

**A Computer Program development for solving linear system by LU Decomposition using Doolittle's algorithm.**

1. Solve the following linear systems  $A\vec{x} = \vec{b}$ , where  $\vec{x} = \begin{Bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{Bmatrix}$ ; using Doolittle's algorithm.

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ -1 & 1 & 2 & 3 \\ 1 & -1 & 1 & 2 \\ -1 & 1 & -1 & 5 \end{bmatrix}; \quad \vec{b}_a = \begin{Bmatrix} 10 \\ 5 \\ 3 \\ 4 \end{Bmatrix}; \quad \vec{b}_b = \begin{Bmatrix} -4 \\ -5 \\ -3 \\ -4 \end{Bmatrix}; \quad \vec{b}_c = \begin{Bmatrix} -2 \\ -3 \\ 1 \\ -8 \end{Bmatrix}$$

We will discuss how to develop a Matlab program using the algorithm discussed in the class.

Doolittle's algorithm suggest that

$$k = 1, 2, 3, 4, \dots, (n-1)$$

$$l_{kk} = 1$$

$$l_{ik} = 0 \quad \text{for } i < k$$

$$u_{ij} = a_{ij}^{(k)} = a_{ij}^{(k-1)} - l_{ik}^{(k-1)} a_{kj}^{(k-1)}$$

$$l_{nk} = \frac{a_{nk}^{(k-1)}}{a_{kk}^{(k-1)}} \quad \begin{matrix} i = k+1, k+2, \dots, n \\ j = k, k+1, k+2, \dots, n \end{matrix}$$

$$l_{nn} = 1$$

To solve the given systems:

$$[L]\{c\} = \{b\} \quad \text{and} \quad [U]\{x\} = \{c\}$$

$\therefore$  ~~3~~

The forward and backward substitution required

$$\begin{aligned} c_1 &= b_1 \\ c_i &= b_i - \sum_{j=1}^{i-1} l_{ij} x_j \quad ; \quad i = 2, 3, 4 \end{aligned} \quad \left. \vphantom{\sum_{j=1}^{i-1}} \right\} \rightarrow \text{Forward substitution}$$

$$\begin{aligned} x_4 &= \frac{c_4}{u_{44}} \\ x_i &= \frac{c_i - \sum_{j=i+1}^3 u_{ij} x_j}{u_{ii}} \quad ; \quad i = 3, 2, 1 \end{aligned} \quad \left. \vphantom{\sum_{j=i+1}^3} \right\} \rightarrow \text{Backward substitution}$$

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% Given A, ba, bb, bc. Their dimensions nxn. To find xa, xb, and xc
% For that first L and U matrices need to be found.
%
AA = [1 2 3 4
      -1 1 2 3
      1 -1 1 2
      -1 1 -1 5];
A = AA;
ba = [10
      5
      3
      4];
bb = [-4
      -5
      -3
      -4];
bc = [-2
      -3
      1
      -8];
nn=length(A);
% Define the existence of L and U matrices
L(1:nn,1:nn)=0;
U=A;
% Start Do loop for LU Factorisation
for k = 1:nn-1
    for i = k+1:nn
        L(k,k)=1.0;
        lik = A(i,k)/A(k,k);
        for j=k:nn
            A(i,j)=A(i,j)-lik*A(k,j);
            U(i,j)=A(i,j);
        end
        L(i,k)=lik;
    end
end
L(nn,nn)=1
%
%Forward substitution for vector c.
%
c(1:nn)=0;
x(1:nn)=0;
%xa=x;
%xb=x;
%xc=x;
for p = 1:3
    if p==1
        b(1:nn)=ba(1:nn)
    elseif p==2
        b(1:nn)=bb(1:nn)
    elseif p==3
        b(1:nn)=bc(1:nn)
    end
    c(1)= b(1)
    for i=2:nn
        c(i)=b(i);
        for j=1:i-1
            c(i)=c(i)-L(i,j)*c(j)
        end
    end
end
x(nn)= c(nn)/U(nn,nn);
for i=nn-1:-1:1
    x(i)=c(i);

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        for j=nn:-1:i+1
            x(i)=x(i)-U(i,j)*x(j);
        end
        x(i)=x(i)/U(i,i)
    end
    if p==1
        xa=x'
    elseif p==2
        xb=x'
    elseif p==3
        xc=x'
    end
end
fid=fopen('out.txt','w');
fprintf(fid,'L = ')
for i=1:nn
    fprintf(fid,'\n')
    for j= 1:nn
        fprintf(fid,'%10.5f', L(i,j));
    end
end
fprintf(fid,'\n')
fprintf(fid,'U = ')
for i=1:nn
    fprintf(fid,'\n')
    for j= 1:nn
        fprintf(fid,'%10.5f', U(i,j));
    end
end
fprintf(fid,'\n3n')
fprintf(fid,'xa = ')
fprintf(fid,'%10.5f',xa(1:nn));
fprintf(fid,'\n')
fprintf(fid,'xb = ')
fprintf(fid,'%10.5f',xb(1:nn));
fprintf(fid,'\n')
fprintf(fid,'xc = ')
fprintf(fid,'%10.5f',xc(1:nn));
fclose(fid)

```

*The output file is given as below:*

```

L =
    1.00000    0.00000    0.00000    0.00000
   -1.00000    1.00000    0.00000    0.00000
    1.00000   -1.00000    1.00000    0.00000
   -1.00000    1.00000   -1.00000    1.00000
U =
    1.00000    2.00000    3.00000    4.00000
    0.00000    3.00000    5.00000    7.00000
    0.00000    0.00000    3.00000    5.00000
    0.00000    0.00000    0.00000    7.00000
xa =    1.00000    1.00000    1.00000    1.00000
xb =    1.00000    1.00000   -1.00000   -1.00000
xc =    1.00000   -1.00000    1.00000   -1.00000

```