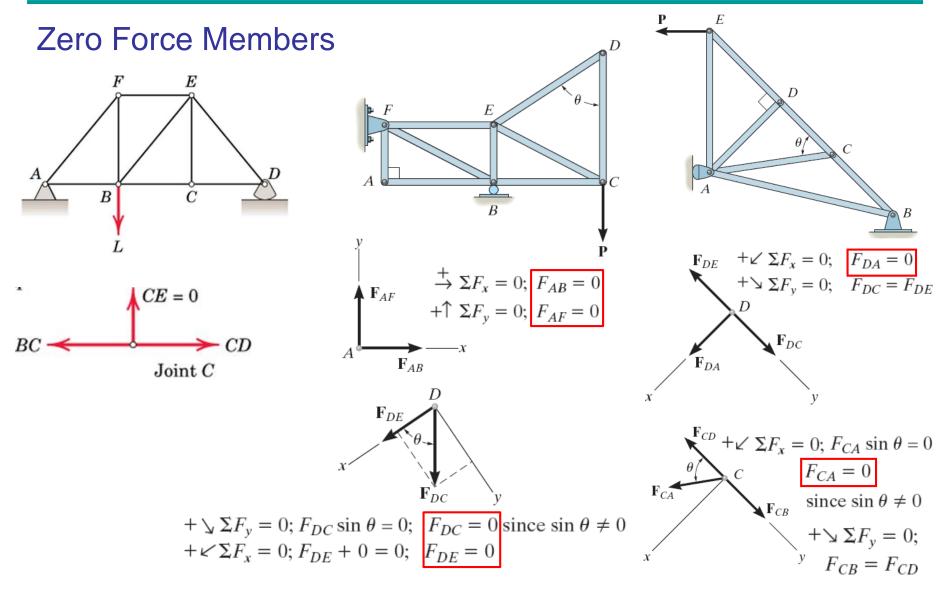
→ Known Quantities

For a truss with "m" number of two force members, and maximum 3 unknown support reactions \rightarrow Total Unknowns = m + 3 ("m" member forces and 3 reactions for externally determinate truss)

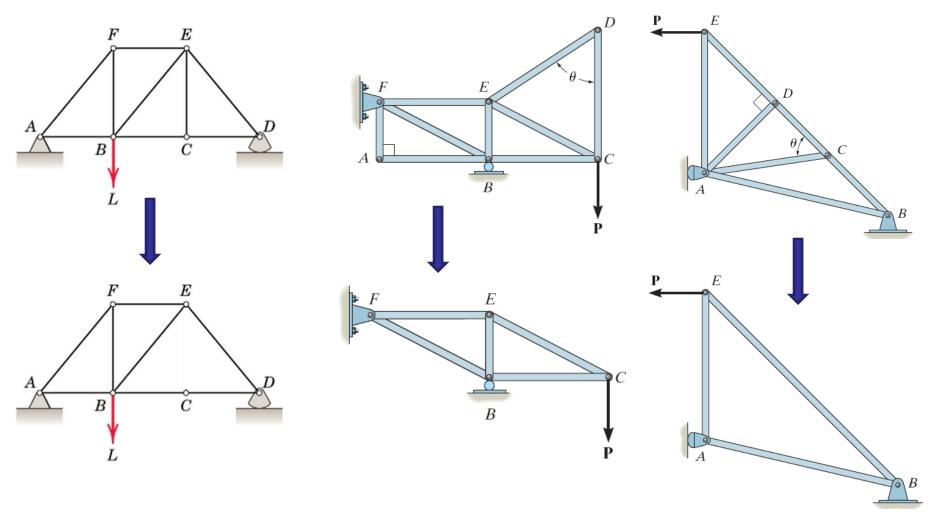
m + 3 = 2j → Statically Determinate Internally m + 3 > 2j → Statically Indeterminate Internally m + 3 < 2j → Unstable Truss

Why to Provide Redundant Members?

- To maintain alignment of two members during construction
- To increase stability during construction
- To maintain stability during loading (Ex: to prevent buckling of compression members)
- To provide support if the applied loading is changed
- To act as backup members in case some members fail or require strengthening
- Analysis is difficult but possible



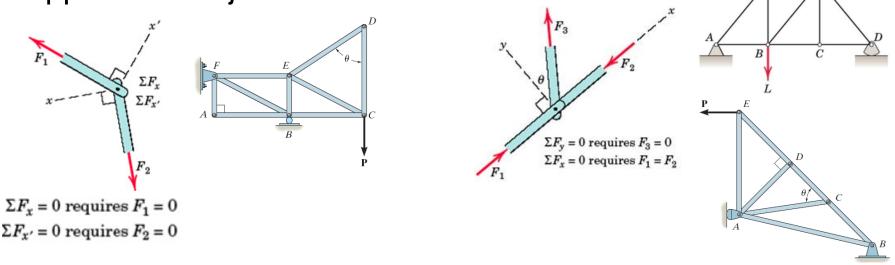
Zero Force Members: Simplified Structures



Zero Force Members: Conditions

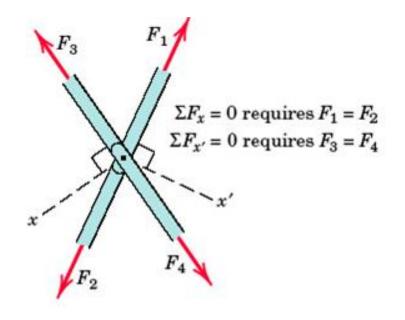
 if only two noncollinear members form a truss joint and no external load or support reaction is applied to the joint, the two members must be zero force members

•if three members form a truss joint for which two of the members are collinear, the third member is a zero-force member provided no external force or support reaction is applied to the joint



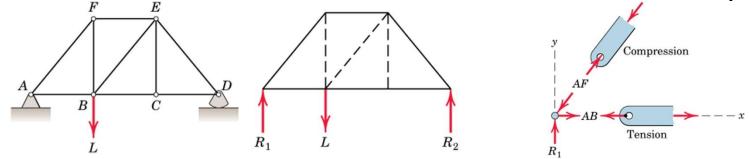
Special Condition

• When two pairs of collinear members are joined as shown in figure, the forces in each pair must be equal and opposite.



Method of Joints

• Start with any joint where at least one known load exists and where not more than two unknown forces are present.



FBD of Joint A and members AB and AF: Magnitude of forces denoted as AB & AF

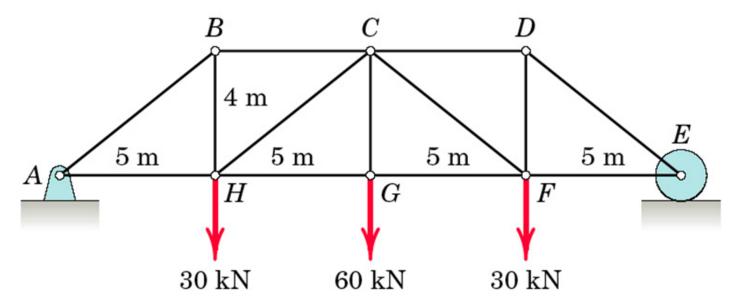
- Tension indicated by an arrow away from the pin
- Compression indicated by an arrow toward the pin

Magnitude of AF from $\Sigma F_y = 0$ Magnitude of AB from $\Sigma F_x = 0$

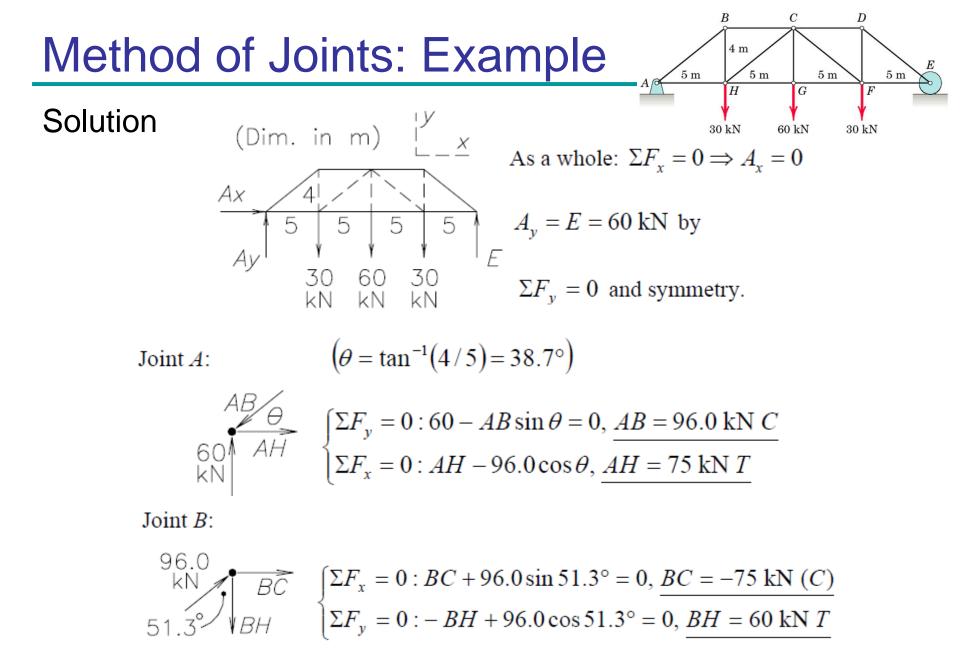
Analyze joints F, B, C, E, & D in that order to complete the analysis

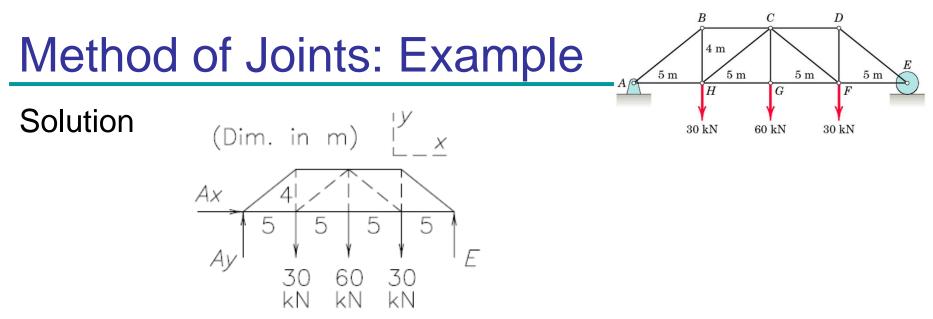
Method of Joints: Example

Determine the force in each member of the loaded truss by Method of Joints.



Is the truss statically determinant externally?YesIs the truss statically determinant internally?YesAre there any Zero Force Members in the truss?No





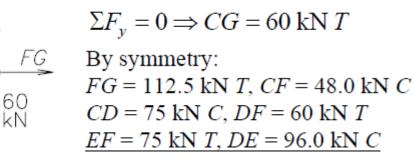
Joint H:

$$\begin{array}{c} \begin{array}{c} 60\\ kN\\ \hline \\ 75\\ kN\\ \hline \\ \hline \\ 30\\ kN \end{array} \end{array} \begin{cases} \Sigma F_y = 0: -CH\sin\theta + 30 = 0, \ \underline{CH} = 48.0 \ \underline{kN} \ \underline{C}\\ \Sigma F_x = 0: 48.0\cos\theta + GH - 75 = 0, \ \underline{GH} = 112.5 \ \underline{kN} \ \underline{T} \end{array}$$

Joint G:

112.5 kN

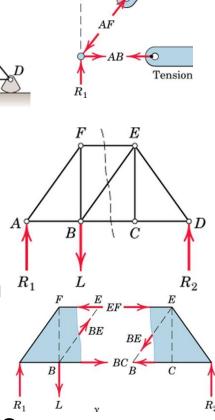
CGM



Method of Joints: only two of three equilibrium equations were applied at each joint because the procedures involve concurrent forces at each joint $\frac{F}{R} = \frac{E}{R}$

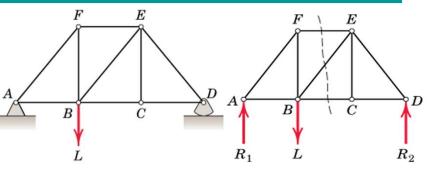
- \rightarrow Calculations from joint to joint
- →More time and effort required
 Method of Sections

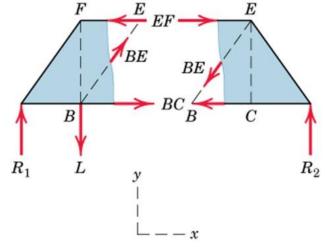
Take advantage of the 3^{rd} or moment equation of equilibrium by selecting an entire section of truss A \rightarrow Equilibrium under non-concurrent force system \rightarrow Not more than 3 members whose forces are unknown should be cut in a single section since we have only 3 independent equilibrium equations



Method of Sections

- Find out the reactions from equilibrium of whole truss
- To find force in member BE:
- Cut an imaginary section (dotted line)
- Each side of the truss section should remain in equilibrium
 - Apply to each cut member the force exerted on it by the member cut away
 - The left hand section is in equilibrium under L, R_1 , BC, BE and EF
 - Draw the forces with proper senses (else assume)
 - Moment @ B \rightarrow EF
 - $L > R_1; \rightarrow \Sigma F_y = 0 \rightarrow BE$
 - Moment @ E and observation of whole truss \rightarrow *BC*
 - Forces acting towards cut section \rightarrow Compressive
 - Forces acting away from the cut section \rightarrow Tensile
- Find *EF* from $\sum M_B=0$; Find *BE* from $\sum F_y=0$
- Find *BC* from $\sum M_E = 0$
 - \rightarrow Each unknown has been determined independently of the other two



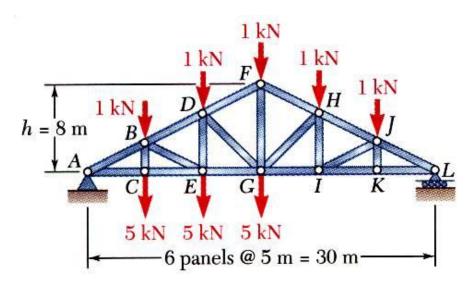


Kaustubh Dasgupta

Method of Sections

- Principle: If a body is in equilibrium, then any part of the body is also in equilibrium.
- Forces in few particular member can be directly found out quickly without solving each joint of the truss sequentially
- Method of Sections and Method of Joints can be conveniently combined
- A section need not be straight.
- More than one section can be used to solve a given problem

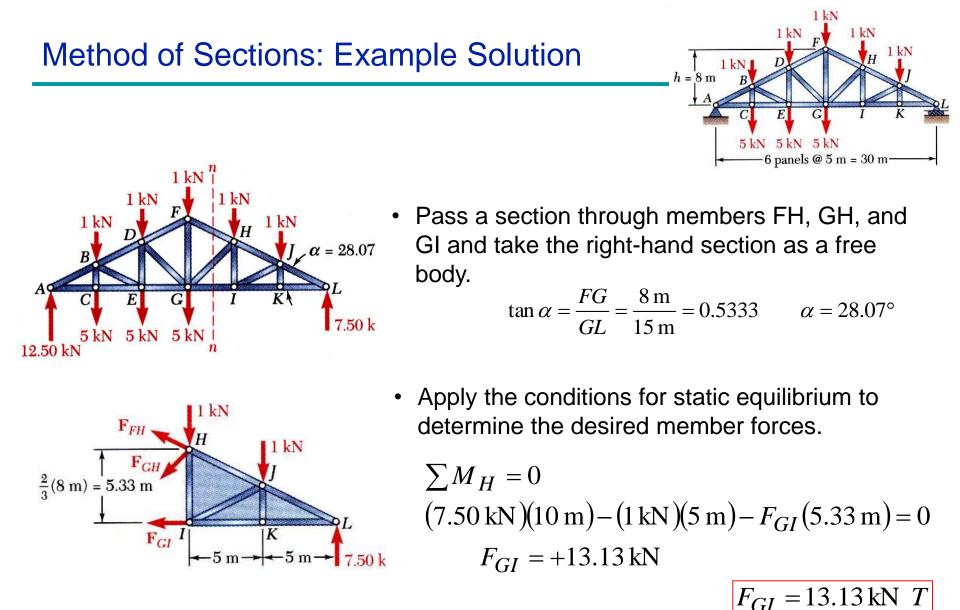
Method of Sections: Example



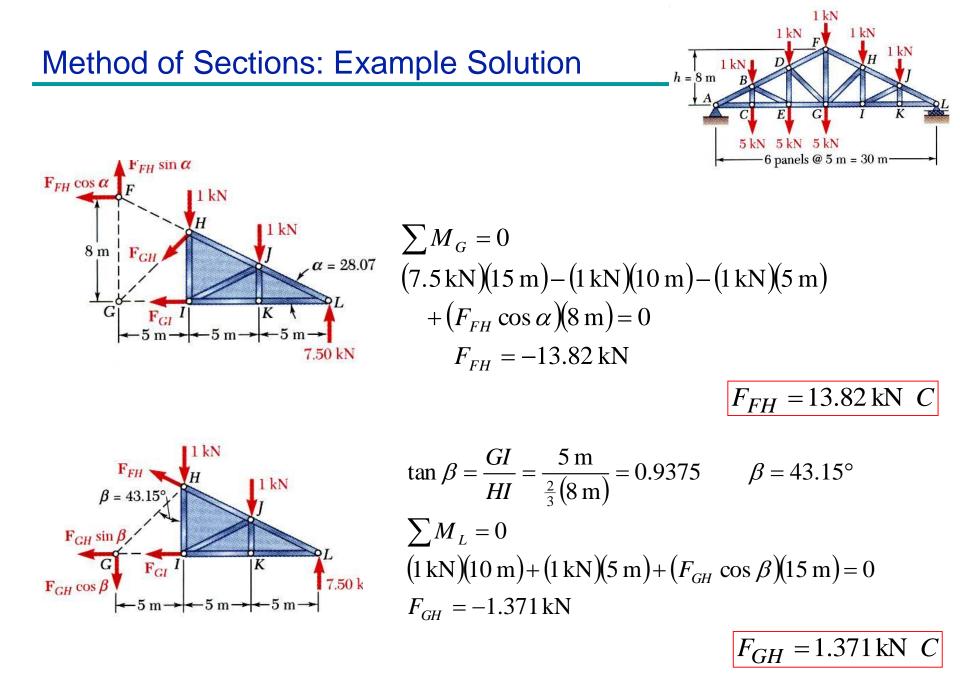
Find out the internal forces in members FH, GH, and GI

Find out the reactions

$$\sum M_{A} = 0 = -(5 \text{ m})(6 \text{ kN}) - (10 \text{ m})(6 \text{ kN}) - (15 \text{ m})(6 \text{ kN}) - (20 \text{ m})(1 \text{ kN}) - (25 \text{ m})(1 \text{ kN}) + (30 \text{ m})L$$
$$L = 7.5 \text{ kN} \uparrow$$
$$\sum F_{y} = 0 = -20 \text{ kN} + L + A$$
$$A = 12.5 \text{ kN} \uparrow$$



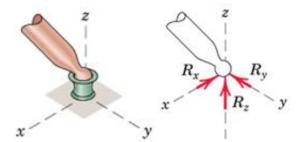
ME101 - Division III



Space Truss



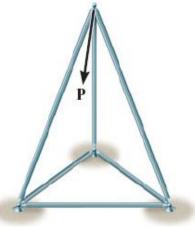
3-D counterpart of the Plane Truss Idealized Space Truss → Rigid links connected at their ends by ball and socket joints





Space Truss

- 6 bars joined at their ends to form the edges of a tetrahedron as the basic non-collapsible unit - 3 additional concurrent bars whose ends are attached to three joints on the existing structure are required to add a new rigid unit to extend the structure.



A space truss formed in this way is called a Simple Space Truss

If center lines of joined members intersect at a point \rightarrow Two force members assumption is justified \rightarrow Each member under Compression or Tension

Static Determinacy of Space Truss

Six equilibrium equations available to find out support reactions \rightarrow if these are sufficient to determine all support reactions

→ The space truss is Statically Determinate Externally

Equilibrium of each joint can be specified by three scalar force equations \rightarrow 3j equations for a truss with "j" number of joints

→ Known Quantities

For a truss with "m" number of two force members, and maximum 6 unknown support reactions \rightarrow Total Unknowns = m + 6 ("m" member forces and 6 reactions for externally determinate truss) Therefore:

m + 6 = 3j→Statically Determinate Internally m + 6 > 3j→Statically Indeterminate Internally m + 6 < 3j→Unstable Truss

A necessary condition for Stability but not a sufficient condition since one or more members can be arranged in such a way as not to contribute to stable configuration of the entire truss

 $\Sigma F_x = 0 \ \Sigma M_x = 0$

 $\Sigma F_{\rm v} = 0 \ \Sigma M_{\rm v} = 0$

 $\Sigma F_{z} = 0 \ \Sigma M_{z} = 0$